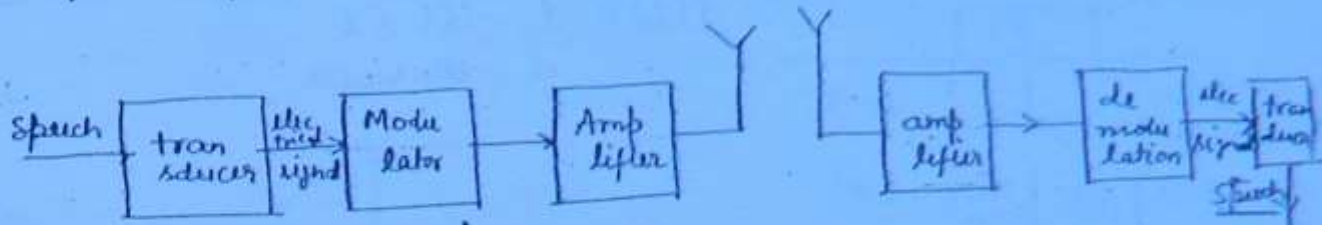


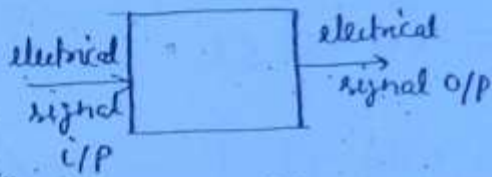
2

Speech signal  $\rightarrow 300\text{Hz} \rightarrow 3400\text{Hz}$

(3)



\* SS  $\rightarrow$  we are concentrating to find response of system.



to find response of a system, we use following rules/tools-

1. Fourier series
2. Fourier transforms
3. Laplace transforms
4. Z-transforms

Audio signal  $\rightarrow 20\text{Hz} - 20\text{KHz}$

Video signal  $\rightarrow 0 - 5\text{MHz}$

data signal  $\rightarrow$  range is based on application.

Signal  $\rightarrow$  is a quantity having associated information with it.

is a function of time.

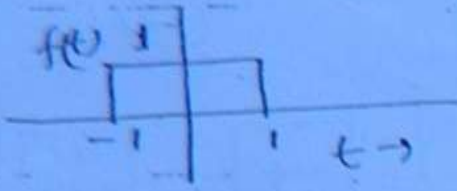
we deal with electrical signal which are voltages or currents, which are both functions of time. In general signal is a function time  $f(t)$ . (electrical)

But signal is not always a function of time.

collect still frame and play back to it is video signal (normally 24 frames/second where play back the still frames).

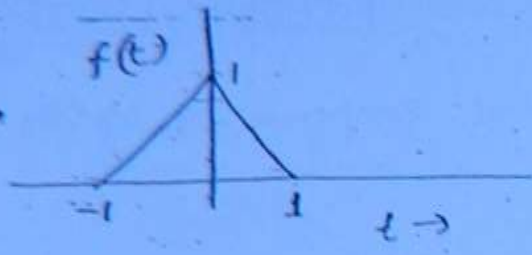
In Motion picture signal is three dimensional  $f(x, y, t)$ .

(4)



$$f(t) = 1 \quad -1 \leq t \leq 1$$

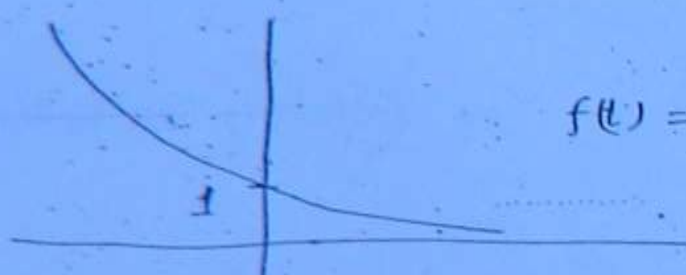
$$0 \quad \text{otherwise}$$



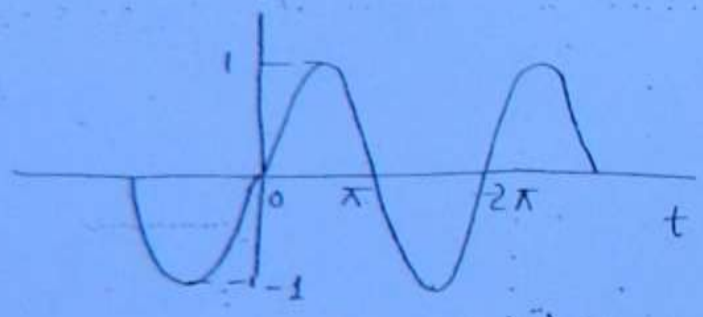
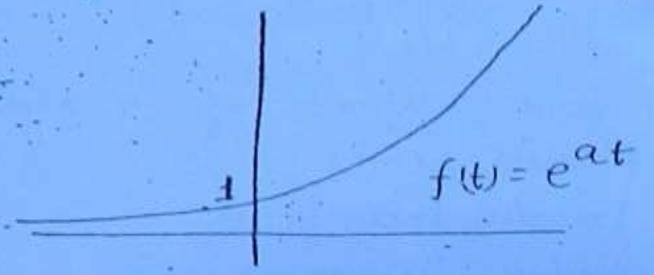
$$f(t) = -1 \leq t \leq 0$$

$$= t+1$$

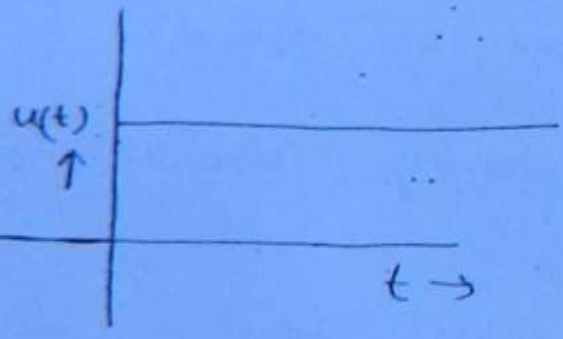
$$= -t+1 \quad 0 \leq t \leq 1$$



$$f(t) = e^{-at}$$

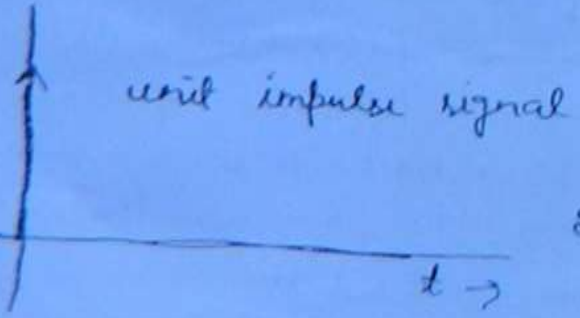


$$f(t) = \sin t$$



$$u(t) = 1 \quad t \geq 0$$

$$0 \quad t < 0$$



unit impulse signal

existence in split second  
effect is enormous.

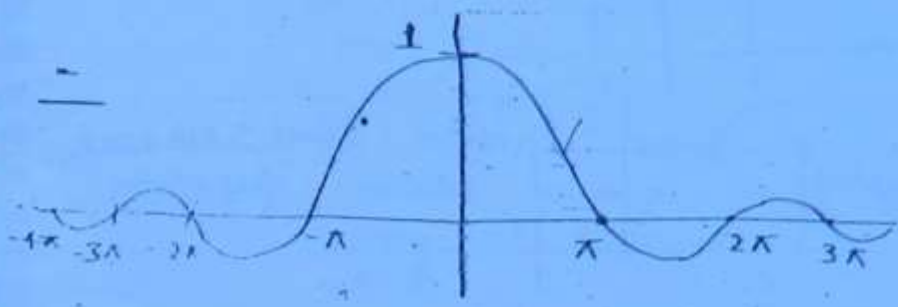
$$\delta(t) = 0 \quad t \neq 0$$

$$= \infty \quad t = 0 \text{ very large}$$

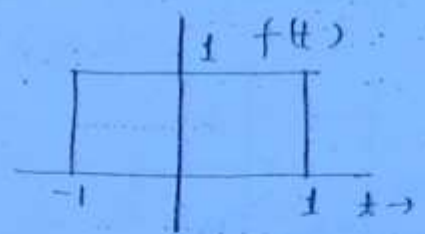
$$\neq 0 \quad t = 0 \quad (\infty)$$

$\text{rect} \left( \frac{t-1}{2} \right)$  3/4  
 $\text{rect}(t+3/4)$

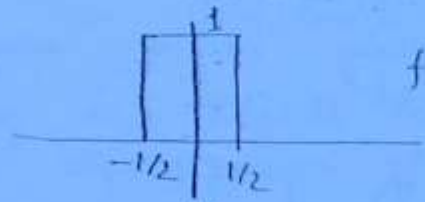
$\int_{-\infty}^{\infty} f(t) dt = 1 \rightarrow \int_{-\infty}^{\infty} \delta(t) dt = 1$  (B)



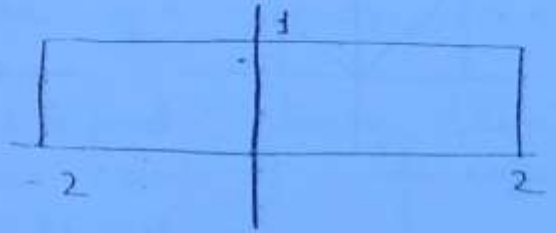
$f(t) = \frac{\sin t}{t} = \text{sinc}(t)$   
 $= \text{Sinc}(t/\pi)$



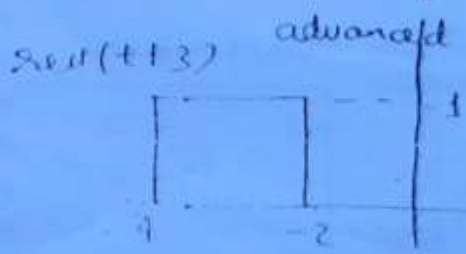
$f(t) = \text{rect}(t/2)$



$f(2t)$  }  $f(t) = \text{rect}(t)$   
 time scaled version of  $f(t)$  (compressed time-axis)



$f(t/2)$   $f(t) = \text{rect}(t/4)$

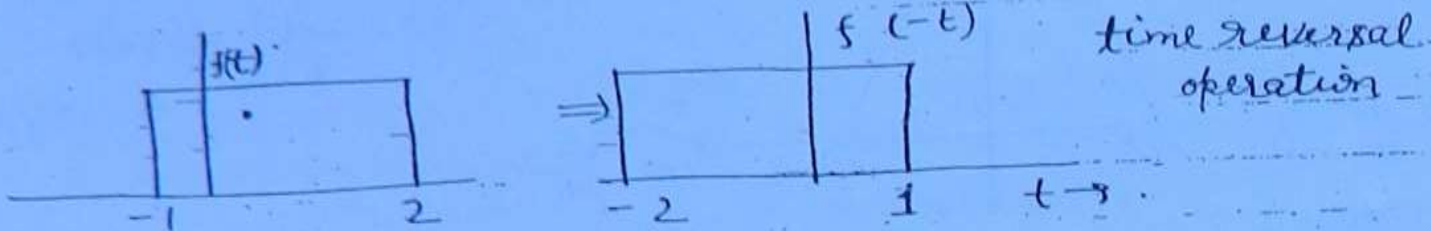


$f(t-4)$  } time shifted version of given signal  $f(t)$   
 $f(t+3)$

$\left[ \frac{\text{divide all time (instant) by } a}{\text{multiply}} \right] f(t) \rightarrow f(at)$   $a > 1 \rightarrow$  compression  
 $a < 1 \rightarrow$  expansion

$f(t) \xrightarrow{+T} f(t+T)$  → advanced (left)   
 (subtract T from all instant) shift  
 $f(t) \xrightarrow{-T} f(t-T)$  → delayed (right)   
 (add T to all instant) shift

6

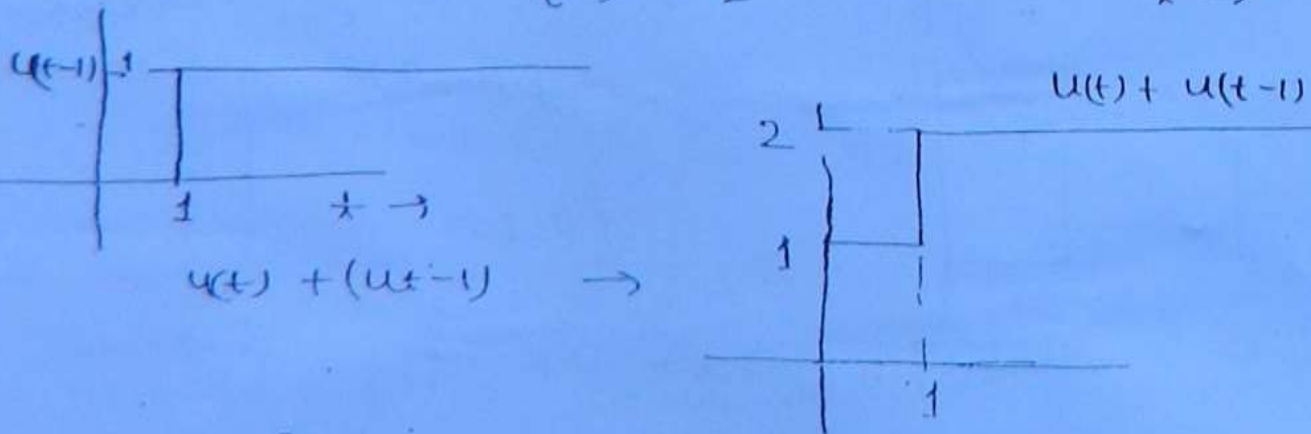
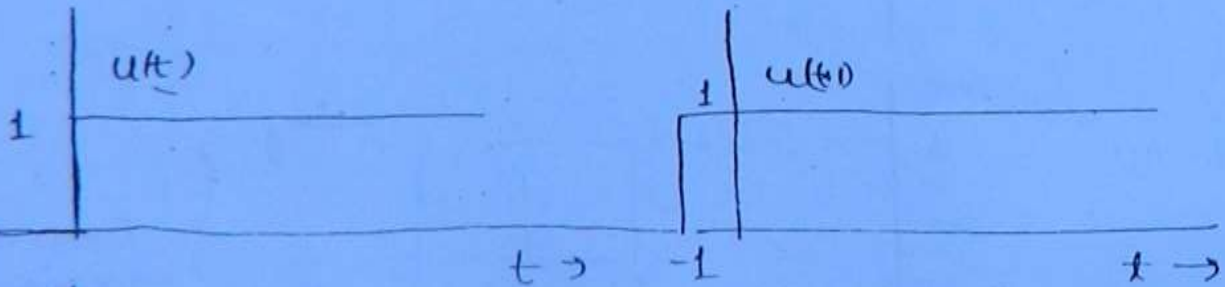
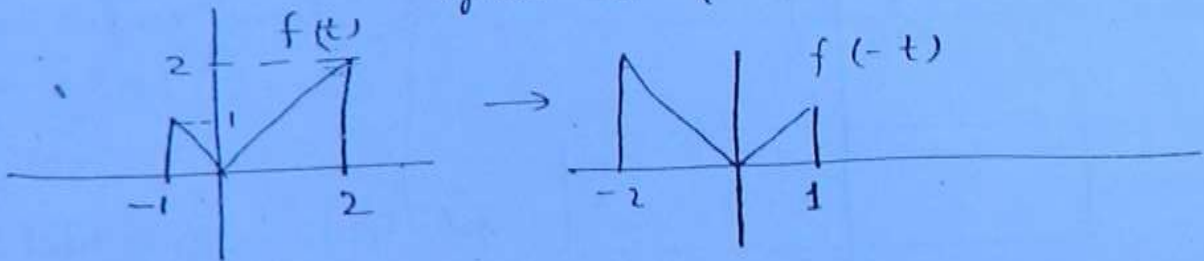


$$f(t) = \begin{cases} 1 & -1 \leq t \leq 2 \\ 0 & \text{otherwise} \end{cases}$$

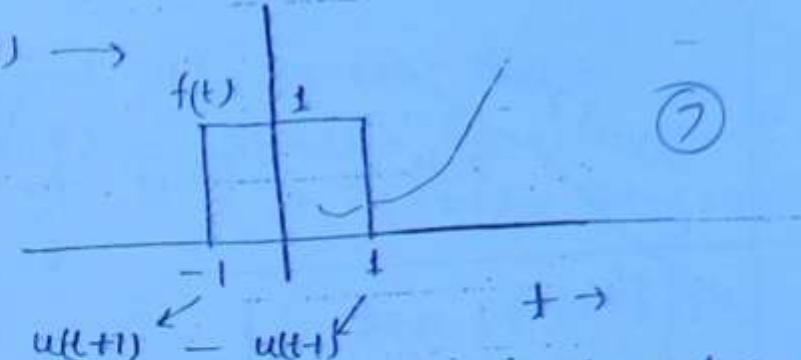
$$f(-t) = \begin{cases} 1 & -1 \leq -t \leq 2 \\ 0 & \text{otherwise} \end{cases}$$

$$= \begin{cases} 1 & -2 \leq t \leq -1 \\ 0 & \text{otherwise} \end{cases}$$

obtained by rotating signal across y-axis / by 180°   
 or by taking mirror image of signal abt y-axis.

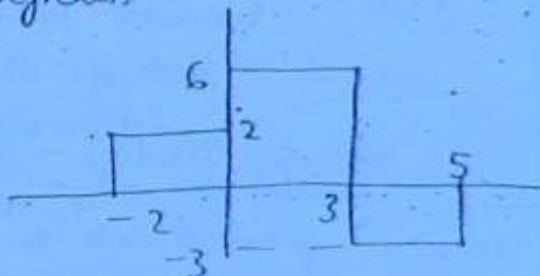


$f(t) = u(t+1) - u(t-1) \rightarrow$



$u(t) \rightarrow$  indicates change in signal value from 0 to 1 exactly at  $t=0$

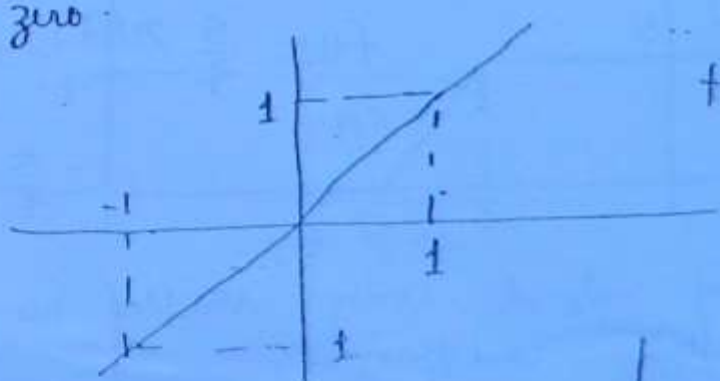
Q. Represent the following signal using shifted unit step signals.



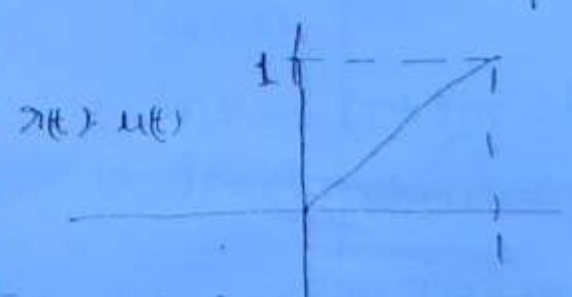
$$2u(t+2) + 4u(t) - 9u(t-3) + 3u(t-5)$$

as long as signal is nonzero only for a finite interval of time then some of coefficient will be zero as in above eq  $\rightarrow 2+4-9+3=0$

(\*) A signal having step changes in finite interval time then some of all coefficient of shifted unit step signal will be zero.

