

MGM'S

Jawaharlal Nehru Engineering College,  
Aurangabad

PSA Laboratory Manual

For

Third Year Students

Manual made by

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## **LABORATORY MANNUAL CONTENTS**

This manual is intended for the second year students of Electronics Engineering in the subject of Programmable logic controller.

Students are advised to thoroughly go through this manual rather than only topics mentioned in the syllabus as practical aspects are the key to understanding and conceptual visualization of theoretical aspects covered in the books.

Good Luck for your Enjoyable Laboratory Sessions

Miss. Molleshree Saware

## FOREWORD

It is my great pleasure to present this laboratory manual for second year engineering students for the subject of Programmable logic control. Keeping in view the vast coverage required for visualization of concepts of Programmable logic controller components with simple language.

As a student, many of you may be wondering with some of the questions in your mind regarding the subject and exactly what has been tried is to answer through this manual. Faculty members are also advised that covering these aspects in initial stage itself, will greatly relieved them in future as much of the load will be taken care by the enthusiasm energies of the students once they are conceptually clear

Prof. Dr. S.D.Deshmukh

Principal

## Power System Analysis Manual 2014-2015

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**Experiment no 01:-**

**Aim : Introduction of MATLAB:-**

**Theory:**

Q. How to start MATLAB ?

Q. write the matrix initialization and basic operation ?

Q. How to Run programs given in this appendix ?

**Conclusion :**

**Experiment no 02:-**

**Aim : To study singular transformation using MATLAB**

**Theory:**

Q. write down algorithmic steps of singular transformation using MATLAB ?

**Conclusion :**

## Experiment no 03:-

### Aim : Solution of power flow problem using gauss seidal method

#### **Theory:**

**Q.** what is the procedure to obtain the solution of power flow problem using gauss seidal method and its advantages ? and drawbacks ?

#### **MATLAB PROGRAM :**

##### **%Program for load flow by Gauss-Seidal Method**

Clear;

N=4

V=[1.04 1.04 11]

```
Y= [3-j*9    -2+j*6          -1+j*3          0
    -2+j*6    3.66-j*11      -0.666+j*2      -1+j*3
    -1+j*3    -0.666+j*2      3.66-j*11      -2+j*6
    0         -1+j*3          -2+j*6          3-j*9 ]
```

Type=ones(n,1)

Typechanged=zeros(n,1)

```
Qlimitmax=zeros(n,1)
Vmagfixed= zeros(n,1)

Type(2)=2

Qlimitmax(2)=1.0
Qlimitmax(2)=0.2
Vmagfixed(2)=1.04

Diff=10;noofiter=1

Vprev=V;

While(diff>0.00001/ noofiter==1),

Abs(V)

Abs(Vprev)

Vprev=V;

P = [inf  0.5  -1  0.3];
Q = [inf  0.0  0.5  -0.1];
S=[inf+j*inf (0.5-j*0.2) (-1.0+j*0.5) (0.3-j*0.1)];

For i=2:n,

If type(i)==2 | typechenged(i)==1,

If type(i)>Qlimitmax(i) | Q(i)<Qlimitmin(i),

If (Q(i)<Qlimitmin(i),

    Q(i)=Qlimitmin(i);

Else

Q(i)=Qlimitmax(i);
```



```
End
Type(i)=1;
Typechanged(i)=1;
Else
Type(i)=2;
Typechanged(i)=0;
End

End

End

End
Sumyu=0;
Fork=1:n,
If(i~=k)
    Sumyv=sumyu=y(i,k)*V(k);
    end
end
V(i)=(1/y(i,i))*((p(i)-j*Q(i))/conj(V(i))-sumyv);
If type(i)==2 & typechanged(i)~=1,
V(i)=PolarTorect(Vmagfixed(i),angle(V(i))*180/pi);
    End
```

End

Diff=max(abs(abs(V(2:n))-abs(Vprev(2:n))));

Noofiter=noofiter+=1;

**Output :**

**Conclusion :**

## Experiment no 04:-

### Aim : solution of power flow problem using N-R method

#### **Theory :**

Q. what is the procedure to obtain the solution of power flow problem using N - R method and its advantages over gauss sidal?