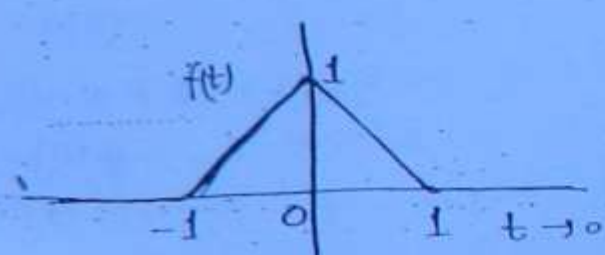
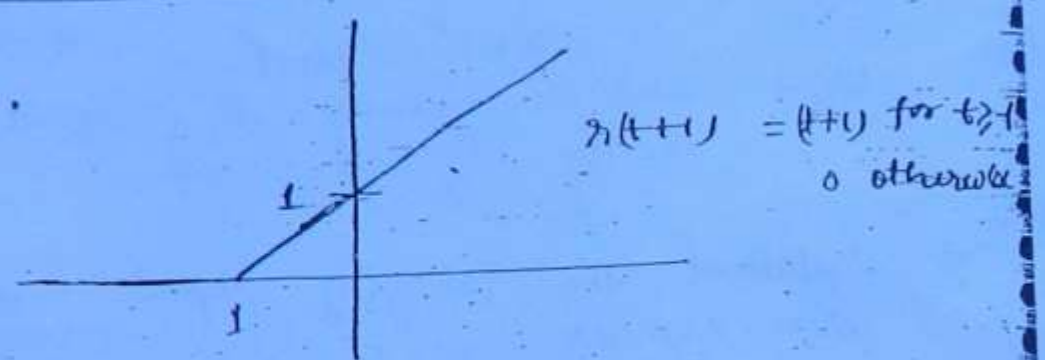
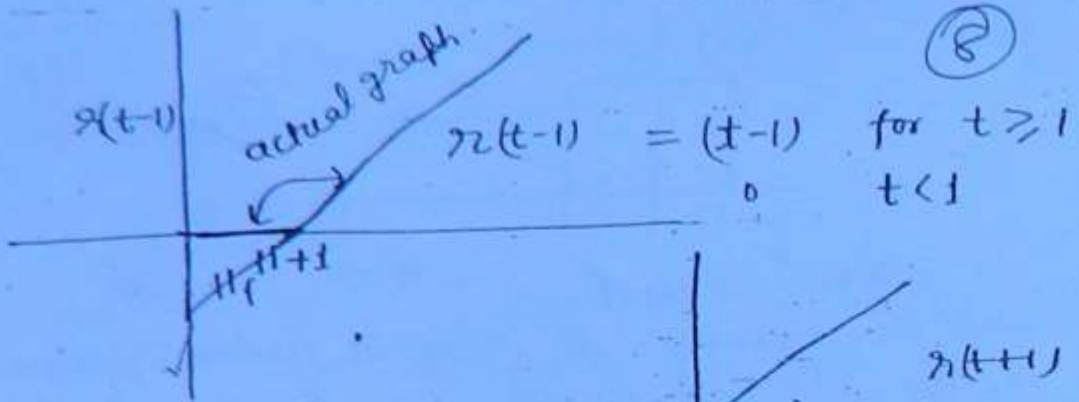


$f(t) = t$  [not ramp signal]



$f(t) = \frac{1}{a} \text{ for } 0 < t \leq a \text{ or } t \geq 0$

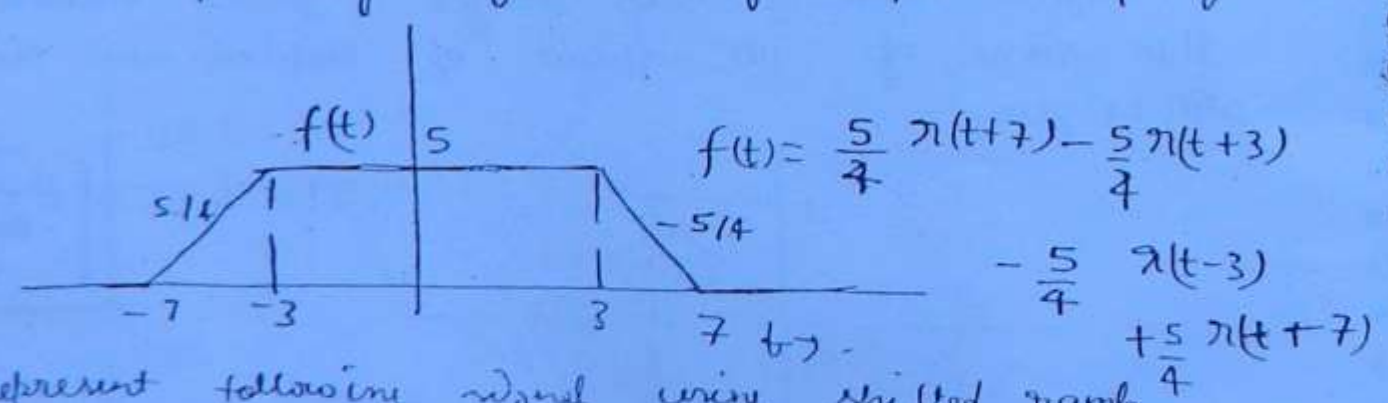
8



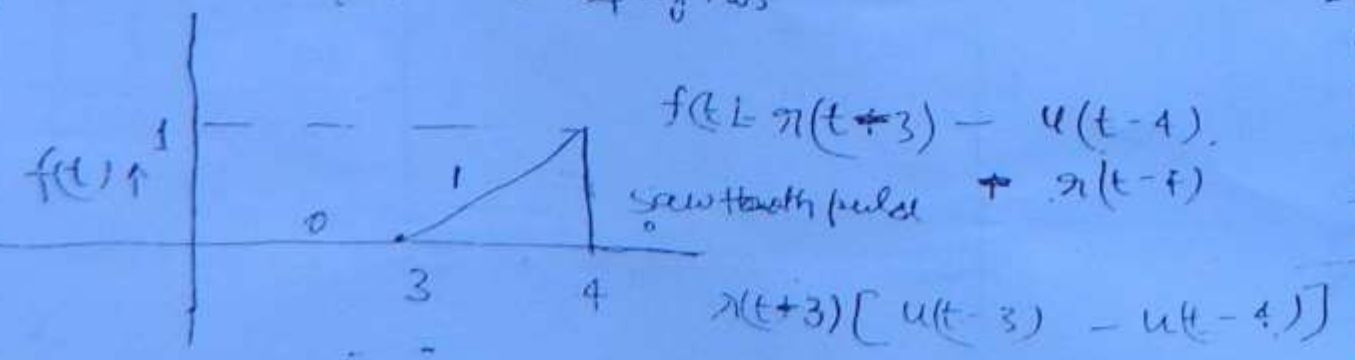
$f(t) = r(t+1) - 2r(t) + r(t-1)$

$r(t)$  represent change in slope at  $t=0$  from  $(0 \rightarrow 1)$   
 if signal is finite interval signal some of coefficients will be zero  $\rightarrow$  eg  $1 - 2 + 1 = 0$

Q. Represent following signal using shifted ramp signal.

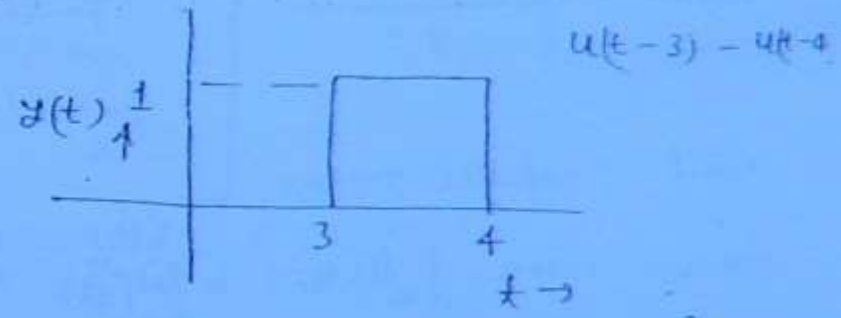
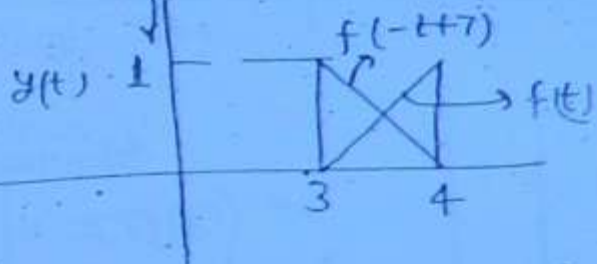
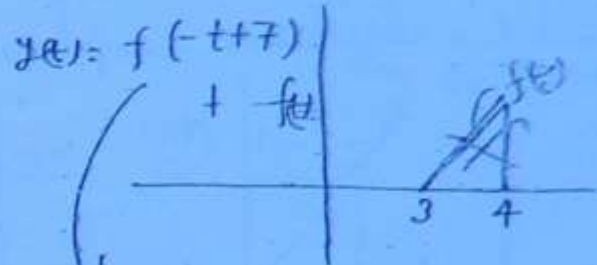
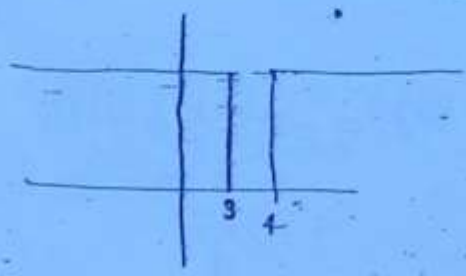


Q. represent following signal using shifted ramp signals and shifted unit step signals.



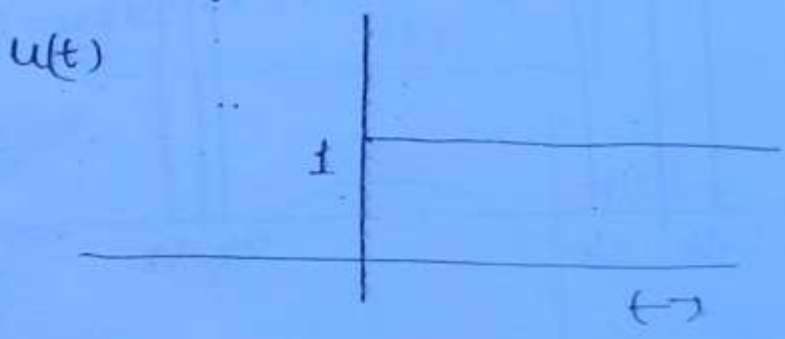
⊙ for the above signal  $f(t) + f(-t+7)$  will be (9)

$$f(t) + f(-t+7) = \pi(t-3) - \pi(t-4) - u(t-4) + \pi(-t+4) - \pi(-t+3) - u(-t+3)$$

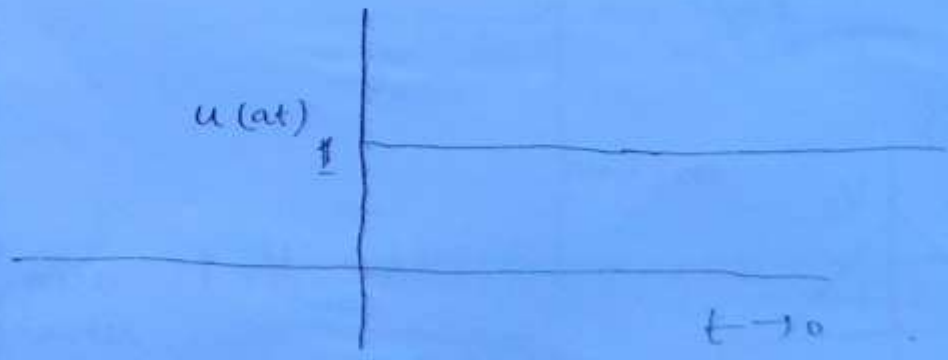


if shifting and reversal operation both involved in given transformation the normal order we follow shifting first and then reversing but we can also do this process in reverse order  $f(-t+7)$

reversal  $f(t) \rightarrow f(-t)$   
 shift by  $\uparrow$   $f(-t+7)$   
 delayed



$f(\ominus(t-7))$   
 $f(at+b)$   
 $f(a(t+b/a))$

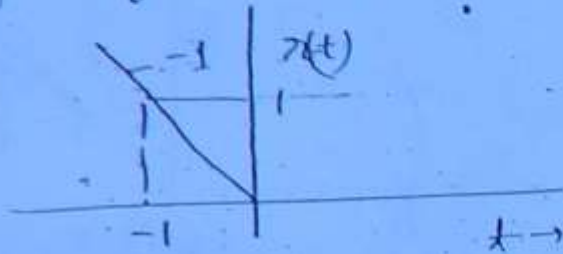




$$x(at) = \begin{cases} at & at \geq 0 \\ 0 & at < 0 \end{cases} \rightarrow \{a > 0\}$$

(10)

\* in comp signal scaling of time results in scaling of magnitude (amplitude).



$$x(t) = \begin{cases} -t & t \leq 0 \\ 0 & t > 0 \end{cases}$$



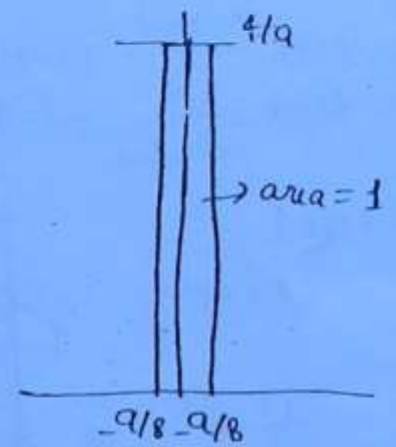
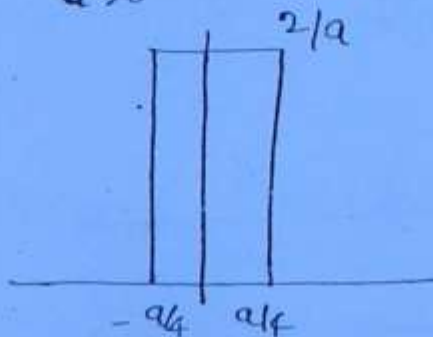
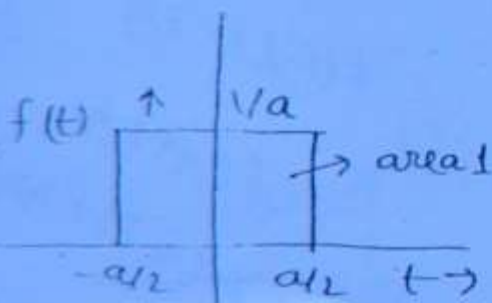
definition of delta function

$$\delta(t) = \begin{cases} 0 & t \neq 0 \\ \neq 0 & t = 0 \end{cases} \quad \text{also called dirac delta function.}$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

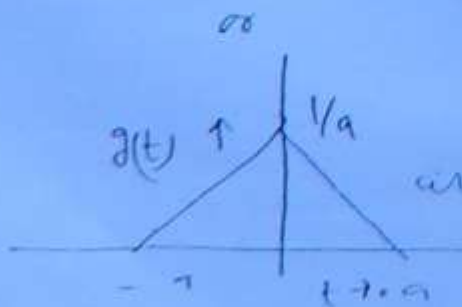
unit impulse means  
↓  
means area  $\int_{-\infty}^{\infty} \delta(t) dt = 1$

$$\delta(t) = \lim_{a \rightarrow 0} f(t)$$



$a \rightarrow 0$

height  $\rightarrow \infty$



area = 1

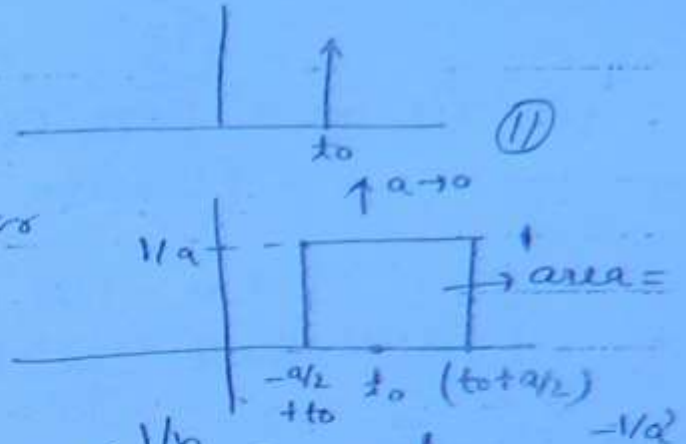
$a \downarrow$

$1/a \uparrow$

area remain same

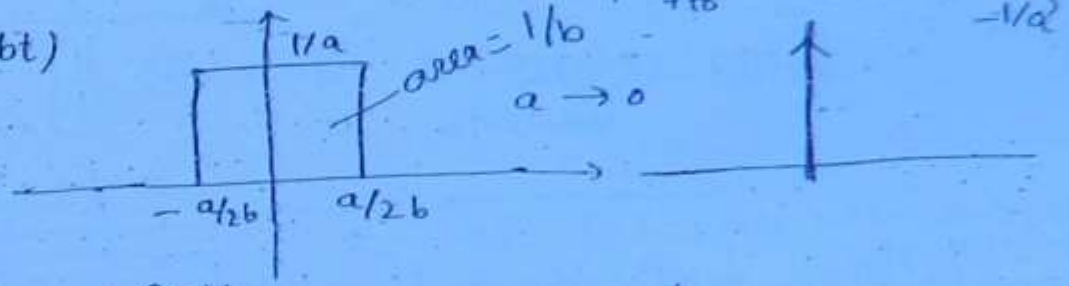
$$\delta(t) = \lim_{a \rightarrow 0} g(t)$$

$$\delta(t-t_0) = \lim_{a \rightarrow 0} f(t-t_0) =$$

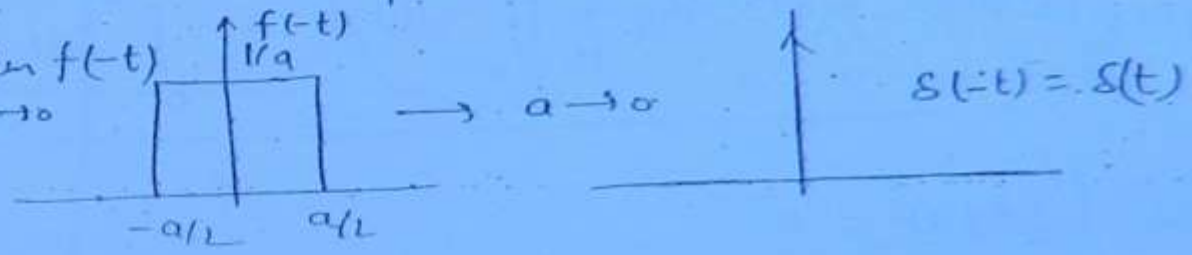


$$\delta(bt) = \lim_{a \rightarrow 0} f(bt)$$

$$= \frac{1}{|b|} \delta(t)$$



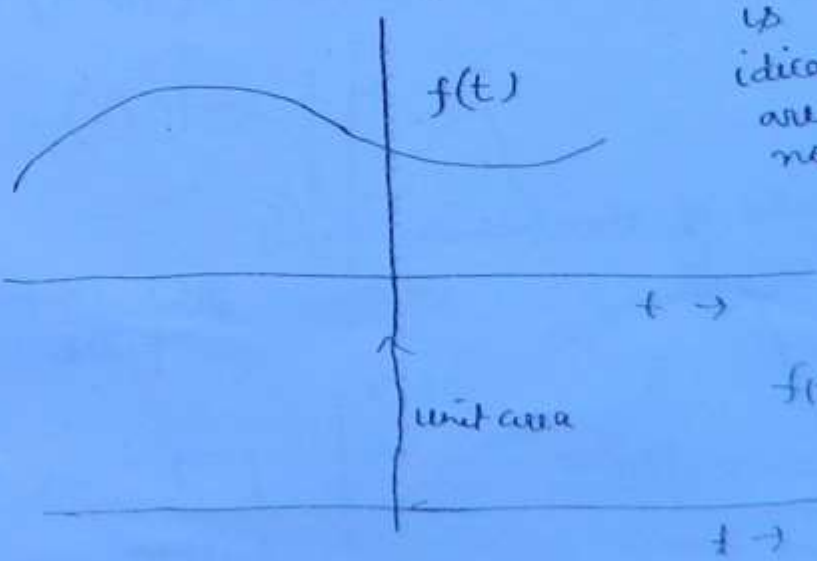
$$\delta(-t) = \lim_{a \rightarrow 0} f(-t)$$



$$\delta(-2t) = \frac{1}{2} \delta(t)$$

$$\delta(-2t) = \delta(2t) = \frac{1}{2} \delta(t)$$

$$\delta(bt) = \frac{1}{|b|} \delta(t)$$



height is indicating area not the value

$$f(t) \cdot \delta(t) = f(0) \cdot \delta(t) = S(t) \quad (\text{if } f(0) > 0)$$

(12)

amplitude  $\infty$  but effect on area area will become

$= f(a) b/w$

$f(t) \delta(t-a) = f(a) \cdot \delta(t-a) \rightarrow$   
 $= f(a) \delta(t)$

sampling Property of  $(-\infty \text{ to } \infty)$    
impulse signal  $(\text{curly})$

$\int_{-\infty}^{\infty} f(t) \delta(t) dt = f(0) \int_{-\infty}^{\infty} \delta(t) dt = f(0)$

$\int_{-\infty}^{\infty} f(t) \delta(t-a) dt = f(a) = \int_a^{\infty} f(a) \delta(t-a) dt$   
 $= f(a) \int_{-\infty}^{\infty} \delta(t-a) dt = f(a)$

$\int_{-\infty}^{\infty} \delta(t) dt = \int_{-1}^1 \delta(t) dt = \int_{-a}^a \delta(t) dt = \int_{0^-}^{0^+} \delta(t) dt = 1$

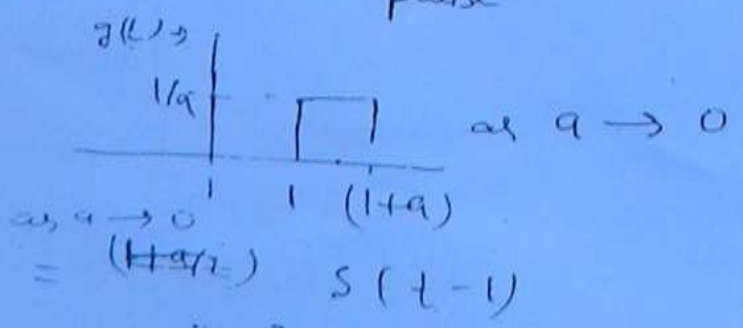
$\int_{-\infty}^{\infty} \delta(t) dt = 0$

calculate following  $\rightarrow$  (i)  $\int_{-\infty}^{\infty} \delta(t - \pi) \sin(t - \pi) \delta(t - \pi/2) dt$   
 $= \sin(\pi/2 - \pi) = \sin(-\pi/2)$   
 $= -\sin \pi/2 = -1$

Q  $\int_{-\infty}^{\infty} \sin(t - \pi) \delta(3t - \pi/2) dt = \frac{1}{3} \sin(\pi/6 - \pi)$   
 $= + \frac{1}{3} \sin(\pi/6)$

Q- (ii) Find the value of the following integral  $= -1/6$   
 $\int_{-\infty}^{\infty} \frac{\sin(\pi t - \pi/2)}{(t^2 + 4)} g(t) dt$  where  $g(t)$  is following pulse

(iii)  $= \frac{\sin \pi/2}{5} = 1/5$

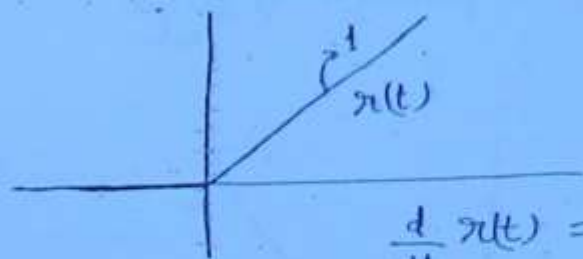


15<sup>th</sup> Oct 10

differentiation →

$$f(t), \frac{df(t)}{dt}$$

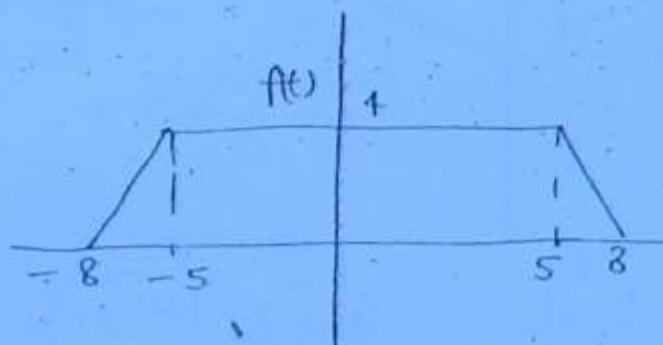
(13)



$$f(t) = mt + c$$

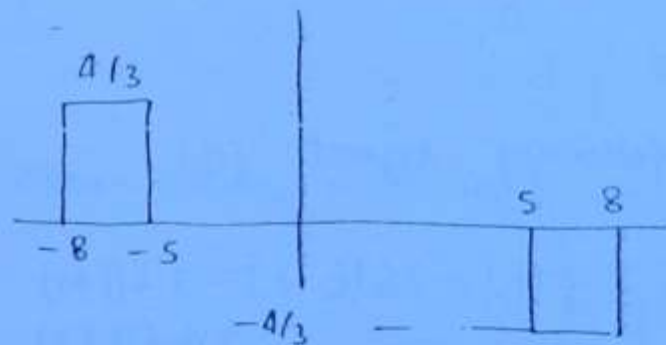
$$\frac{df(t)}{dt} = m$$

$$\frac{d \pi(t)}{dt} = \begin{cases} 1 & 0 \leq t < 1 \\ 0 & \text{otherwise} \end{cases} = u(t)$$

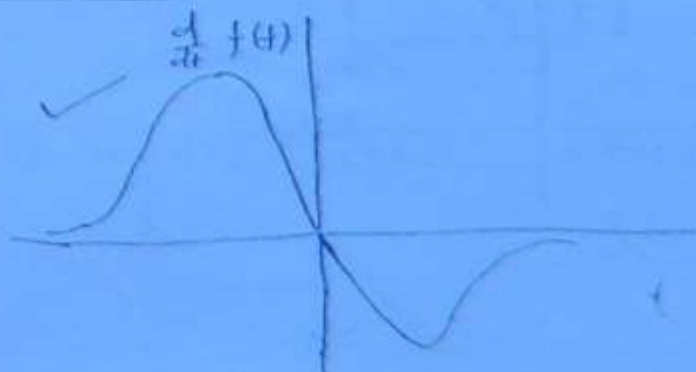
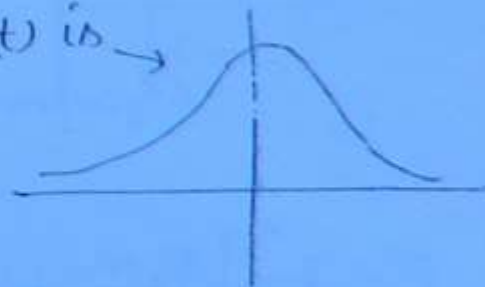
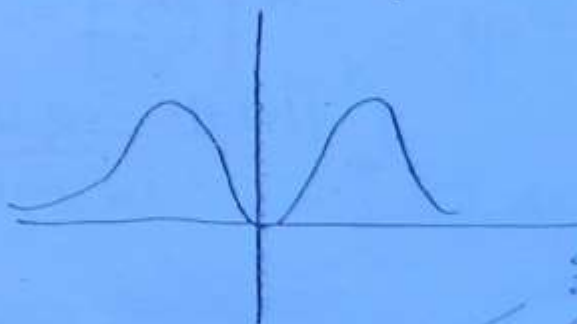


$$\text{or } f(t) = \frac{4}{3} \pi(t+8) - \frac{4}{3} \pi(t-5) + 4$$

$$\left\{ \begin{aligned} \frac{d}{dt} f(t) &= \frac{4}{3} - \frac{4}{3} - \frac{4}{3} + 4 \\ &= 0 \text{ for } t > 8 \end{aligned} \right.$$



Q derivative of the following signal  $f(t)$  is →



$$\int_{-\infty}^{\infty} f(t) dt = K \text{ (scalar } \rightarrow \text{ may be finite or infinite)}$$

$$\int_{-\infty}^{t} f(\tau) d\tau = g(t) \text{ area as a function of time}$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

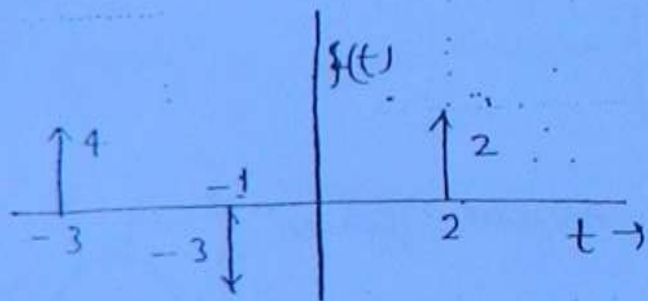
$$\int_{-\infty}^t \delta(\tau) d\tau = \begin{cases} 1 & \text{if } t \geq 0 \\ 0 & \text{if } t < 0 \end{cases}$$

$$= u(t)$$

$$\frac{d}{dt} u(t) = \delta(t)$$

$$x(t) = \int_{-\infty}^t u(t) dt$$

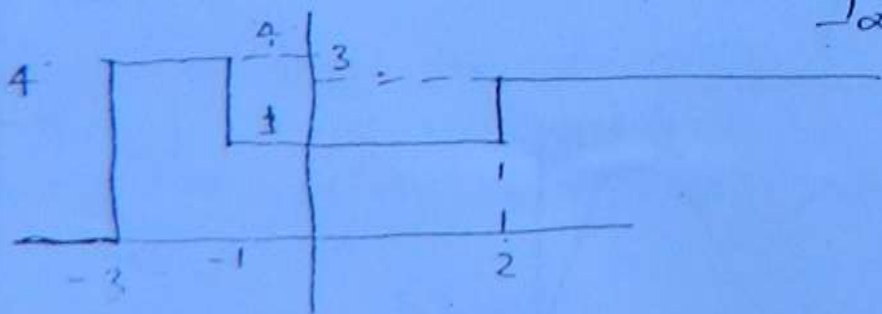
Calculate the integral of following signal  $f(t)$ .



$$f(t) = 2\delta(t-2) - 3\delta(t+1) + 4\delta(t+3)$$

$$\int_{-\infty}^{\infty} f(t) dt = 3$$

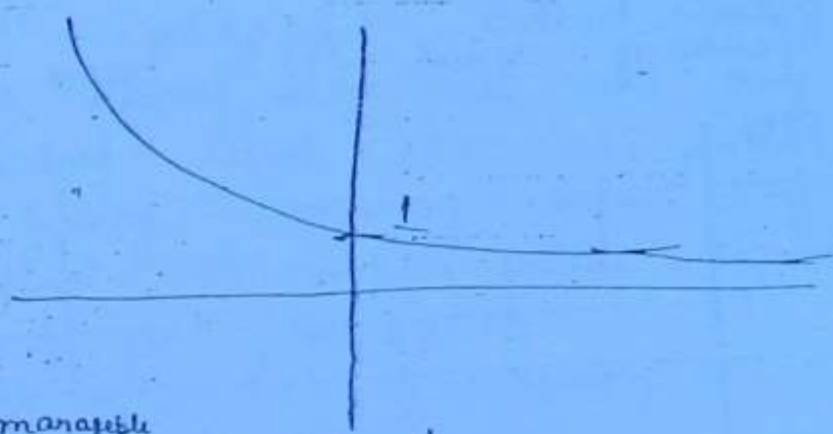
$$\int_{-\infty}^t f(\tau) d\tau = 2u(t-2) - 3u(t+1) + 4u(t+3)$$



$$\frac{d}{dt} e^{-at} = -a e^{-at}, \quad \frac{d}{dt} e^{at} = a e^{at}$$

$$\int_{-\infty}^t e^{-at} dt = \left[ \frac{e^{-at}}{-a} \right]_{-\infty}^t = \frac{1}{a} [e^{-at} - \infty]$$

= not defined  
unmanageable.



$$\int_{-\infty}^t \overset{\text{manageable}}{e^{-at} u(t)} dt = \int_0^t e^{-at} dt$$

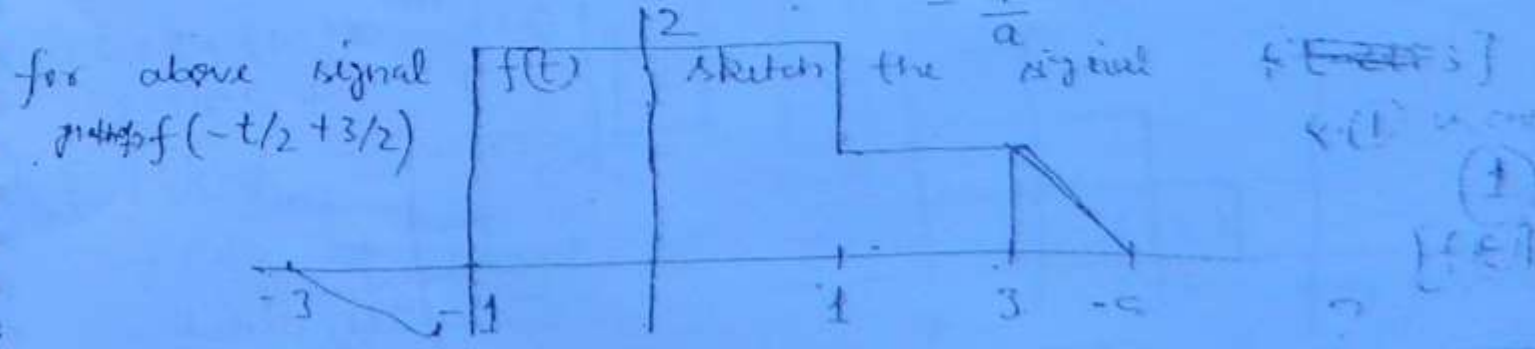
$$= -\frac{1}{a} [e^{-at} - 1]$$

area under  $e^{-at} u(t) = \int_{-\infty}^{\infty} e^{-at} u(t) dt$

$$= \int_0^{\infty} e^{-at} u(t) dt$$

$$\int_{-\infty}^t e^{at} dt = \left[ \frac{e^{at}}{a} \right]_{-\infty}^t = \frac{1}{a} [e^{at}] \text{ unmanageable}$$

$$\int_{-\infty}^t \overset{\text{manageable}}{e^{at} u(-t)} dt = \int_{-\infty}^0 e^{at} dt = \frac{1}{a} [e^{at}]_{-\infty}^0 = \frac{1}{a}$$

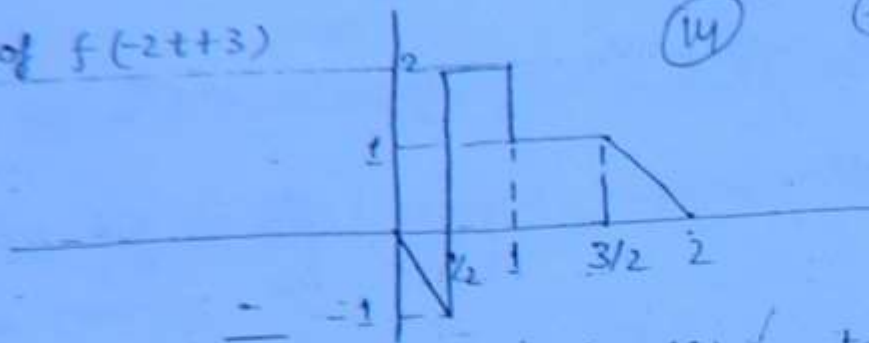


Graph of  $f(-2t+3)$

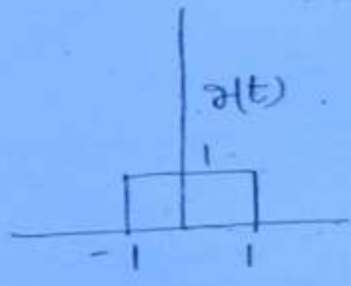
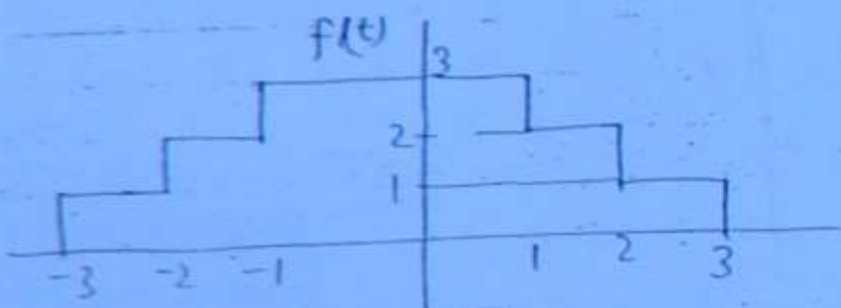
(14)

$$(-2t+3) = t_1$$

$$t = -t_1/2 + 3/2$$



Q. Represent the following signal  $f(t)$  in terms of  $g(t)$

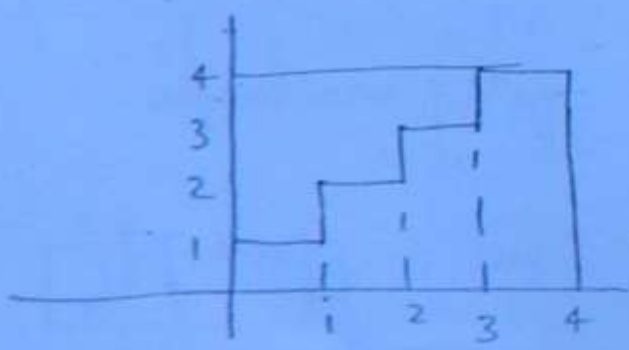


$$f(t) = \left\{ \cancel{g(t+2)} + \overset{\text{wrong}}{g(t+1)} + g(t) + g(t-2) - g(t-3) \right. \\ \left. - g(t-4) \right\}$$

$$f(t) = g(t/3) + g(t/2) + g(t)$$

Q. Represent the following signal  $f(t)$  in terms of  $g(t)$

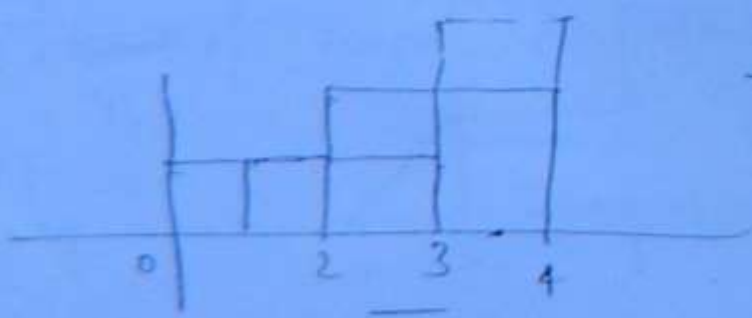
$g(t)$  is same in previous question



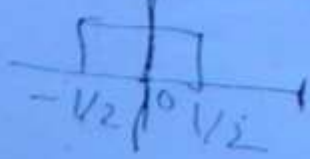
$$g(t-1) + g(t-2) + 2g(t-3) \\ + \cancel{g(t-4)} \\ + 2g\left[\frac{2}{3}(t-7/2)\right]$$

Ans -

$$f(t) = g(t-1) + g(t-2) \\ + 2g(t-3)$$



$$+ 2g[2t-7]$$



Types of signal →

can be real value signal or complex value signal  
 $f(t) = at$  real valued  
 $f(t) = at + ibt$  complex valued.

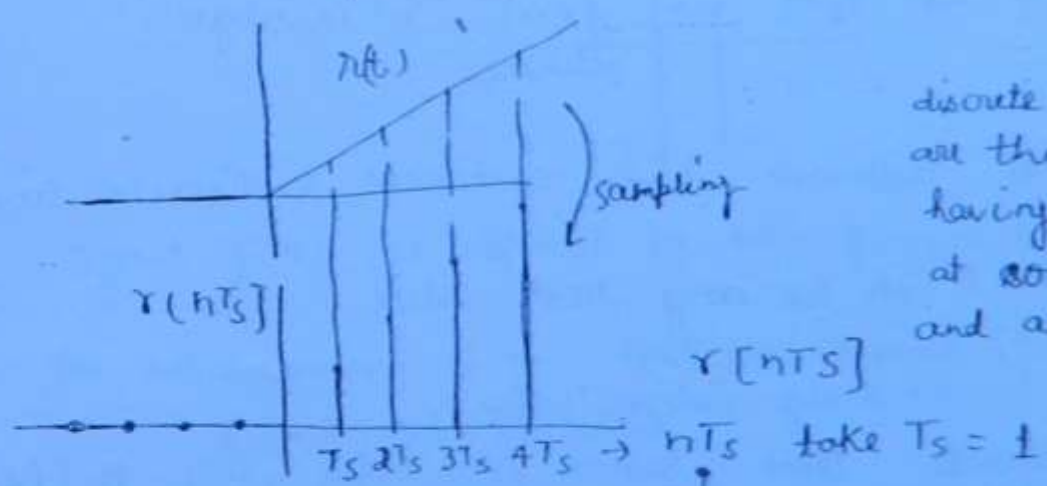
$e^{it} = \cos t + j \sin t$  Euler's identity

- \* Signals having only real value they are called as real valued signal  $f(t) = \cos t, \sin t$ , real valued signal
- \* Signals having imaginary value along with real value are defined as complex valued signal.

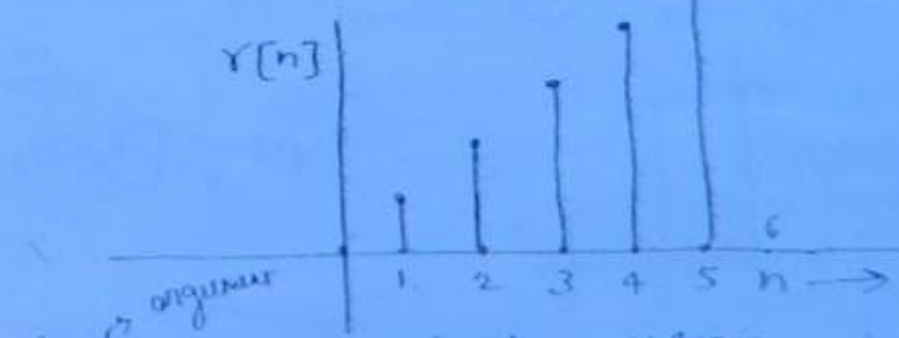
eg.  $e^{it} = \cos t + j \sin t$   
real part =  $\cos t$ , imaginary part =  $\sin t$

Continuous time & discrete time signal →

⊕ Continuous time signals are those signal having def value for every real value of time.



discrete-time signals are those signals having defined values at some fixed instants and at other instants undefined.



$f[n]$  →  $n$  must be integer, discrete time signal  
 $f(t)$  → any real value, continuous time signal



$$f[n] = \begin{cases} -1, & \uparrow \\ 1, & \uparrow \\ 2, & \uparrow \\ -2 \end{cases}$$

(16)

$$-1 \rightarrow n = -1$$

$$1 \quad n = 0$$

$$2 \quad n = 1$$

$$-2 \quad n = 2$$

0 otherwise other values of  $n$ .

\* Continuous time signal is that signal which is defined for all values of time.

\* A discrete time signal is a signal which is defined only for specific values of time. It is not defined for other values of time. A discrete time signal is derived from a continuous time signal by a procedure called as uniform sampling and then selecting uniform sampling interval value to be 1.

$$f(t) \rightarrow f[nT_s] \rightarrow T_s = 1 \rightarrow f(n) \quad n \text{ is integer.}$$

continuous discrete

Fundamental difference b/w continuous & discrete time signal

is  $f(t)$

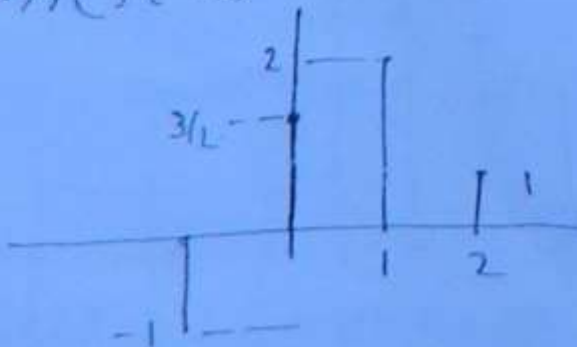
$\rightarrow t$  can be any real value

$f(n)$

$\rightarrow n$  only integer value.

\* For a discrete time signal  $f(n)$ , value like  $f(4/3)$ ,  $f(5/6)$ ,  $f(-2/3)$  are not defined.