Q. write down the difference in gauss seidal and N-R method ?

#### **MATLAB PROGRAM :**

##### **%Program for load flow by Newton- raphson Method**

Clear

n=3;

V=[1.04 1.0 1.04]

Y= [ 5.88228-j\*23.50514   -2.9427+j\*11.7676     -2.9427+j\*11.7676

      -2.9427+j\*11.7676     5.88228-j\*23.50514   -2.9427+j\*11.7676

      -2.8427+j\*11.7676   -2.9427+j\*117676     5.88228-j\*23.50514 ]

type =ones(n,1);

```
Typechanged=zeros(n,1);
Qlimitmax=zeros(n,1);
Qlimitmin=zeros(n,1);
Vmagfixed=zero(n,1);
Type(3)=2;
Qlimitmax(3)=1.5;
Qlimitemin(2)=0;
Vmagfixed(2)=1.04;
Diff=10;noofiter=1.0
Pspec=[inf 0.5 -1.5]
Qspec=[inf 1 0];
S=[inf+j*inf(0.5-j*0.2) (-1.0+j*0..5) (0.3-j*0.1)];
While (diff>0.00001 | noofiter==1),
Eqcount=1;
For i=2:n,
Abs(Vprev)
Pause
Vprev=V;
For ceq=1:eqcount,
    Am=real(Y(assoeqbus(ceq),assocolbus(ccol))*V(assocolbus(ccol)));
    bm =imag(Y(assoeqbus(ceq),assocolbus(ccol))*V(assocolbus(ccol)));
```

```
ei= real(V(assoeqbus(ceq)));
fi= imag(V(assoeqbus(ceq)));

if assoeqvar(ceq)=='p' & assocolbus(col)=='d',
    if assoeqbus(ceq)~=assocolbus(ccol),
        H=am*fi-bm*ei;
    Else
        H=Q(assoeqbus(ceq))-imag(Y(assoeqbus(ceq)))^2;
    End
    Jacob(ceq,ccol)=H
End

If assoeqvar(ceq)=='p' & assocolver(ccol)=='v',
If assoeqbus(ceq)`= assocolver(ccol),
N =am*ei+bm*fi
Else
N=P(assoeqbus(ceq))+real(Y(assoeqbus(ceq),assocolbus(ceq))*abs(V(assocolbus(ceq)))^2);
Scal(i)=0;
Sumyv=0;
Fork=1:n,
Sumyv=sumyv+Y(i,k)*V(k);
End
```

```
Scal(i)=V(i)*conj(sumyv);
P(i)=real(scale(i));
Q(i)=image(Scal(i));
If type(i)==2 | typechanged(i)==1,
If(Q(i)<Qlimitmax(i) | Q(i)<Qlimitmax(i)),
    If(Q(i)<Qlimitmax(i));
        Q(i)<Qlimitmax(i);
Else
Q(i)=Qlimitmax(i);
End
Type(i)=1;
Typechanged(i)=0;
End
End
If type (i)==1,
Assoeqvar(eqcount)='p';
Assoeqbus(eqcount)=i;
Mismatch(eqcount)=Pspec(i)-P(i);
Assoeqvar(eqcount+1)='Q';
Assoeqbus(eqcount+1)=i;
Mismatch(eqcount+1)=Qpec(i)-Q(i);
```

```
Assoeqvar(eqcount)='d';
Assoeqbus(eqcount)=i;
Assoceqvar(eqcount+1)='V';
Assoeqbus(eqcount+1)=i;
Mismatch=(eqcount+2);
Else

Assoeqvar(eqcount)='p';
Assoeqbus(eqcount)=i;
Assoceqvar(eqcount+1)='Q';
Assoeqbus(eqcount+1)=d;
Mismatch(eqcount+1)=Ppec(i)-P(i);
Eqcount=eqcount+1;
End
End
Mismatch
Eqcount=eqcount-1;
Noofeq=eqcount;
Update=Zeros(eqcount,1)
Vprvw=V
Abs(V);
```

End

Jacob(ceq,ccol)=N

End

If assoeqvar(ceq)=='Q' & assocolvar (ccol)=='d',

If assoeqbus(ceq)~=assocolbus(ccol),

J=am\*ei+bm\*fi;