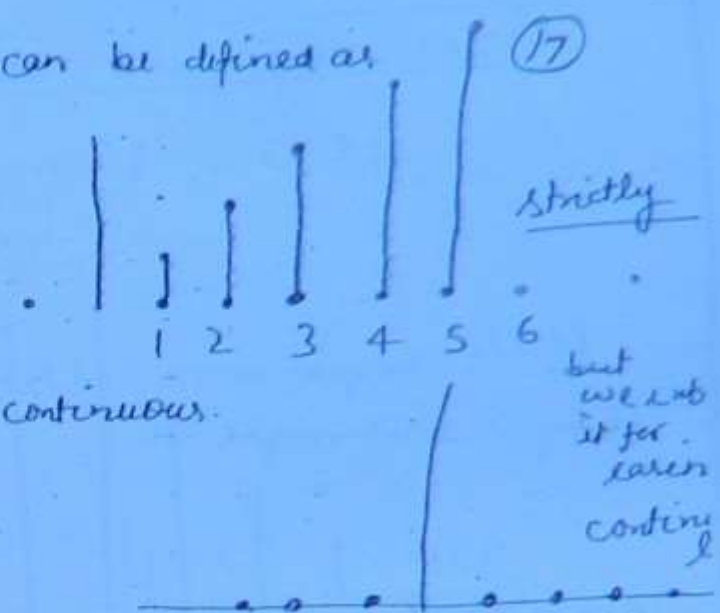
an eg  $\rightarrow$



$$f(n) = \begin{cases} -1, & n = -1 \\ 3/2, & n = 0 \\ 2, & n = 1 \\ 1 \end{cases}$$

discrete time ramp signal can be defined as (17)

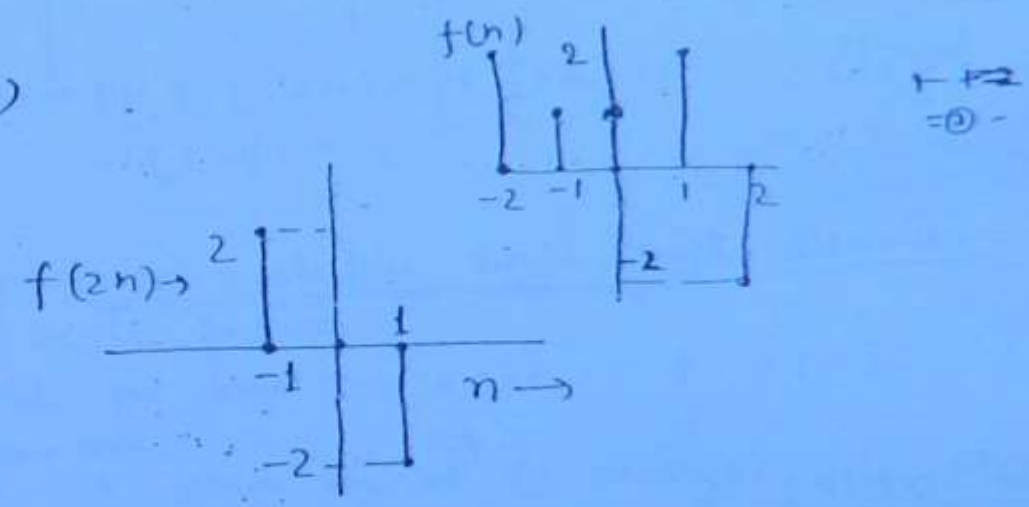
$$x[n] = \begin{cases} n & n \geq 0 \\ 0 & \text{otherwise} \end{cases}$$



∅ n-axis discrete  
amplitude axis is continuous.

$$f(n) \xrightarrow{n \rightarrow n-3} f(n-3)$$

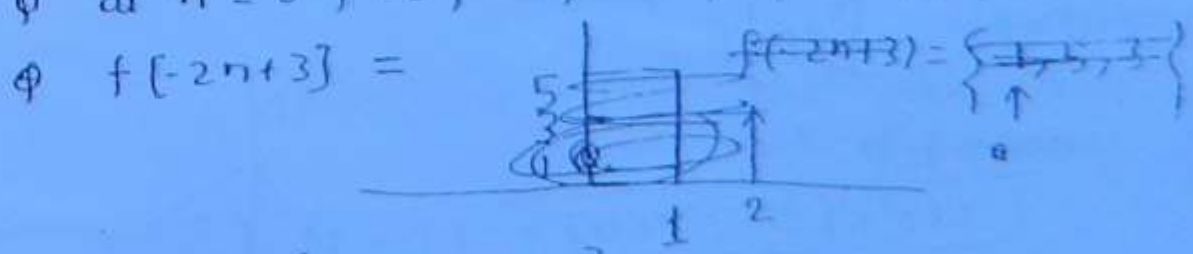
$$f(2n) \rightarrow$$



Q. Signal  $f(n)$  is defined to be  $f(n) = \{1, 2, 3, 4, 5\}$

for what values of  $n$  will the signal  
 $f[-2n+3]$  be zero  
 $f[-2(n-3/2)]$

∅ at  $n = 0, -2, -4, \dots, +2, 4$



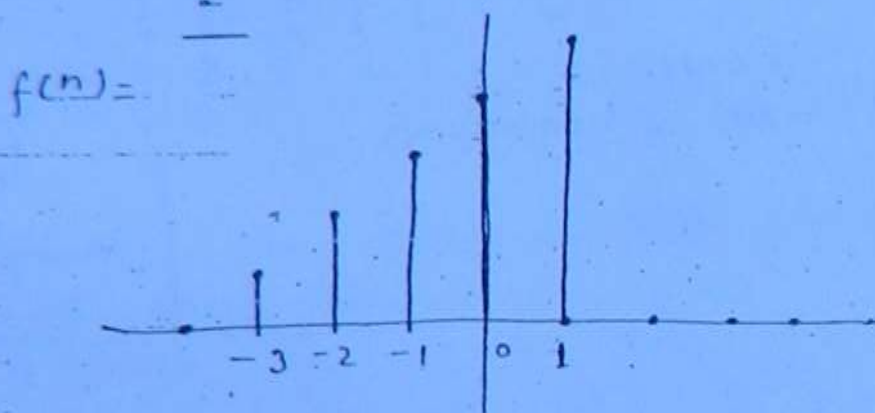
$$f[-2n+3] = \begin{cases} 0, 5, 3, 1 \\ \uparrow \\ \end{cases} \text{ for } n \leq 0 \text{ and } 0 < n < 3$$

9

discrete time unit step signal  $\rightarrow$

(18)

$$u[n] = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases}$$



$$f(n) = u[n+3] + u[n+2] + u[n+1] + u[n] + u[n-1] - 5u[n-2]$$

discrete time unit impulse function  $\rightarrow$

area of  $\delta(t) = 1$

$$\delta[n] = \begin{cases} 1 & n = 0 \\ 0 & n \neq 0 \end{cases}$$

$\rightarrow$  by defining value 1 we are making it manageable.

17<sup>th</sup> Oct 10:

$$\delta[n] = u[n] - u[n-1]$$

$$\delta(t) = \frac{du(t)}{dt}$$

$$u[n] = \sum_0^n \delta[n-k]$$

$$u(t) = \int_{-\infty}^t \delta(t) dt$$

$$u[n] = \sum_{k=-\infty}^n \delta[k]$$

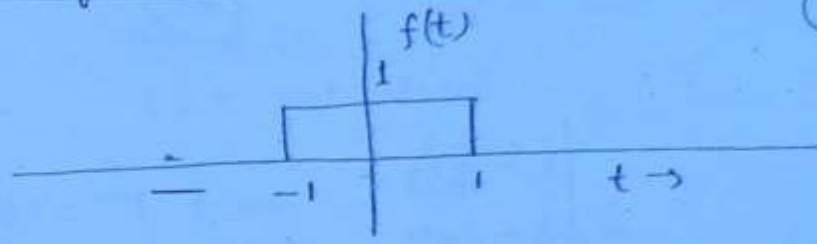
$$\delta[n] =$$

$$u[n] = \sum_{k=-\infty}^n u[k]$$

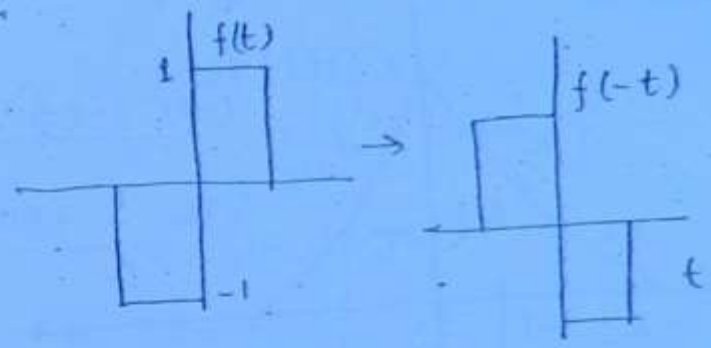
$$\delta[n] = \sum_{k=-\infty}^n \delta[k]$$

Even signal or odd signals :

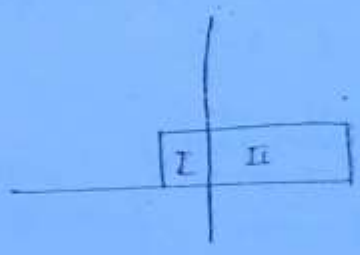
(19)



$f(-t) = f(t)$  even signal.  
or symmetrical signals



odd signal  
or antisymmetrical  
signal.

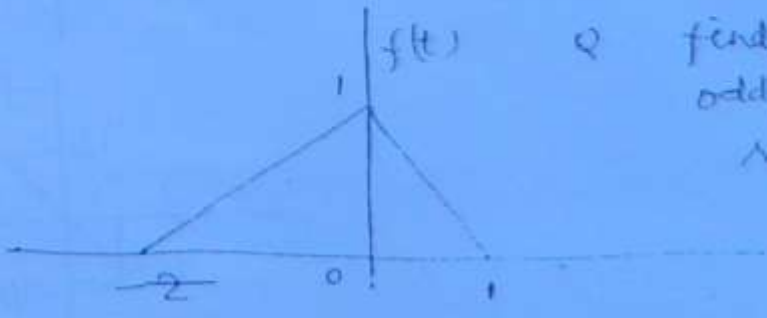


neither even nor odd signal.

$f(t) + f(-t) \rightarrow$  even signal (always)  
 $f(t) - f(-t) \rightarrow$  odd signal.

$f(t) = \frac{1}{2} [ \text{even signal} + \text{odd signal} ]$   
                   even part of  $f(t)$       odd part of  $f(t)$ .

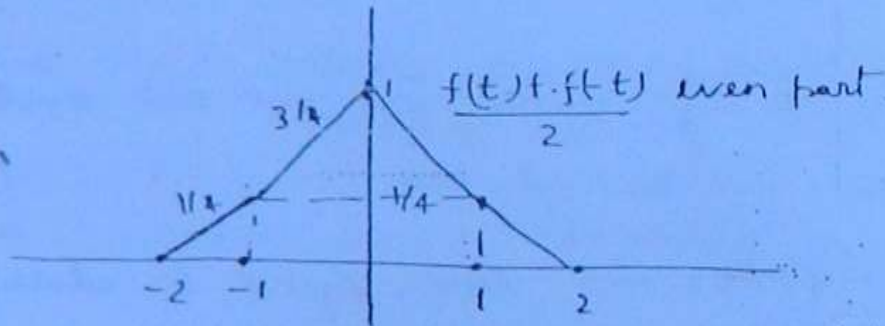
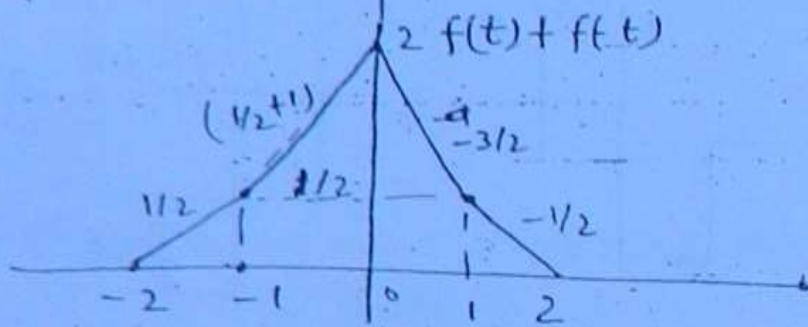
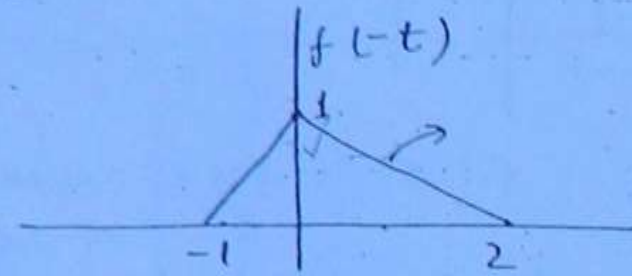
$\cos(t) = \cos(-t) \rightarrow$  even signal or symmetrical signal  
 $\sin(t) = -\sin(-t) \rightarrow$  odd signal or antisymmetrical signal  
 (opposite symmet)



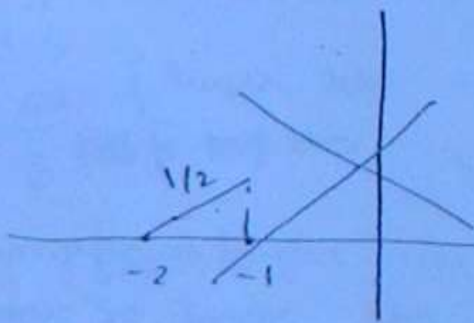
Q find the even and odd part of following signal  $f(t)$ .

$$\text{even part} = \frac{1}{2} [f(t) + f(-t)]$$

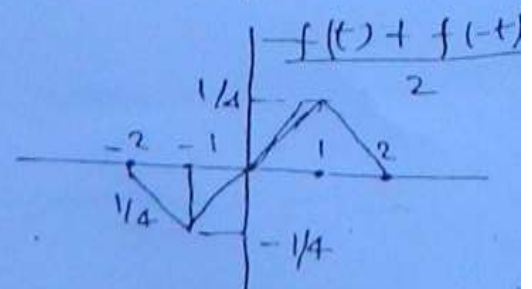
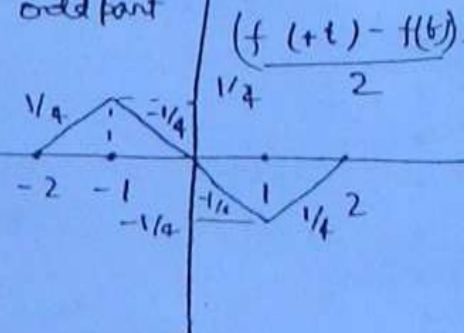
(20)



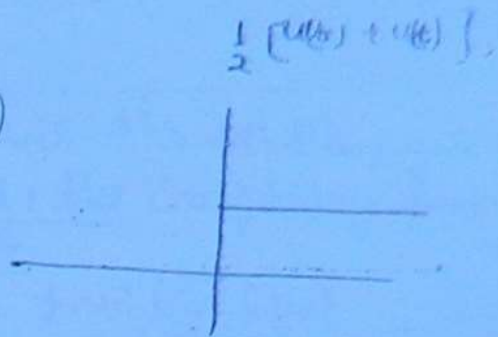
odd part



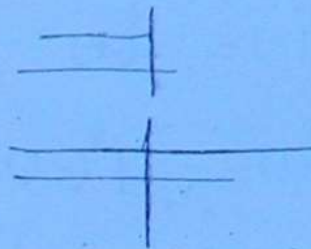
odd part



$$u(t) = \begin{cases} 1 & t > 0 \\ 0 & t < 0 \\ t=0 & \text{not defined} \end{cases} \quad (21)$$



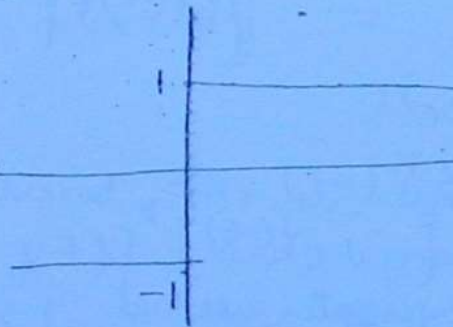
$$u(t) = \begin{cases} -1 & t > 0 \\ 0 & t < 0 \\ 1/2 & t = 0 \end{cases} \quad \text{take any definition}$$



$$u_e(t) = \frac{u(t) + u(t)}{2} = 1/2$$

$$u_o(t) = \frac{u(t) - u(t)}{2} = \frac{1}{2} \text{sgn}(t)$$

$$\text{sgn}(t) = \begin{cases} 1 & t > 0 \\ -1 & t < 0 \end{cases}$$



four definitions }  
any we can take }  
 $t=0$  undefined  
 or 1  
 or -1  
 or 0

Q. find @ even and odd part of  $f(t) = \sin(t) u(t)$

$$f(t) = e^{jt} = \cos t + j \sin t$$

(2.2)

$$f_e(t) = \frac{e^{jt} + e^{-jt}}{2} = \cos t$$

$$f_o(t) = j \sin t$$

$f(t)$  &  $f^*(t)$

\*

- $f(t) = f^*(-t)$  even conjugate signal  
conjugate symmetric signal
- $f(t) = -f^*(-t)$  odd conjugate signal  
or conjugate antisymmetric signal

$e^{jt} \rightarrow$  even conjugate signal

$$f(t) = f^*(-t) = [e^{j(-t)}]^* = e^{jt}$$

ii)  $j e^{jt}$

$$= -f^*(-t) = -[j e^{j(-t)}]^* = -[-j e^{jt}] = j e^{jt}$$

odd conjugate signal

$$f(t) = e^{jt} = \underbrace{\cos t}_{\text{even}} + j \underbrace{\sin t}_{\text{odd}}$$

\* for an even conjugate signal

Real part  $[f(t)] =$  even part of  $f(t) \rightarrow$  even in nature

odd part  $[f(t)] =$  ~~odd~~ imaginary part of  $f(t)$

$$j e^{jt} = -\underbrace{\sin t}_{\text{odd}} + j \underbrace{\cos t}_{\text{even}}$$

(\*) for a complex valued signal which is even conjugate in nature real part is always even and imaginary part is always odd.

⊛ For a complex valued signal which is odd conjugate in nature real part is always odd and imaginary part is always even.

$$f(t) = f_{ec}(t) + f_{oc}(t)$$

(23)

$$f^*(t) = f_{ec}^*(t) + f_{oc}^*(t)$$

$$f^*(-t) = f_{ec}^*(t) + f_{oc}^*(-t)$$

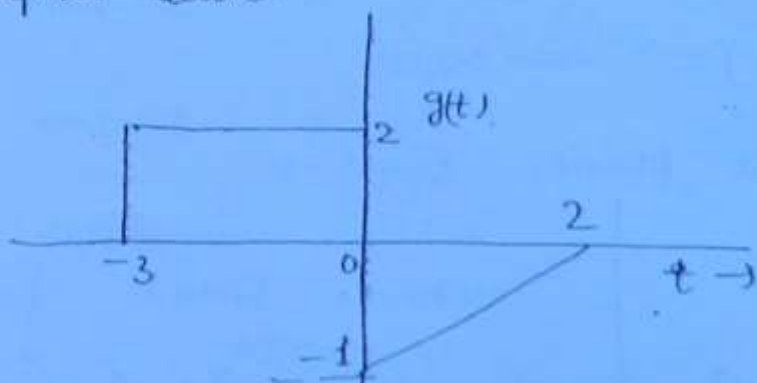
$$= f_{ec}(t) - f_{oc}(t)$$

$$f_{ec}(t) = \frac{1}{2} [f(t) + f^*(-t)]$$

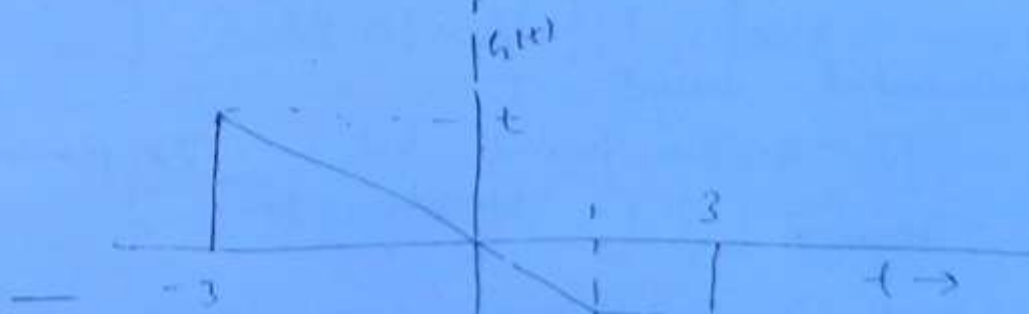
$$f_{oc}(t) = \frac{1}{2} [f(t) - f^*(-t)]$$

J  
0  
 $\frac{f(t) + J}{\sin(t) + j}$   
 $\frac{\sin(t) - j}{- \cos(t)}$

Q. A complex valued signal  $f(t)$  is defined with a real part  $\rightarrow [g(t) \rightarrow g(-t)]$  and imaginary part which is  $[h(t) + [h(t)]]$  where  $g(t)$  &  $h(t)$  are as defined below.