Else

J=p(assoeqbus(ceq))+real(Y(assoeqbus(ceq),assocolbus(ceq))\*abs(V(assoeqbus(ceq)))^2);

End

Jacob(ceq,ccol)=J

End

If assoeqvar(ceq)=='Q' & assocolvar (ccol)=='V',

If assoeqbus(ceq)~=assocolbus(ccol),

L=am\*fi-bm\*ei;

else

L=Q(assoeqbus(ceq))-

Imag(Y(assoeqbus(ceq),assocolbus(ceq))\*abs(V(assoeqbus(ceq)))^2);

End

Jacob(ceq,ccol)=L;

End



```
End
End
Jacob;
Pause
Update=inv(Jacob)*mismatch;
Noofeq=1;
For i=2:n,
    If i=2:n,
        newchinangV=update(noofeq);
        newangV=angle(V(i))+newchinangV;
        newchinmagV=update(noofeq+1)*abs(V(i));
        newangV=abs(V(i))+newchinangV;
        V(i)=polartorect(newmagV*180/pi);
        Noofeq=noofeq+2;
    Else
        newchinmagV=update(noofeq);
        newangV=angle(V(i))+newchinangV;
        V(i)=polartorect(newmagV*180/pi);
        Noofeq=noofeq+2;
    end
end
clear mismatchJacob update assoeqvar assoeqbus Assoeqlvar assocllous
```

```
diff=min(abs(abs(V(2:n))-abs(Vprwv(2:n))));  
noofiter=noofiter+1;
```

**Output :**

**Conclusion :**

**Experiment no 05:-**

**Aim : Solution of formation of bus impedance matrix by building algorithm :-**

**Theory :**

Q. write down the detail procedure of formation of bus impedance matrix by building algorithm ?

**Conclusion:**

## Experiment no 06 :-

### Aim : Programme for optimum loading of generator :-

#### **MATLAB PROGRAM :-**

```
clear ;
n=2
Pd = 231.25
alpha = [0.20  0.25]
beta = [40  30]
lamda = 20
lamdaprev = lamdba
esp = 1
deltalambda = 0.25
Pgmin = [20 20]
pg = 1008ones(n,1)
while abs (sum (Pg)-Pd)>eps
    for i= 1:n,
        Pg(i) = (lamda-beta(i)) / alpha(i) ;
```

```
if Pg(i)>Pmax(i)
    Pg(i) = Pmax (i);
end
if Pg(i)>Pmin(i)
    Pg(i) = Pmin (i);
end
end
if(sum (Pg-Pd)) < 0
    lamdaprev = lambda
    lamda= lamda + deltalambda ;
else
    lamdaprev = lambda
    lamda= lamda - deltalambda ;
end
end
dis('the final value of lambda is')
lamdaprev
dis('the distribution of load shared by two units is')
Pg
```

**Output :**

**Conclusion :**

## **Experiment no 07 :-**

### **Aim : Programme for building of Z-Bus by addition of branch or link :-**

#### **Theory :**

**Q.** write down the algorithmic steps of building zbus by addition of branch or link

#### **MATLAB PROGRAM :-**

```
clear ;  
zprimary = [1100.25  
            2210.1  
            3310.1  
            4200.25  
            5230.1 ]  
[elements columes] = size(zprimary)  
zbus = []  
currentbus no = 0  
for count = 1:elements,  
[row cols] = size(zbus)  
from=zprimary(count,2)
```

```
to=zprimary(count,3)
valu=zprimary(count,4)
newbus=max(from,to)
if newbus>currentbusno & ref == 0
zbus = [zbus zeros(rows,1)
        zeros(1,cols) value]
currentbus no =newbus
continue
end
if newbus>currentbusno & ref ~= 0
zbus=[zbus zbus(:,ref)
      zbus(ref,:) value+zbus(ref,ref)]
currentbusno = newbus
continue
end
if newbus<=currentbusno & ref ~= 0
zbus=zbus-1/(value+zbus(from,from)+zbus(to,to)-2*zbus(from,to))*(zbus(:,from)-
zbus(:,to))*((zbus(from,:)-zbus(to,:)))
continue
end
end
end
```



**Output :**

**Conclusion :**