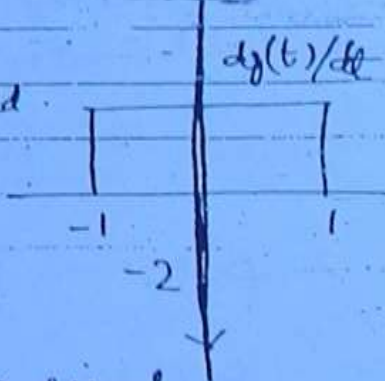
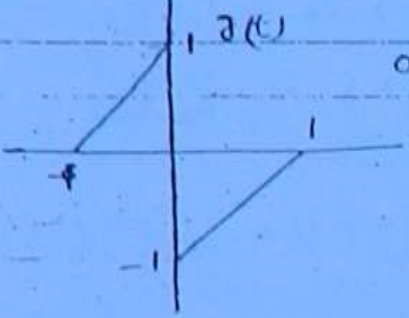
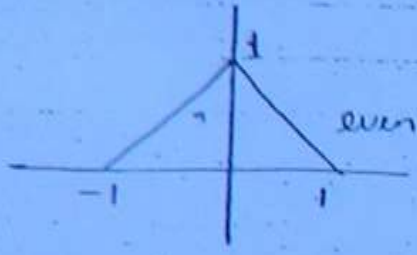
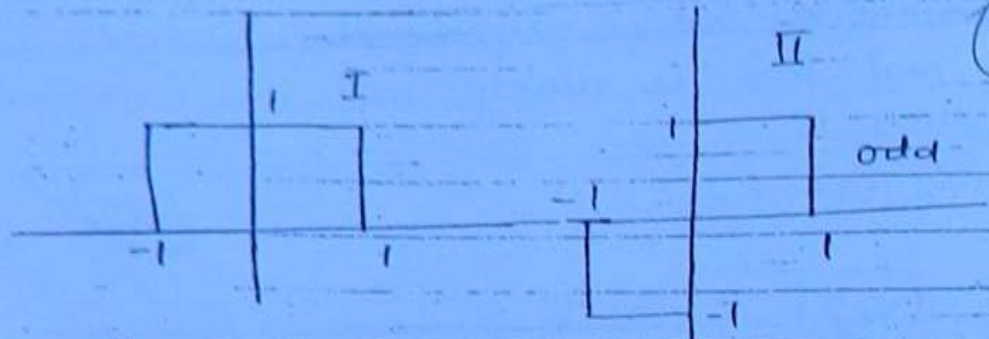
then the signal  $f(t)$  is even comp  
✓ odd comp  
neither even  
nor odd  
can't comment



12



2.4-



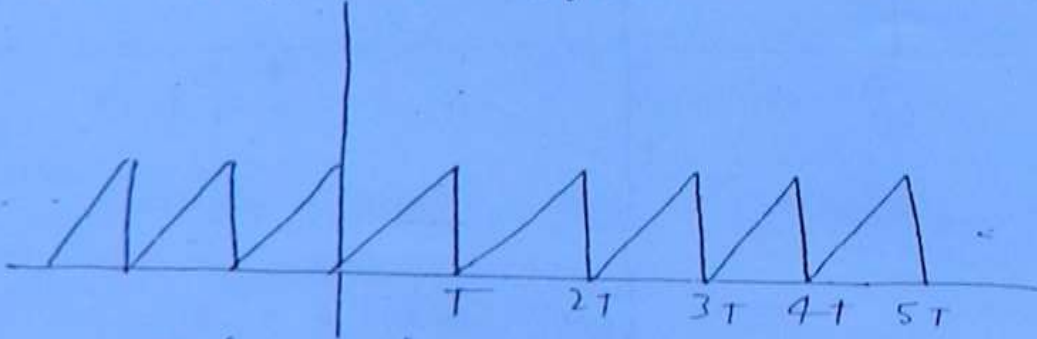
$$\int_{-a}^a f(t) dt = 2 \int_0^a f(t) dt \quad \text{for even signal}$$

$$\int_a^a f(t) dt = 0 \quad \text{for odd signal}$$

$$\frac{d}{dt} [\text{even signal}] = \text{odd signal}$$

$$\frac{d}{dt} [\text{odd signal}] = \text{even signal}$$

periodic and a periodic signal  $\rightarrow$



fundamental period = T

$kT \rightarrow$  time period but not the fundamental period.  
 $\downarrow$   
 integer

any shifting will not change period.

$$f(t) = f(t \pm KT) \quad \begin{matrix} \nearrow \text{fundamental period} \\ \searrow \text{integer} \end{matrix}$$

(25)

fundamental period of  $\sin Kt \rightarrow \frac{2\pi}{|K|} \rightarrow$  also a period  $\frac{2\pi \times m}{|K|}$   
 $\downarrow$   
 Can be  $2\pi$

$\left. \begin{matrix} \sin t \\ \sin 2t \\ \sin 3t \\ \dots \\ \sin Kt \end{matrix} \right\} \rightarrow$  all has period  $2\pi$  (but this is not fundamental period for all except  $\sin t$ )

$$\int_0^{2\pi} \sin Kt \, dt = 0 \quad \left\{ \begin{matrix} \text{K complete cycle of period } \frac{2\pi}{|K|} \\ \text{so area} = 0 \end{matrix} \right.$$

$\uparrow$   
K is integer.

$\sin \omega_0 t \rightarrow \frac{2\pi}{\omega_0}$  fundamental period  
 $\sin 2\omega_0 t \rightarrow \frac{2\pi}{2\omega_0} \rightarrow \frac{\pi}{\omega_0}$   
 $\sin 3\omega_0 t \rightarrow \frac{2\pi}{3\omega_0}$

$\left. \begin{matrix} \text{Common} \\ \text{period} \\ \text{of} \\ \frac{2\pi}{\omega_0} \end{matrix} \right\}$

$$\int_0^{2\pi/\omega_0} \sin \omega_0 t \cdot \sin 2\omega_0 t \, dt = \frac{1}{2} \int_0^{2\pi/\omega_0} (\cos \omega_0 t - \cos 3\omega_0 t) \, dt = 0$$

$$\int_0^{2\pi/\omega_0} \cos \omega_0 t \cos 2\omega_0 t \, dt = \frac{1}{2} \int_0^{2\pi/\omega_0} (\cos 3\omega_0 t + \cos \omega_0 t) \, dt = 0$$

$$\int_0^{2\pi/\omega_0} \sin \omega_0 t \cos 2\omega_0 t \, dt = \frac{1}{2} \int_0^{2\pi/\omega_0} [\sin 3\omega_0 t - \sin \omega_0 t] \, dt = 0$$

$$\begin{cases} \sin \omega_0 t \\ \cos \omega_0 t \end{cases} \rightarrow 2\pi/\omega_0$$

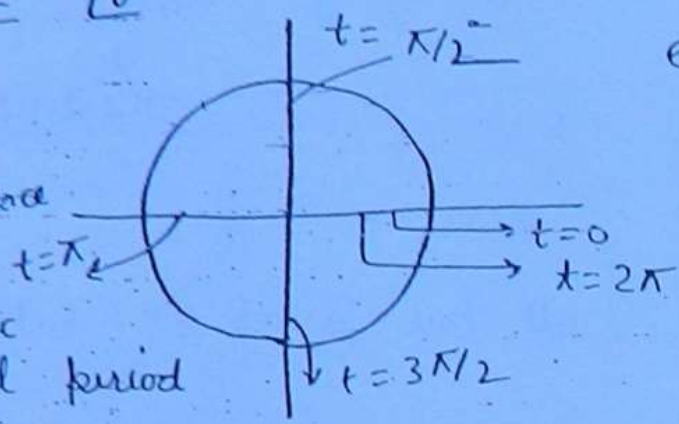
$$e^{j\theta} = \cos \theta + j \sin \theta = 1 \angle \tan^{-1}(\tan \theta)$$

$$= \angle 0$$

$$e^{j\omega t} = 1 \angle \omega t$$

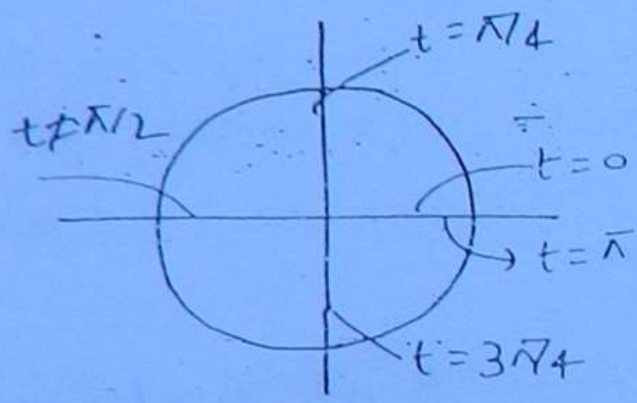
$$e^{j\omega t} \xrightarrow{\text{rev}} 2\pi$$

phase quantity  
 covering the circumference  
 of circle of unit  
 radius and periodic  
 with fundamental period  
 $2\pi$ .



$$e^{j(2t)}$$

$$= 1 \angle 2t$$



fundamental  
 period =  $\pi$

$$e^{jkt} \rightarrow \text{fundamental period } \frac{2\pi}{k}$$

$$e^{j\omega_0 t} \rightarrow \frac{2\pi}{\omega_0}$$

$$e^{-j\omega_0 t} \rightarrow \frac{2\pi}{\omega_0} \text{ rotate in opposite direction.}$$

Minimum No. of samples taken to repeat itself is defined as the fundamental time period of a discrete time periodic signal.

No. of samples is always a integer and hence time period of a discrete time signal is always an integer.

\* For a discrete time complex exponential  $e^{j\omega_0 n}$  to be periodic the condition is ratio  $\frac{2\pi}{\omega_0}$  must be rational, if it is rational the period

$$N = m \cdot \frac{2\pi}{\omega_0}$$

where  $m$  is selected to be a minimum possible integer such that above product is an integer.

$$e^{j\omega_0 n} \rightarrow \omega_0 \rightarrow (\omega_0 + 2\pi k) \rightarrow \text{integer}$$

\* A discrete time complex exponential signal there is no change in signal even if  $\omega_0$  is replaced by  $(\omega_0 + 2\pi k)$  i.e. discrete time complex exponential signals the frequencies  $\pi + 2\pi, \pi + 4\pi, \pi + 6\pi \dots$  so on,  $\pi - 2\pi, \pi - 4\pi \dots$  so on, all denote the same discrete time complex exponential signal.

same as  $\left. \begin{array}{l} \cos \omega_0 n \\ \sin \omega_0 n \end{array} \right\} \rightarrow \left( \frac{2\pi}{\omega_0} \right)$

rational  
integer

### Some of signals

$$\sin t + \sin 2t$$

$$\downarrow \quad \downarrow$$

$$2\pi \quad \pi$$

over all period =  $2\pi$

$$\frac{T_1}{T_2} = 2 \rightarrow \text{rational number}$$

$$\frac{\sin t + \sin \pi t}{T = 2\pi \quad T = \pi}$$

$$\therefore T_1 = \pi \text{ not rational}$$



$$x_{ec}[n] = \frac{x[n] + x^*[-n]}{2} \quad (29)$$

$$= \left\{ \begin{array}{c} -2.5j \quad 1 \\ \quad \quad \quad \uparrow \\ \quad \quad \quad 2.5j \end{array} \right\}$$

$$\begin{aligned} \therefore E_{ec} &= 1 + (2.5)^2 + (2.5)^2 \\ &= 1 + 6.25 + 6.25 \\ &= 13.5 \text{ J} \end{aligned}$$

$$\begin{aligned} \int_{-\infty}^{\infty} f^2(t) dt &= \int_{-\infty}^{\infty} [f_c(t) + f_o(t)]^2 dt \\ &= \int_{-\infty}^{\infty} f_c^2(t) dt + \int_{-\infty}^{\infty} f_o^2(t) dt + 2 \int_{-\infty}^{\infty} f_c(t) f_o(t) dt \\ &= E_e + E_o + 0 \end{aligned}$$

odd sign

$$\boxed{E = E_e + E_o}$$

Causal or Non Causal signal

↳ the signal which not start before zero

↳

If signal start before zero then it is a noncausal signal. (all periodic signals are noncausal)

Deterministic or Random signal :

\* A signal which can be defined by well defined mathematical expression, it is called as deterministic signal.

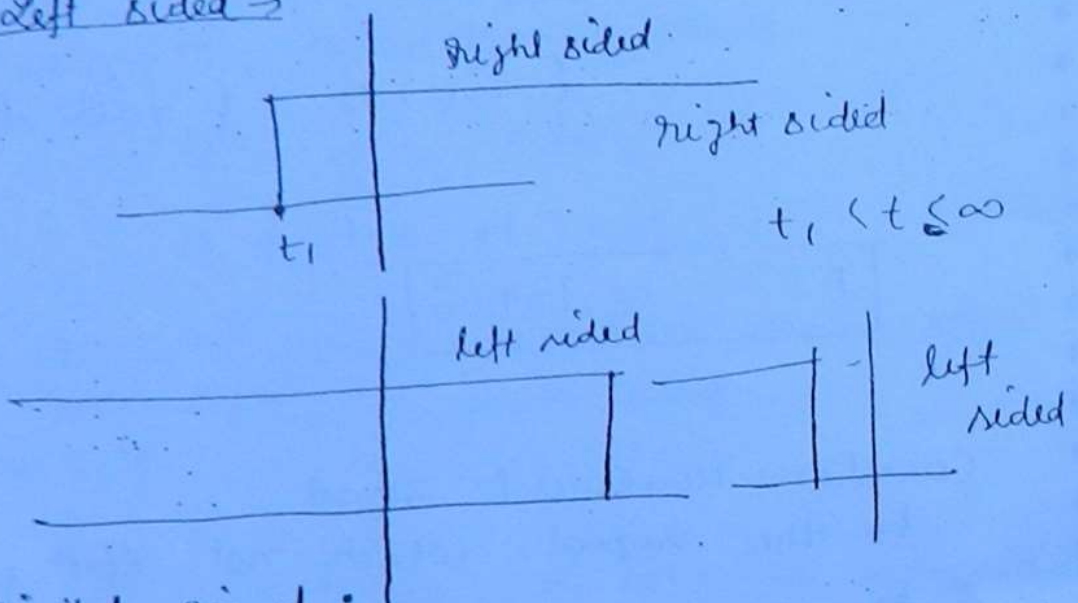
\* A signal for which we can't give a well defined mathematical expression is defined as a random signal.

Bounded or unbounded signal →  
\* If the amplitude of signal have some finite boundaries for all values of time it is called as bounded signal

—  $|f(t)| < \infty$   
 $|f(t)| < M \rightarrow$  finite } for all t, bounded signal

if signal value become infinite for any value of time, it is called as unbounded signal.

Right sided or Left sided →



Analogy or digital signal :

\* A signal which can assume infinite no. of values for its amplitude is defined as analog signal.  
\* If a signal is allowed only to assume finite no. of amplitude then the corresponding signal is a digital signal. A digital signal is that signal which may discrete in both on time axis & amplitude axis.

$$f(t) u(t) = 0$$

$$f(t)$$

Match the following:

(31)

List-I

expression of  $f(t)$

- A.  $f(t) [1 - u(t)] = 0$
- B.  $f(t) + K \frac{df(t)}{dt} = 0$  ( $K = +ve$ )
- C.  $f(t) + K \frac{d^2f(t)}{dt^2} = 0$
- D.  $f(t) [g(t) - g(0)] = 0$   
arbitrary  $g(t)$

List-II

nature of  $f(t)$

- (i) Increasing exponential
- (ii) Causal signal
- (iii) decreasing exponential
- (iv) Sinusoidal
- (v) Impulse

- C → (iv)
- B → (ii)
- A → (i)
- D → (v)

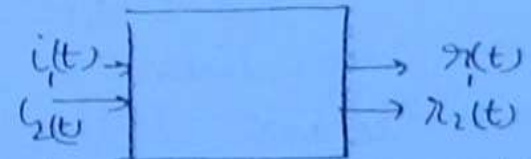
$$f(t) g(t) = f(t) g(0)$$

$$A \rightarrow f(t) = f(t) u(t)$$

$$t < 0$$

$$f(t) = 0$$

System :



(\*) A system is a quantity which maps a set of i/p signals to a set of o/p signals  
we can understand a system by

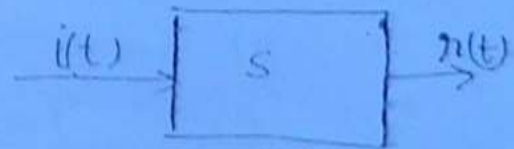
- (i) i/p - o/p relationship
- (ii) Physical composition
- (iii) differential equation or difference equations
- (iv) Unit impulse response  $h(t), h[n]$
- (v) Transfer function  $H(\omega), H(s), H(z)$
- (vi) State variable

$$V = L \frac{di}{dt}$$

$$i = \frac{dV}{dt}$$

our  $\frac{dV}{dt}$

total constant





$i(t) \xrightarrow{S} r(t)$   
Linear system or Nonlinear system where  $a$  is a real or imaginary quantity or constant [like 2 or 2j]

$i(t) \xrightarrow{S} r(t)$   
 $a i(t) \xrightarrow{S} a r(t)$  homogeneity principle

$i_1(t) \xrightarrow{S} r_1(t)$   
 $i_2(t) \xrightarrow{S} r_2(t)$   
 $a i_1(t) + b i_2(t) \xrightarrow{S} a r_1(t) + b r_2(t)$  Linearity principle

$i_1(t) + i_2(t) \xrightarrow{S} r_1(t) + r_2(t)$  superposition principle or additivity principle

⊗ A system satisfying both homogeneity & superposition principle then it is said to be linear system. If it can not satisfy one of these principle or both, it is defined as non linear system.

$r(t) = 2i(t) + 3 \rightarrow$  not linear

$r(t) = \log i(t) \rightarrow$  not linear

$r(t) = i^2(t) \rightarrow$  non linear

$r(t) = t i(t) \rightarrow$  linear

$r(t) = \sin t i(t) \rightarrow$  linear

$r(t) = \int_{-\infty}^t i(t) dz \rightarrow$  linear ✓

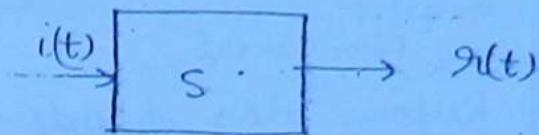
$r(t) = \int_{-5}^5 i(t) dz \rightarrow$  linear

✓  $r(t) = \text{real part of } \{ i(t) \}$  not linear.

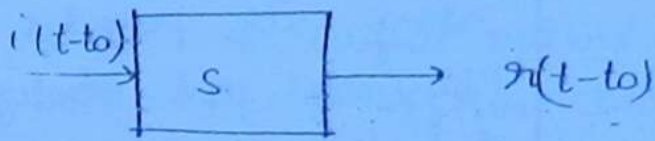
it does not hold homogeneity for an  $a = j b$  means  $a i(t)$  will not be  $a r(t)$  non linear ✓ real ✓

time variant or time invariant. →

(33)



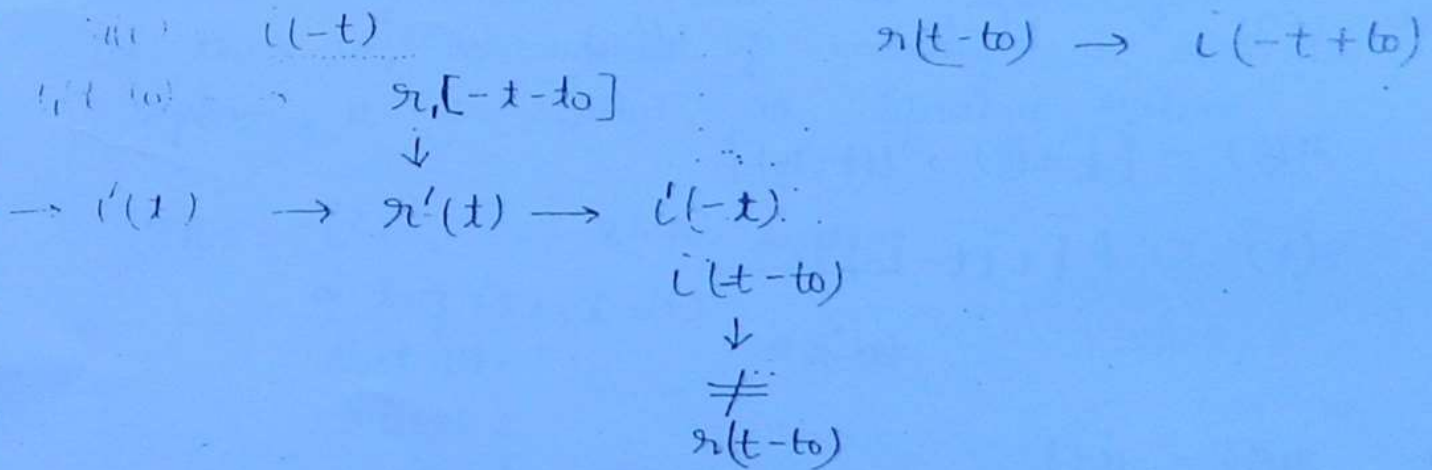
time invariant system



\* The system is defined as time invariant system if the response is delayed by the same amount as delay given to the system.

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\* If response to  $i(t-t_0)$  is not equal to  $r(t-t_0)$ , system is called as time variant system.



time variant system

$y(t) = 2i(t) + 3 \rightarrow$  time invariant

$y(t) = \log i(t) \rightarrow$  time invariant

$y(t) = i^2(t) \rightarrow$  T.I.

$y(t) = t i(t) \rightarrow$  T.V

$y(t) = \sin t \cdot i(t) \rightarrow$  T.V

$y(t) = \int_{-\infty}^t i(\tau) d\tau \rightarrow$  T.II

$y(t) = \int_{-5}^5 i(\tau) d\tau$

$y(t) = \int_{-\infty}^{\infty} i(\tau) d\tau$

⊛ Causal system & Non Causal system →

(34)

Cause → Causal

Causal	Non Causal
(i) response depends upon present & past i/p	Response also depends on future along with present & past i/p
(ii) Physically realizable	Physically not realizable
(iii) Nonanticipatory	Anticipatory

\* Non causal system also become physically realizable when the data <sup>which</sup> is being operated upon or the <sup>input</sup> data is recorded data. But by default we consider data to be real time data and hence only causal systems are physically realizable systems.

$$i=0 \quad \begin{matrix} i(t) \\ i(0) \end{matrix} \quad \begin{matrix} i(t-t_0) \\ i(-t_0) \end{matrix} \quad \begin{matrix} i(t+t_0) \\ i(t_0) \end{matrix}$$

$$r(t) = f[i(t), i(t-t_0)]$$

$$r(t) = f[i(t-t_0)]$$

$$t_0 \geq 0$$

\*  $r(t) = i(-t)$

non causal

$$r(1) = i(-1)$$

$$r(-1) = i(1) \rightarrow \text{depend future i/p}$$

$$r(t) = i(t) + i(t-2) + i(t-4) \rightarrow \text{Causal system}$$

$$r(t) = i(2t) \rightarrow \text{non causal system}$$

$$r(t/2) = i(1)$$

$r(t) = u(1/2 t)$  - non causal

$r(-1) = \delta(-1/2) \rightarrow$  future i/p

\*  $r(t) = i(at) \rightarrow$  always non causal

$r(t) = i^2(t) \rightarrow$  causal system

$r(t) = i(t^2) \rightarrow$  non causal

$r(t) = i(\sin t) \rightarrow$  non causal

$r(\pi/2) = i(1)$

$r(-\pi/2) = i(-1) \rightarrow$  future i/p

$r(\pi) = i(\sin \pi) = i(0)$

$r(-\pi) = i(0)$

\* Systems can be static or dynamic

If there is no arrangement for memory in an electrical system, it is called as static system

If there is arrangement of memory in electrical system, it is called as dynamic system

$r(t) = i^2(t)$  - static system

or  $\log i(t), t i(t)$

$\sin t i(t)$

$2 i(t) + 3$

$A i(t)$  { - Linear, static, time invariant }

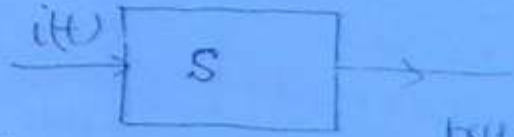
\* For a static system to be linear & time invariant

Only way the response can be related to i/p

is  $r(t) = A i(t)$

Stable or unstable system:  $\rightarrow$

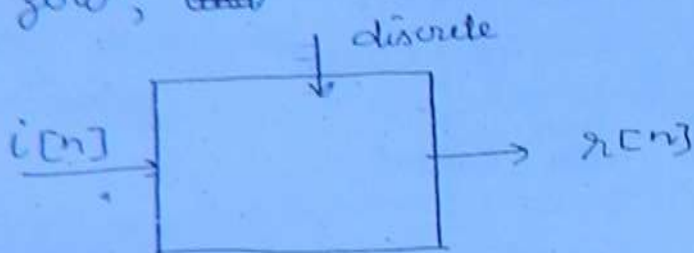
BIBO stability



$|i(t)| < M$

$|r(t)| < N$

- \* A system can become noninvertible in following cases
- (i) if more than one i/p to system is generating the same response for the system.
  - (ii) if the response of the system to a nonzero i/p is zero;



(36)

Verify whether the following discrete time system is linear, time invariant, causal, static, stable, invertible.

$$y[n] = \sum_{k=-\infty}^n x[k] \rightarrow \text{accumulator}$$

linear, time invariant,  
causal, dynamic,  
unstable, ~~invertible~~  
invertible

$$y'[n] = y[n] - y[n-1] = x[n]$$

$y[n] = \sum_{k=-\infty}^n x[k]$   
 $y[n-1] = \sum_{k=-\infty}^{n-1} x[k]$   
 $y[n] - y[n-1] = x[n]$

Q. Find weather system defined as

$$y[n] = x[n] - x[n-1] ; \text{ check}$$

for L, T, C, S, I.

this system  $\rightarrow$  linear, time invariant,  
causal, stable

Invertible system because we can select a system having input

$$y'[n] = \sum_{k=-\infty}^n y[k] = \sum_{k=-\infty}^n \{x[k] - x[k-1]\}$$

$$\{ \dots (x[n-2]) + (x[n-1]) + x[n] \} = x[n]$$

- Q. 9f P → defined: linearity  
 Q → defined: Time invariant  
 R → Causality  
 S → Stability

(37)

A discrete time system defined by i/p o/p relationship.

$$y[n] = x[n] \quad n > 0$$

$$0 \quad n = 0$$

$$x[n+1] \quad n < 0$$

where  $x[n]$  and  $y[n]$ , i/p and o/p of the system system is

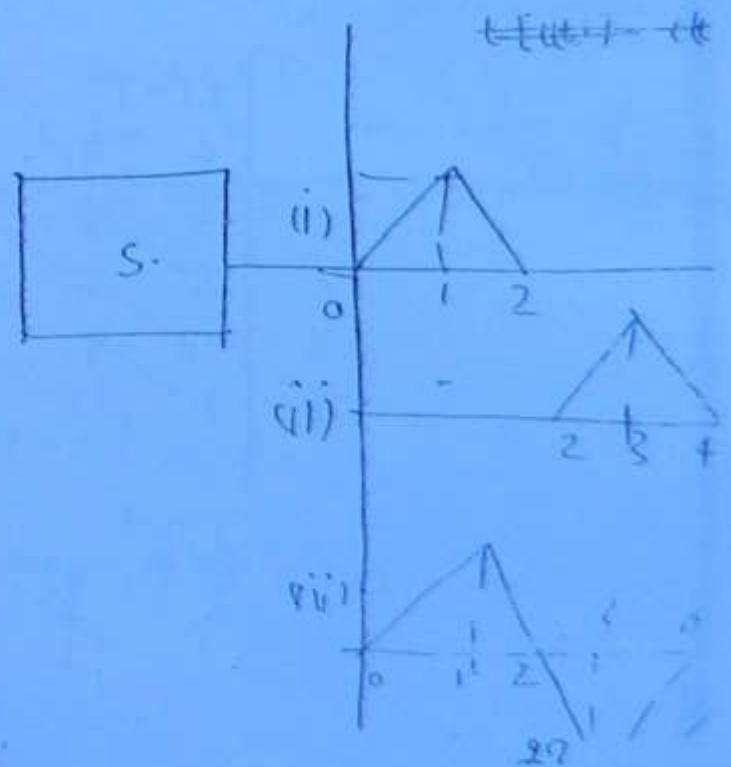
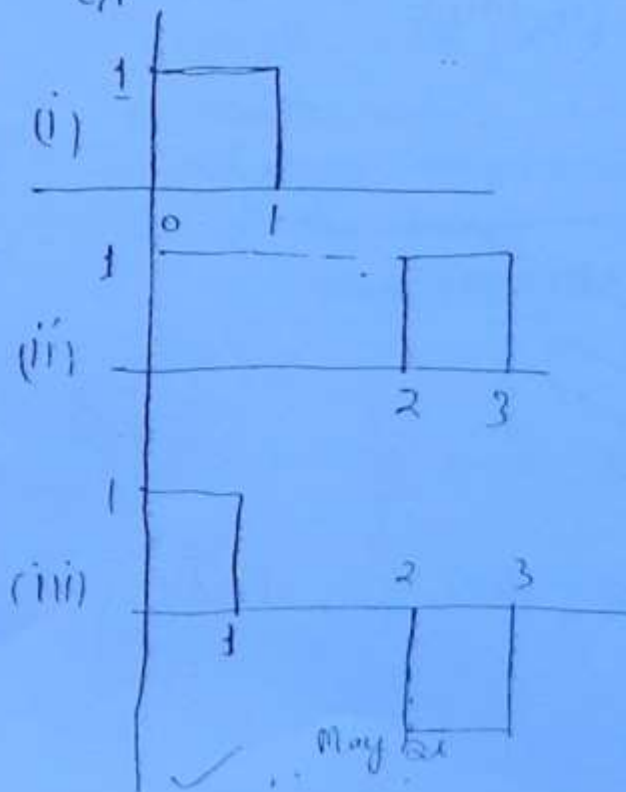
- (i) P, Q, R, S
- (ii) P, Q, S but NOT R
- ✓ (iii) P, S but NOT Q, R
- (iv) P but no Q, R, S.

$$y[n] = u[n-1] x[n] + u[n+1] x[n+1]$$

Linear, Not causal,

Stable, time variant

Q. 9 A system S has the following i/p for the considered



Length of resultant signal  $l$  always =  $L_1 + L_2 - 1$

Lower end of resultant signal =  $(n_1 + n_2)$  38

$n_1 \rightarrow$  Lower end of  $f[n]$   
 $n_2 \rightarrow$  Lower end of  $h[n]$

Then we convolve  $f[n]$  &  $h[n]$

$A_1$  summation of all sample of  $f[n] = \sum_{k=-\infty}^{\infty} f[k]$

$A_2$  " " " of  $h[n] = \sum_{k=-\infty}^{\infty} h[k]$

$A_1 \cdot A_2 = \sum_{k=-\infty}^{\infty} y[k]$

$y[n] = f[n] * h[n]$

=

$n_2 \rightarrow$  upper end of  $f[n]$   
 $n_3 \rightarrow$  " " " of  $h[n]$

upper end of  $y[n] = f[n] * h[n]$   
 $= (n_2 + n_3)$

	h[n]			
	4	3	2	1
1	4	3	2	1
2	8	6	4	2
3	12	9	6	3
4	16	12	8	4

$f[n] = \left\{ \begin{matrix} n=-1 & & & & & & n=5 \\ 4, & 11, & 20, & 30, & 20, & 11, & 4 \end{matrix} \right\}$

↑

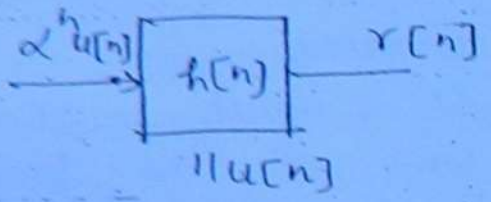




$$\sum_{k=-\infty}^{\infty} y[k] = \sum_{k=-\infty}^{\infty} h[k] \cdot \sum_{k=-\infty}^{\infty} x[k] \quad (48)$$

*impulse response*       $\rightarrow$   $y[k]$

$$\sum_{k=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} x[m] h[k-m] = \sum_{k=-\infty}^{\infty} h[k] \cdot \sum_{k=-\infty}^{\infty} x[k]$$



$$y[n] = \alpha^n [u[n]] \otimes u[n]$$

$$y[n] = \sum_{k=-\infty}^{\infty} \alpha^k u[k] u[n-k]$$

$$= \left[ \sum_{k=0}^{\infty} \alpha^k u[k] u[n-k] \right] \quad (u[n-k])$$

$$y[n] = \left[ \begin{aligned} &0 \cdot u[n] + \alpha u[n-1] + \alpha^2 u[n-2] \\ &+ \dots + \alpha^r u[n-r] + \dots \end{aligned} \right]$$

$$= \begin{cases} 0 & n < 0 \\ \left( \frac{\alpha^{n+1} - 1}{\alpha - 1} \right) & n \geq 0 \end{cases}$$

- $n=0 \quad 1$
- $n=1 \quad (1+\alpha)$
- $n=2 \quad 1+\alpha+\alpha^2$

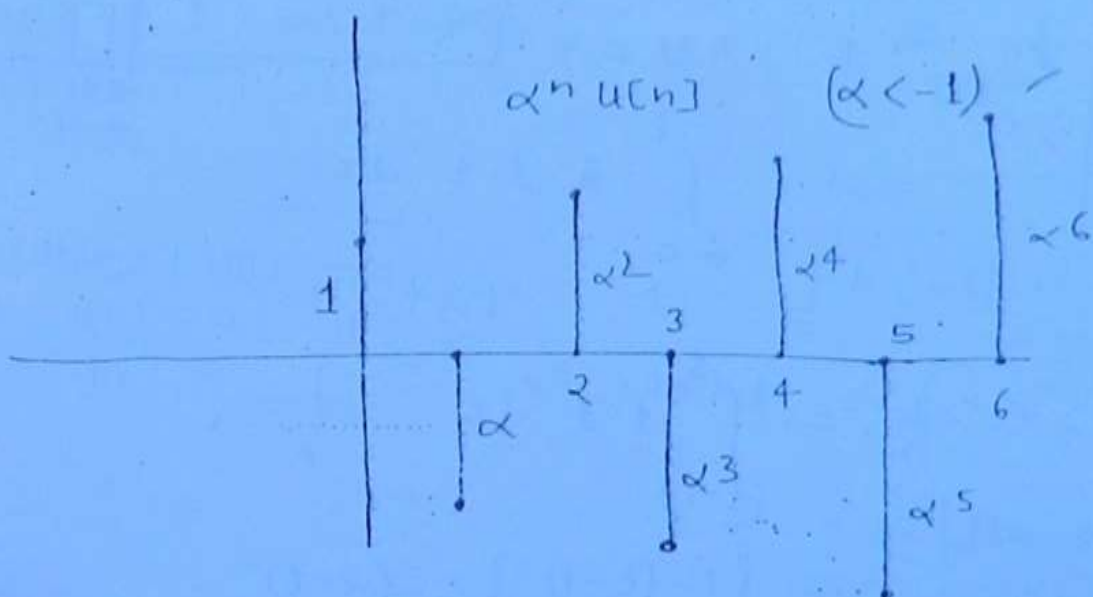
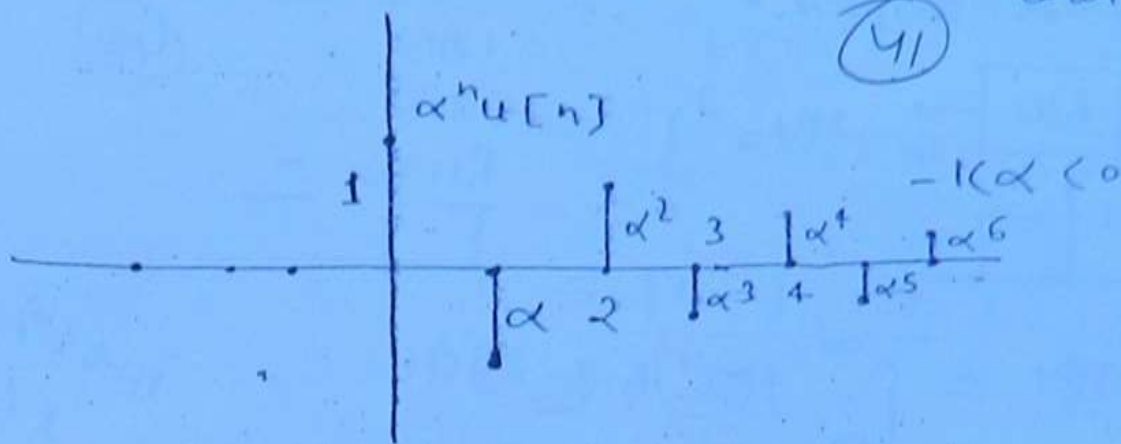
$$n=r \rightarrow 1 + \alpha + \alpha^2 + \dots + \alpha^r = \frac{1 - \alpha^{r+1}}{\alpha - 1}$$

$$y[n] = \left( \frac{\alpha^{n+1} - 1}{\alpha - 1} \right) u[n]$$

Sketch the graphs  $\alpha^n u[n]$  when  $0 < \alpha < 1$

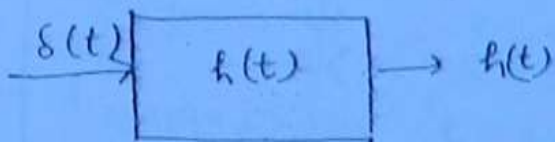
(41)

when  $-1 < \alpha < 0$   
 $\alpha < -1$



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$$f(t) = \int_{-\infty}^{\infty} f(\tau) \delta(t-\tau) d\tau$$



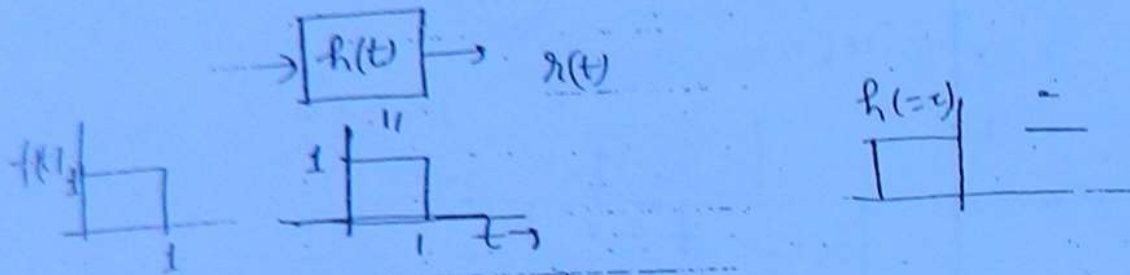
for any i/p  $f(t)$  response  $g(t)$

$$g(t) = \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau \rightarrow \text{convolution integral}$$

$\Downarrow$   
 $f(t) \otimes h(t)$

Q. Find the response of a continuous time LTI system with impulse response  $h(t)$

(42)



$$g(t) = \int_{-\infty}^{\infty} f(t) \cdot h(t-\tau) d\tau$$

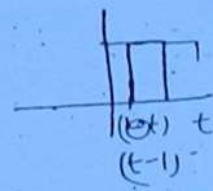
$h(-t+\tau)$   
 $h(-\tau)$

for  $t < 0$   $\Rightarrow g(t) = 0$

for  $t \geq 0$ .

$$= \int_0^t 1 \cdot 1 d\tau$$

$$= t \quad 1 \geq t \geq 0$$



for  $2 \geq t > 1$

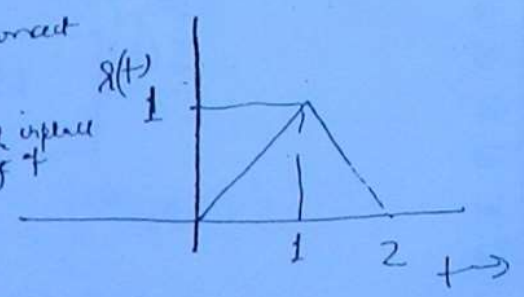
$$= \int_{t-1}^1 1 \cdot 1 d\tau$$

$$= [1 - (t-1)] = (2-t)$$

for  $t > 2$   
 $g(t) = 0$

$$g(t) = \begin{cases} t, & 1 \geq t \geq 0 \text{ or } 0 < t < 1 \\ (2-t), & 2 \geq t > 1 \\ 0, & t > 2 \\ 0, & t < 0 \end{cases}$$

both correct  
or  $t < 2$  replace  $t$  by  $t-1$



Repeat the above problem if the  $f(t) = u(t)$  and the  $h(t) = u(t)$

$$g(t) = 0 \quad t < 0$$

$$g(t) = t \quad t \geq 0$$

Ans ✓

Q. Repeat the problem if  $f(t) = u(t) \cdot e^{-t}$ ,  $h(t) = u(t)$

(43)

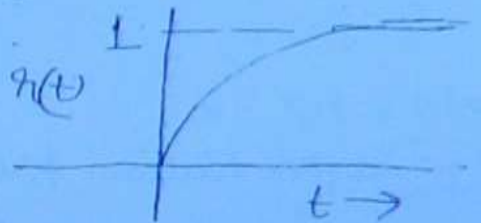
$$r(t) = 0 \quad t < 0$$

$$r(t) = \int_0^t e^{-\tau} \cdot 1 \, d\tau \quad t > 0$$

$$= -\left[ e^{-\tau} \right]_0^t$$

$$r(t) = (1 - e^{-t}) \quad t > 0$$

$$\boxed{r(t) \rightarrow 1 \text{ as } t \rightarrow \infty}$$



Q.  $e^{-t} u(t) \otimes t u(t) \rightarrow$

$$t < 0 \quad r(t) = 0$$

$$t > 0 \quad r(t) =$$

$$\int_0^t e^{-\tau} (-\tau + t) \, d\tau = -\int_0^t \tau e^{-\tau} \, d\tau + \int_0^t e^{-\tau} \, d\tau$$

$$= -\left[ (1 - e^{-t}) - t e^{-t} \right] + t[1 - e^{-t}]$$

$$r(t) = t e^{-t} + (t-1)(1 - e^{-t}) \quad t \geq 0$$

Q.  $e^{-t} u(t) \otimes e^{-t} u(t) \rightarrow$

$$t < 0 \quad r(t) = 0$$

$$t > 0$$

$$r(t) = \int_0^t e^{-\tau} e^{\tau-t} \, d\tau$$

$$r(t) = t e^{-t} \quad t \geq 0$$

$$\frac{e^{\tau} u(\tau)}{e^{-\tau}}$$

Q.  $e^{at} u(t) \otimes e^{-bt} u(t) \rightarrow$

$$t < 0 \quad r(t) = 0$$

for  $t > 0$

$$= \int_0^t e^{a\tau} e^{b(\tau-t)} \, d\tau = e^{-bt} \int_0^t e^{(a+b)\tau} \, d\tau$$

$t > 0 \quad r(t) =$

$$\frac{e^{at} - e^{-bt}}{a+b}$$

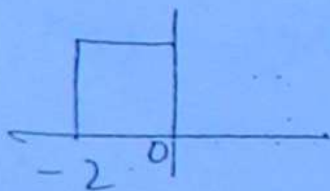
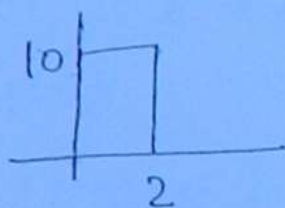
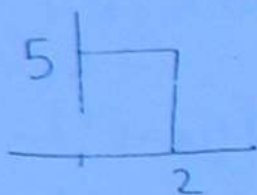
$$r(t) = \frac{e^{(a+b)t} - 1}{(a+b)} e^{-bt}$$

$$\textcircled{*} \quad r(t) = f(t) \otimes h(t) = \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau \quad (44)$$

$$\begin{aligned} \frac{d}{dt} r &= \frac{d}{dt} [f(t) \otimes h(t)] = \int_{-\infty}^{\infty} f(\tau) \frac{d}{dt} h(t-\tau) d\tau \\ &= \int_{-\infty}^{\infty} f(\tau) h'(t-\tau) d\tau \\ &= f(t) \otimes h'(t) \end{aligned}$$

differentiation property  $\left[ \frac{dr}{dt} = f(t) \otimes \frac{dh}{dt} \right]$

① Calculate the convolution of following two pulses



$$r(t) = 0 \quad t < 0$$

$$2 \geq t > 0$$

$$r(t) = \int_0^t 5 \cdot 10 dt = 50t$$

$$t = 2 \quad r(t) = 100$$

$$f \text{ and } t > 2$$

$$\int_{t-2}^2 5 \cdot 10 dt$$

$$t-2$$

$$= 50[4-t]$$

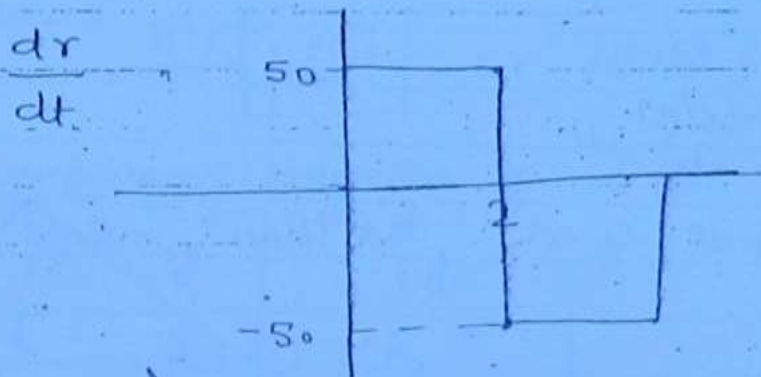
$$4 \geq t > 2$$

$$0 \quad t \geq 4$$

$$\frac{dh}{dt} = \begin{array}{c} \uparrow 10 \\ \text{---} \\ \downarrow -10 \end{array} \quad \therefore = 10[\delta(t) + \delta(t-2)]$$

(-45)

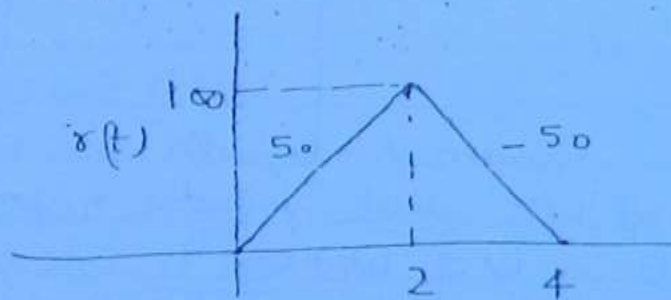
$$f(t) \otimes \frac{dh}{dt} = 10 f(t) - 10 f(t-2)$$



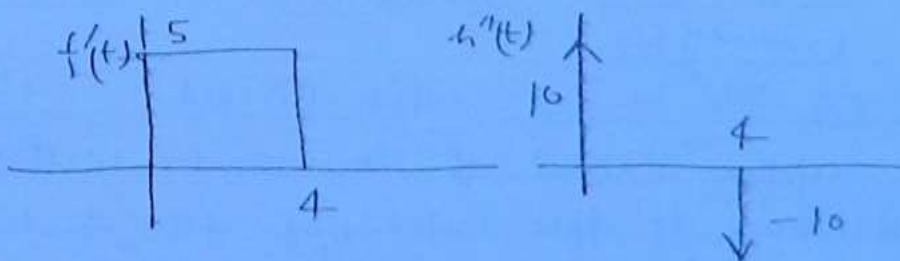
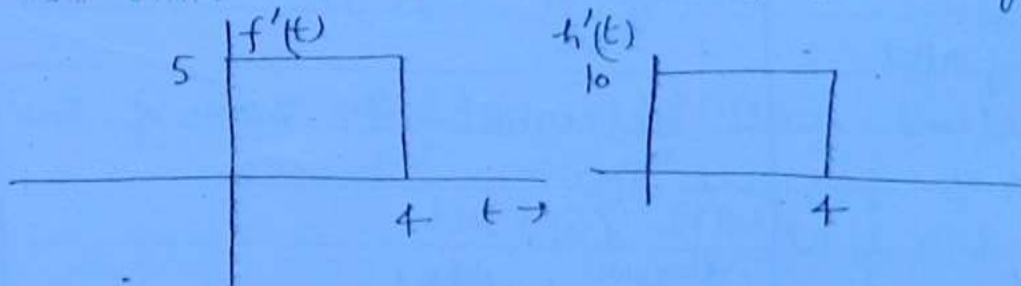
$$* 50t + (-100)$$

(-50t)

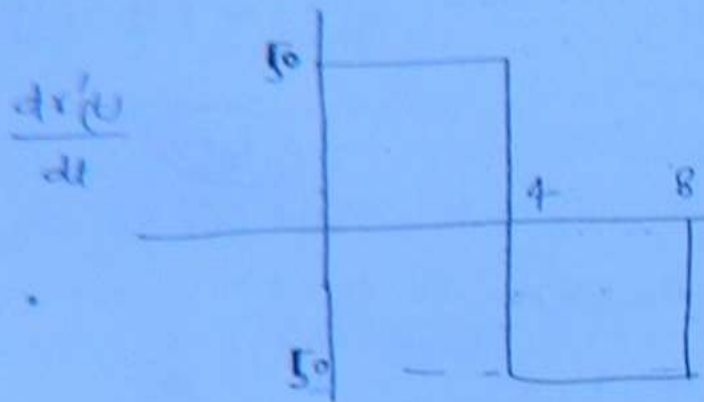
$$\int_{-\infty}^t \frac{dr}{dt} dt =$$



Q. Calculate the convolution of following signal

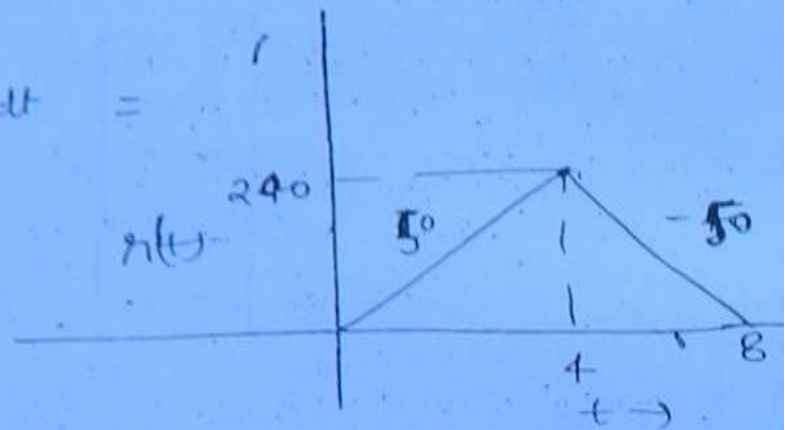


$$f''(t) \otimes h''(t) = 10 f''(t) - 10 f''(t-4)$$



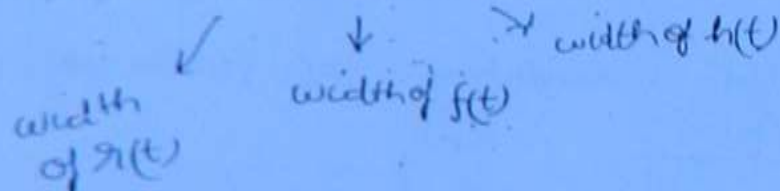
(46)

$$r'(t) = \int_{-\infty}^t \frac{dr'(t)}{dt} dt =$$

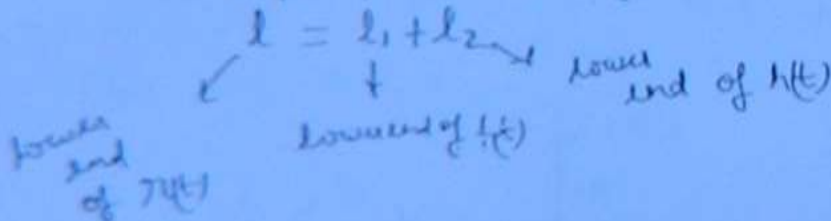


\* width of resultant signal will be always some of widths of i/p and impulse response  $h(t)$

$$w = w_1 + w_2$$



(\*) Lower extend will be equal to some of lower extends of  $f(t)$  and  $h(t)$



Similarly upper extend of resultant will be equal to some of upper extends of  $f(t)$  &  $h(t)$

$$u = u_1 + u_2$$

## Commutative Property :->

$$f(t) \otimes h(t) = h(t) \otimes f(t)$$

(47)

$$\boxed{f(t)} \quad \boxed{h(t)} \quad \rightarrow \quad f(t) \otimes h(t) = r(t)$$

||  
Same

$$\boxed{h(t)} \quad \boxed{f(t)} \quad \rightarrow \quad h(t) \otimes f(t) = r(t)$$

⊗ Interchanging positions of i/p and impulse response for an LTI system does not change response of the system

$$\boxed{\begin{aligned} \frac{dr}{dt} &= f(t) \otimes \frac{dh}{dt} \\ \frac{dr}{dt} &= h(t) \otimes \frac{df(t)}{dt} \end{aligned}}$$

$$\boxed{\begin{aligned} \frac{d^2r}{dt^2} &= h(t) \otimes \frac{d^2f(t)}{dt^2} \\ &= f(t) \otimes \frac{d^2h(t)}{dt^2} \\ &= \frac{df(t)}{dt} \otimes \frac{dh(t)}{dt} \\ &= \frac{dh(t)}{dt} \otimes \frac{df(t)}{dt} \end{aligned}}$$

$$\frac{d^m r}{dt^m} = h(t) \otimes \frac{d^m f(t)}{dt^m} = \frac{d^m h(t)}{dt^m} \otimes f(t)$$

$$= \frac{d^{m-1} f(t)}{dt^{m-1}} \otimes \frac{dh(t)}{dt}$$

$$= \frac{d^{m-2} h(t)}{dt^{m-2}} \otimes \frac{d^2 f}{dt^2}$$

$$\text{where } \boxed{(n+p) = m}$$

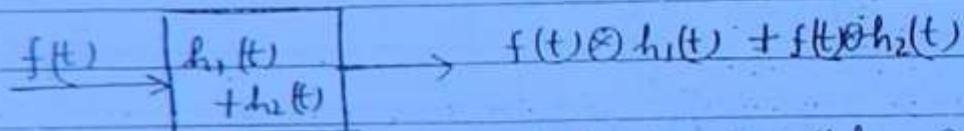
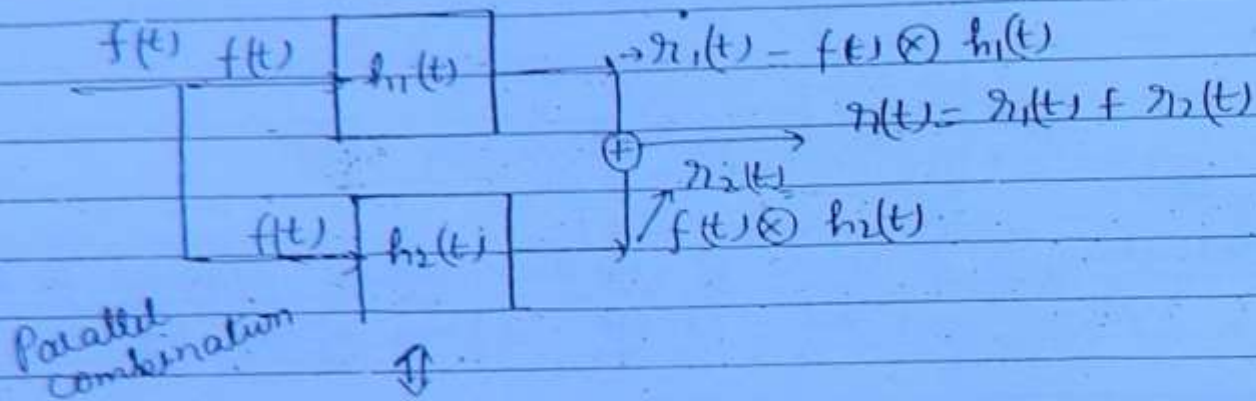
$$= \frac{d^{m-1} f(t)}{dt^{m-1}} \otimes \frac{dh}{dt}$$



$a \times [b + c] = a \times b + a \times c$   
 distributive property  $\rightarrow$

(48)

$$h(t) \otimes [f_1(t) + f_2(t)] = h(t) \otimes f_1(t) + h(t) \otimes f_2(t)$$

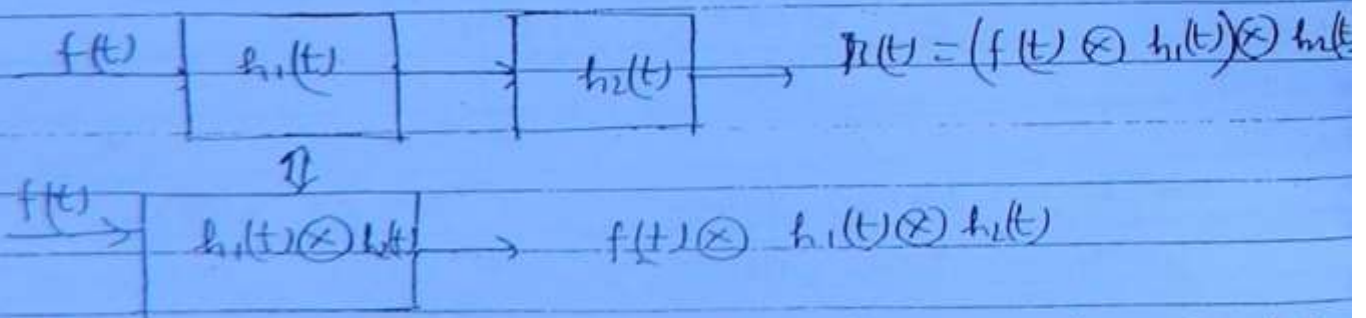


⊗ Any no. of systems connected in parallel can be combined into a single system whose impulse response is some of all the individual <sup>input</sup> responses.

Associative Property  $\rightarrow$

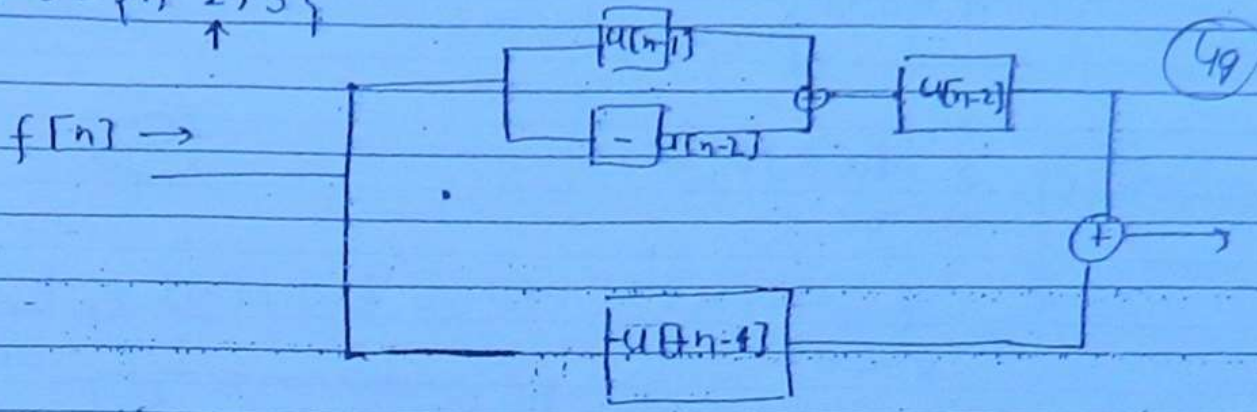
$$f(t), h_1(t), h_2(t)$$

$$f(t) \otimes h_1(t) \otimes h_2(t) = [f(t) \otimes h_1(t)] \otimes h_2(t)$$



⊗ Any no. of systems connected in cascade can be combined into a single system whose impulse response is convolution of all the individual impulse responses.

\* Q. what is the response of following system, to an i/p  
 $f[n] = \{1, 2, 3\}$



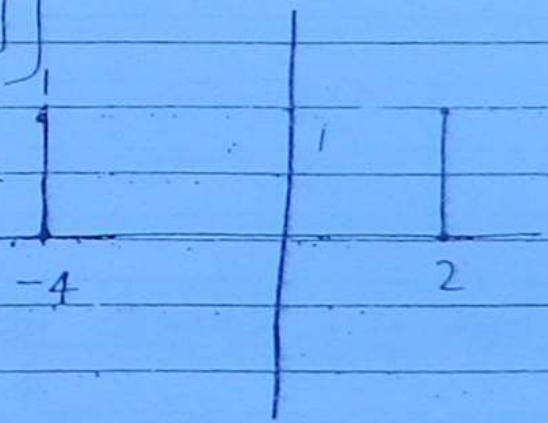
$$y[n] = f[n] \otimes \left[ -u[n-4] + \{ u[n-1] + u[n-2] \} \right]$$

$$= f[n] \otimes \left[ -u[n-4] + \delta[n-1] \otimes u[n-2] \right]$$

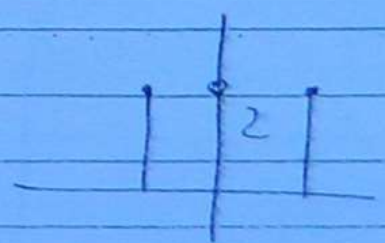
$$= f[n] \otimes \left[ -u[n-4] + u[n-3] \right]$$

$$= f[n] \otimes \left[ \delta[n-3] \right]$$

$$= f[n-3]$$



$\left\{ \begin{array}{l} y[n] \\ f[n] \otimes u[n-2] \end{array} \right\}$



$$f[n] \xrightarrow{h[n]} \sum_{k=-\infty}^{\infty} f[k] h[n-k] = \sum_{k=-\infty}^{\infty} h[k] f[n-k]$$

$$y[n] = \sum_{k=-\infty}^{\infty} h[k] f[n-k]$$

(50)

$$= \sum_{k=-\infty}^{-1} h[k] f[n-k] + h[0] f[n] + \sum_{k=1}^{\infty} h[k] f[n-k]$$

for system to be causal:  $h[n] = 0 \quad n < 0$

$$h(t) = 0 \quad t < 0$$

$$f(t) \xrightarrow{h(t)} \int_{-\infty}^{\infty} h(\tau) f(t-\tau) d\tau$$

$t-\tau = m$   
 $\tau = (t-m)$

causal system

$$= \int_0^{\infty} h(\tau) f(t-\tau) d\tau = \int_{-\infty}^t h(t-m) f(m) -dm$$

~~$\int_0^{\infty} f(\tau) h(t-\tau) d\tau$~~

$$y(t) = \int_{-\infty}^t h(t-\tau) f(\tau) d\tau$$

both are causal  $f(t)$  & system is causal  
 $\downarrow$   
 causal signal

$$y(t) = \int_0^t f(\tau) h(t-\tau) d\tau$$

$$y(t) = \int_0^t h(\tau) f(t-\tau) d\tau$$

$$f(t) \rightarrow 0$$

+ 1-2

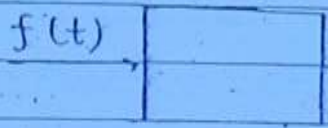
$$y(t) = \int_0^{(t+2)} f(\tau) h(t-\tau) d\tau$$

$$= (t+2) \dots$$

(5)

$$\left. \begin{aligned} (t+\tau) - t &= t - M \\ \tau - t &= -M \\ &= -2M \\ &= -t \end{aligned} \right\} \begin{aligned} & \\ & \\ & \\ & \end{aligned}$$

(\*)  $h(t)$  is not equal to a impulse function it is representing a dynamic system.



$|f(t)| \leq M$

$$y(t) = \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} f(t-\tau) h(\tau) d\tau$$

$$= \left| \int_{-\infty}^{\infty} f(t-\tau) h(\tau) d\tau \right| < \infty$$

$$\left| \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau \right| < \infty$$

$$\int_{-\infty}^{\infty} |h(\tau)| |f(t-\tau)| d\tau < \infty$$

$$\int_{-\infty}^{\infty} |h(\tau)| \cdot M d\tau < \infty$$

$$\boxed{\int_{-\infty}^{\infty} |h(\tau)| d\tau < \infty} \rightarrow \text{System to be stable}$$

$$\sum_{k=-\infty}^{\infty} |h(k)| < \infty$$

$$\boxed{\sum_{n=-\infty}^{\infty} |h(n)| < \infty}$$

$f(t) = \sin t \rightarrow$  unstable system oscillatory

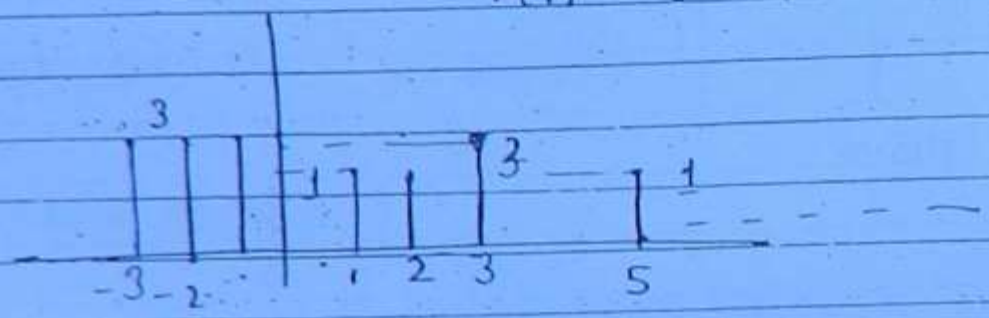
$h(t) = e^{-at} u(t) \rightarrow$  1/a area stable system.

$h[n] = u[n] \rightarrow$  unstable

$h[n] = (-1)^n u[n] \rightarrow$  unstable oscillatory

Q. A discrete time system is defined by the impulse response  $h[n] = 3u[n+3] - 2u[n-1] + 2u[n-3] - 2u[n-5]$

$h[0] = 3 \rightarrow$  not causal



Unstable, not causal

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Invertible or non invertible  $\rightarrow$

$f(t)$	$S$	$Y(t)$	$S'$	$H'(t)$	$\rightarrow [f(t) \otimes h(t)] \otimes h'(t)$
	$h(t)$	$\downarrow$			$= f(t)$

$$f(t) \otimes h(t) = f(t) \otimes [h(t) \otimes h'(t)] = f(t) \otimes \delta(t)$$

for condition invertibility  $= f(t)$

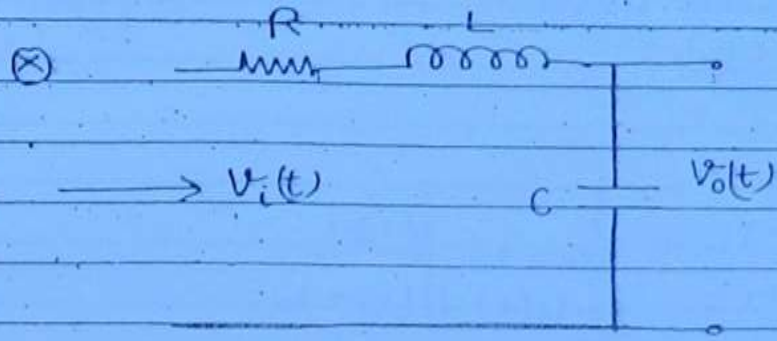
$$h(t) \otimes h'(t) = \delta(t)$$

Q. A discrete time system's impulse response is defined as  $h[n] = \alpha^n u[n] + \beta^n u[-n-1]$  the system is stable only if

$$0 < |\alpha| < 1$$

$$|\beta| > 1$$

(S3)



$$LC \frac{d^2 V_o}{dt^2} + RC \frac{dV_o}{dt} + V_o(t) = V_i(t)$$

⊗ A system is general can be represented by a differential eq<sup>n</sup> given below

$$a_2 \frac{d^2 y}{dt^2} + a_1 \frac{dy}{dt} + a_0 y = b_1 \frac{dx}{dt} + b_0 x(t)$$

In above differential eq<sup>n</sup> there are no product terms of the i/p  $x(t)$  or o/p  $y(t)$  or their derivatives

(i.e. there are no terms like  $x^2(t)$ ,  $x^3(t)$ ,  $\left(\frac{dx}{dt}\right)^2$ ,  $\left(\frac{d^2x}{dt^2}\right)^2$ ,  $[y(t)]^2$ ,  $\left(\frac{dx}{dt} \frac{d^2x}{dt^2}\right)$ )

$$\left(\frac{dx}{dt}\right)^2, \left(\frac{d^2x}{dt^2}\right)^2, [y(t)]^2, \left(\frac{dx}{dt} \frac{d^2x}{dt^2}\right)$$

such a differential equation is called a linear differential and it directly corresponds to a linear system. In the

⊗ In the above differential eq<sup>n</sup> if all the coefficients  $a_2, a_1, a_0, b_1, b_0$  are ~~const~~ independent of time (i.e. constants) then the above differential eq<sup>n</sup> can be called as a constant coefficient differential eq<sup>n</sup> and it directly corresponds to time invariant system

Q. A system represented by following differential eq<sup>n</sup>

$$2 \frac{d^2 y}{dt^2} + 4 \frac{dy}{dt} + 9 y(t) = 2 x(t)$$

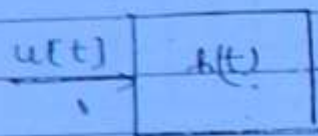
linear but time variant

$$2 \frac{d^2 y}{dt^2} + 4 \frac{dy}{dt} + 2 y^2(t) = 2 x(t)$$

Non linear, but time invariant

$$2 \frac{d^2 y}{dt^2} + \sin t \cdot \frac{dy}{dt} + y(t) = 2 x(t)$$

linear, time variant



$$x(t) = \int_{-\infty}^{\infty} u(\tau) h(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} h(\tau) u(t-\tau) d\tau$$

$$x(t) = \int_{-\infty}^t h(\tau) d\tau$$

$$u(t) = \int_{-\infty}^t \delta(\tau) d\tau$$

∴ system is linear

∴ response to  $u(t) = \int_{-\infty}^t h(\tau) d\tau$

$$h(t) = \frac{d x(t)}{dt} = \frac{d S(t)}{dt}$$

$S(t)$  is step response

Q. The following four signal define step responses & impulse responses of continuous time LTI systems

(i)  $(5 - 1e^{-2t}) u(t)$

(ii)  $(7 - 3e^{-4t}) u(t)$

(iii)  $5\delta(t) + 8e^{2t} u(t)$

(iv)  $2\delta(t) + 6e^{-2t} u(t)$

of this which two signals corresponds to step response & impulse of the same LTI system

Ans

(i) & (iii)

(i) step response

(iii) is impulse response  $h(t) = 5\delta(t) + 8e^{-2t}u(t)$

$$S(t) = \int_0^t h(\tau) d\tau = 5\tau + 8 \int_0^t e^{-2\tau} d\tau$$

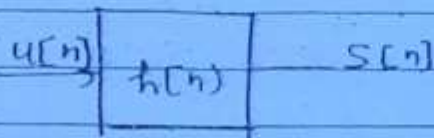
$$= 5\tau + 8 \left[ -\frac{1}{2} e^{-2\tau} \right]_0^t$$

$$= 5\tau + 4(1 - e^{-2t})$$

$$S(t) = (5 - 4e^{-2t}) u(t)$$

$$h(t) = \frac{dS(t)}{dt} = 5\delta(t) - 4S(t) + 8e^{-2t}u(t)$$

$$= \delta(t) + 8e^{-2t}u(t)$$



$$h[n] = S[n] - S[n-1]$$

↑  
Impulse response

↓  
 $S[n]$  step response

$$S[n] = \sum_{k=-\infty}^n h[k]$$

Q. For a discrete time system, the response to a step i/p is known to be  $\{1, 2, 1\}$  find  $h[n]$  response of the system for  $f[n] = \{1, 2, 1\}$

$$S[n] = \{1, 2, 1\}$$

$$h[n] = S[n] - S[n-1] = \{1, 1, -1, -1\}$$

↑ impulse response

$$f[n] = \{1, 2, 1, 3\}$$

$$y[n] =$$

	1	1	-1	-1	= { 1, 3 + 0 - 5 }	
1	1	1	-1	-1		↑
2	2	2	-2	-2		
3	3	3	-3	-3		



# Eigen Function :

(56)

$$\frac{f(t)}{AS(t)} \rightarrow Af(t)$$

\* If the response of a given LTI system is same as the I/P function  $f(t)$  except for a scalar multiple, the function is defined as eigen function of the system. So, for a system with unit impulse response  $AS(t)$ , any general signal  $f(t)$  forms an eigen function.

$$\frac{f(t)}{AS(t-t_0)} \rightarrow Af(t-t_0)$$

$$f(t) \otimes AS(t-t_0) = Af(t-t_0)$$

$$f(t-t_0) = f(t)$$

✓  $f(t)$  should be periodic with period  $t_0$ .

⊗ For a system with impulse response  $AS(t-t_0)$ , any signal which is periodic with a period  $t_0$  forms an eigen function.

$$\frac{\cos(\omega t)}{h(t)} \rightarrow h(t) \otimes \cos \omega t$$

$$= \int_{-\infty}^{\infty} h(\tau) \cos[\omega(t-\tau)] d\tau$$

$$= \int_{-\infty}^{\infty} h(\tau) \left( \cos \omega t \cos \omega \tau + \sin \omega t \sin \omega \tau \right) d\tau$$

$$y(t) = \cos \omega t \int_{-\infty}^{\infty} h(\tau) \cos \omega \tau d\tau + \sin \omega t \int_{-\infty}^{\infty} h(\tau) \sin \omega \tau d\tau$$

$$\int_{-\infty}^{\infty} h(\tau) \cos \omega_0 \tau d\tau = A$$

$$\int_{-\infty}^{\infty} h(\tau) \sin \omega_0 \tau d\tau = 0$$

↓  
should be even signal

(S7)  
Condition for  $\cos \omega_0 t$  to become eigen function of system.

Scaler (constant)

⊗ For a system with general impulse response  $h(t)$ , if  $\cos \omega_0 t$  is to be formed eigen function then impulse response  $h(t)$  must be an even function of time.

LTI

$$e^{j\omega_0 t} \xrightarrow{h(t)} e^{j\omega_0 t} \otimes h(t)$$

$$= \int_{-\infty}^{\infty} h(\tau) e^{j\omega_0 (\omega_0 t - \tau)} d\tau$$

always forms an eigen function for a system having impulse response  $h(t)$ .

$$= e^{j\omega_0 t} \int_{-\infty}^{\infty} h(\tau) e^{-j\omega_0 \tau} d\tau$$

$$= e^{j\omega_0 t} \left[ \int_{-\infty}^{\infty} h(\tau) \cos \omega_0 \tau d\tau - j \int_{-\infty}^{\infty} h(\tau) \sin \omega_0 \tau d\tau \right]$$

$h(\tau) \rightarrow$  should be even

$h(t) \rightarrow$  should be an even function of time so then  $e^{j\omega_0 t}$  can form eigen function for system  $h(t)$  having impulse response  $h(t)$  if  $h(t)$  is an even function of time or  $h(t)$  should be even conjugate function

$$e^{j\omega_0 t} \rightarrow H(j\omega_0) e^{j\omega_0 t}$$

$$C_1 e^{j\omega_1 t} \rightarrow C_1 H(j\omega_1) e^{j\omega_1 t}$$

$$C_2 e^{j\omega_2 t} \rightarrow C_2 H(j\omega_2) e^{j\omega_2 t}$$

$$f(t) = \sum C_n e^{jn\omega_0 t} \Rightarrow x(t) \rightarrow \sum_{n=-\infty}^{\infty} C_n e^{jn\omega_0 t} H(jn\omega_0) \quad (58)$$

Signal  $e^{j\omega_0 t}$  forms an eigen function for any general LTI system with impulse response, response of any LTI system when i/p is  $e^{j\omega_0 t}$  can be written as  $e^{j\omega_0 t} H(j\omega_0)$  where  $H(j\omega_0)$  is defined as

$$H(j\omega_0) = \int_{-\infty}^{\infty} h(\tau) e^{-j\omega_0 \tau} d\tau$$

If we can now express any signal  $f(t)$  as some of complex exponentials, response also will be some of no. of complex exponential signal multiplied by a suitable value

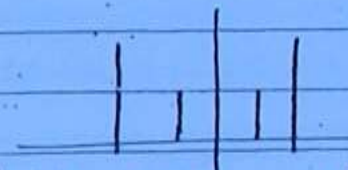
i.e.  $f(t) = \sum_{n=-\infty}^{\infty} C_n e^{jn\omega_0 t}$  will have a response

$$y(t) = \sum_{n=-\infty}^{\infty} C_n e^{jn\omega_0 t} H(jn\omega_0)$$

where  $H(jn\omega_0) = \int_{-\infty}^{\infty} h(\tau) e^{-jn\omega_0 \tau} d\tau$

Q. A discrete time system with an impulse response

$$h[n] = \begin{cases} 2 & n=2, -2 \\ 1 & n=1, -1 \\ 0 & \text{otherwise} \end{cases}$$



given an i/p  $f[n] = e^{jn\pi/2}$  find the response of the system.

$$y[n] = \sum_{k=-\infty}^{\infty} h[k] f[n-k] = \sum_{k=-\infty}^{\infty} h[k] e^{j(n-k)\pi/2}$$

$$= e^{jn\pi/2} \sum_{k=-\infty}^{\infty} h[k] e^{-jk\pi/2}$$

$$= e^{jn\pi/2} \left[ 2 \cdot e^{j\pi} + 1 \cdot e^{j\pi/2} + 1 \cdot e^{-j\pi/2} + 2 \cdot e^{-j\pi} \right]$$

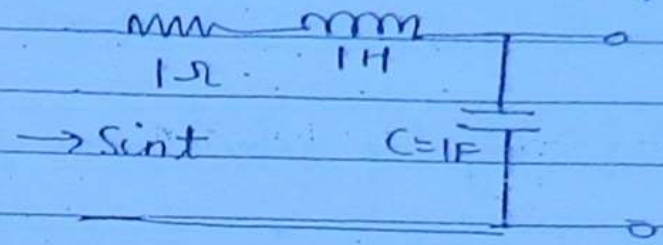
$$= e^{jn\pi/2} [-4]$$

$$y[n] = -4 e^{jn\pi/2}$$

$-4$  is eigen value and  $e^{jn\pi/2}$  is eigen function

$2\pi$   
 $\pi/2$   
 $2$

Q. Find the response of following ckt to an i/p  $\sin t$ .



(59)

$$I(t) = \frac{\sin t}{1} \quad \sin t = \frac{e^{jt} - e^{-jt}}{2j}$$

$$= \frac{-\sin t}{1+j+1}$$

$$I(t) = \sin t$$

$$\therefore V(t) = \frac{1}{j} \sin t = -\sin(t - \pi/2) = -\cos t$$

$$= -j \sin t \quad -\sin(t + 3\pi/2)$$

$$V(t) = \sin t \quad \left[ \frac{3\pi}{2} \right]$$

d/p c/p

$$L.C. \frac{d^2 V(t)}{dt^2} + RC \frac{dV(t)}{dt} + V(t) = V_e(t)$$

$$1 \cdot \frac{d^2 \sin t}{dt^2} + 1 \cdot \frac{d \sin t}{dt} + \sin t = V_e(t)$$

LTI system  $\rightarrow$   $-\sin t + \cos t + \sin t = V_e(t)$

$$V_e(t) = \cos t$$

$$V_e(t) = \sin(\pi/2 + t)$$

$$= \sin(t - \pi/2)$$

$$H(j\omega_0) = -j$$

$$H(j) = -j$$

$$H(j\omega_0) = \frac{1}{(j\omega_0)^2 + j\omega_0 + 1}$$

inner product

$$\bar{x} \cdot \bar{y} = 0$$

(60)

$[\bar{x}, \bar{y}] \rightarrow$  orthogonal

then we can express any vector in form of  $\bar{x}$  &  $\bar{y}$  vectors

Similarly  $f(t), g(t)$

$$\int_0^T f(t) g(t) dt = 0$$

in interval  $(0, T)$ ,  $f(t), g(t)$  are orthogonal

$$\int_0^{2\pi/\omega_0} \sin m\omega_0 t \cdot \sin n\omega_0 t dt$$

$m, n$  integer (+ve)  $\geq 0$  or -ve integer  $\leq 0$   
and  $m \neq n$

then above integral will be zero always.

then  $\sin m\omega_0 t$  is orthogonal  $\sin n\omega_0 t$  in interval  $(0, 2\pi/\omega_0)$

$$\int_0^{2\pi/\omega_0} \cos m\omega_0 t \cos n\omega_0 t dt$$

condition  $m \neq n$  and  $m \geq 0$  or  $m \leq 0$   
and  $n \geq 0$  or  $n \leq 0$   
 $m$  and  $n$  are integers

then  $\cos m\omega_0 t$  &  $\cos n\omega_0 t$  both will be orthogonal in interval  $(0, 2\pi/\omega_0)$

Same will be true for

$$\int_0^{2\pi/\omega_0} \sin K\omega_0 t \cos K\omega_0 t dt = 0$$

if  $K$  is any integer other than 0

So we can define any  $f(t)$  in terms of independent functions  $\cos \omega t$  &  $\sin \omega t$

$$f(t) = a_0 + a_1 \cos \omega t + a_2 \cos 2\omega t + \dots + b_1 \sin \omega t + b_2 \sin 2\omega t + \dots$$

$$f(t) = a_0 + \sum_{n=1}^{\infty} (a_n \cos n\omega t + b_n \sin n\omega t) \quad (6)$$

$f(t)$  is periodic with period  $= \frac{2\pi}{\omega_0}$

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$$f(t) = a_0 + \sum_{n=1}^{\infty} \sqrt{a_n^2 + b_n^2} \cos(n\omega t - \phi_n)$$

$$f(t) = \sum_{n=0}^{\infty} Y_n \cos(n\omega t - \phi_n)$$

⊕ Fourier series represents the information of the signal  $f(t)$  as amplitude and angles at different angular frequencies which are integer multiples of a fundamental angular frequency  $\omega_0$  i.e.  $n\omega_0$ .

where

$$a_0 = \frac{1}{T} \int_{-T/2}^{T/2} f(t) dt$$

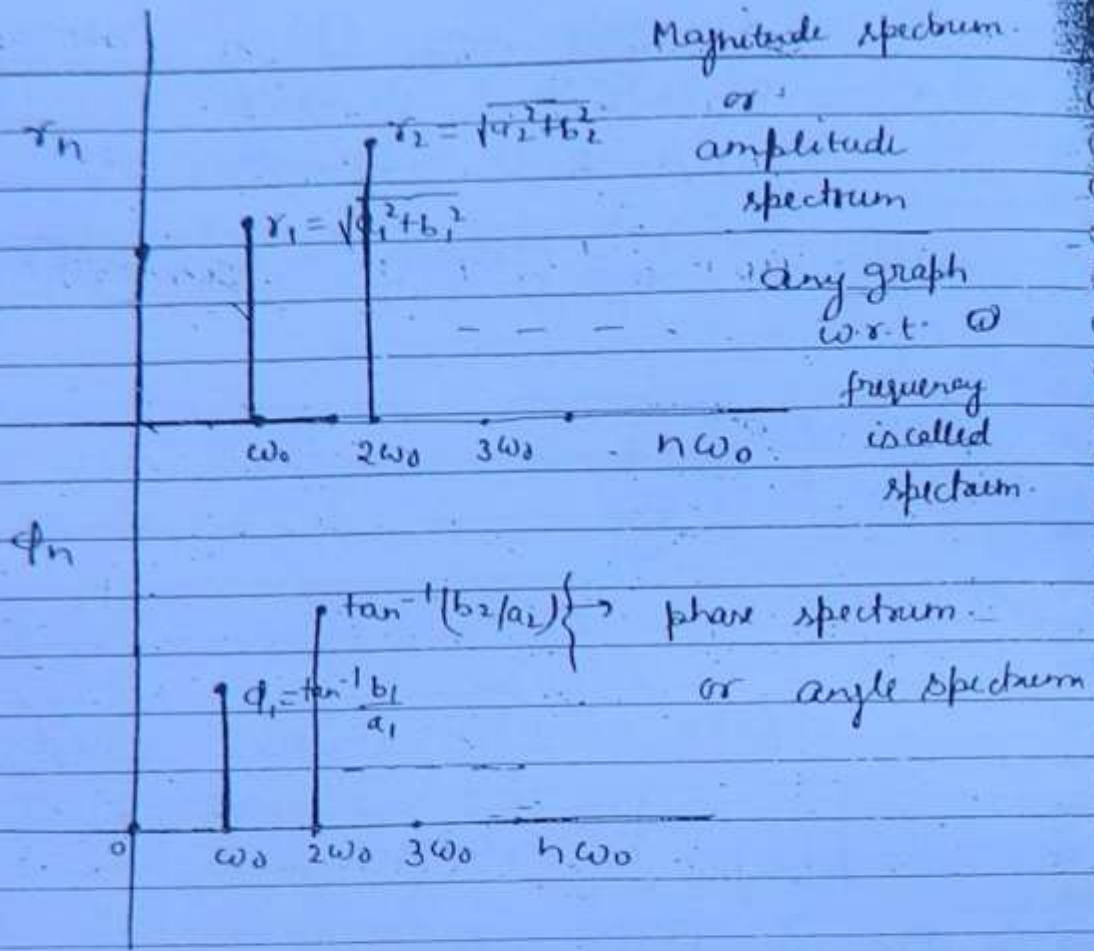
$$a_n = \frac{2}{T} \int_{-T/2}^{T/2} f(t) \cos n\omega t dt$$

$$b_n = \frac{2}{T} \int_{-T/2}^{T/2} f(t) \sin n\omega t dt$$

$$a[n\omega_0] = a_n = \frac{2}{T} \int_{-T/2}^{T/2} f(t) \cos n\omega_0 t dt$$

$$b[n\omega_0] = b_n = \frac{2}{T} \int_{-T/2}^{T/2} f(t) \sin n\omega_0 t dt$$

(62)



Gen  $\cos n\omega t$

$\sin n\omega t$

$n \rightarrow -\infty \rightarrow \infty$  integer  $\rightarrow$  all have time period  $(\frac{2\pi}{\omega_0})$

$$\int_0^T f(t) g^*(t) dt = 0$$

$\rightarrow$  for  $f(t)$  &  $g(t) \rightarrow$  two complex valued signal to be orthogonal in interval  $(0, T)$

$$\int_0^{2\pi/\omega_0} e^{jm\omega_0 t} (e^{jk\omega_0 t})^* dt = 0$$

$$f(t) = c_0 + c_1 e^{j\omega_0 t} + c_2 e^{j2\omega_0 t} + c_3 e^{j3\omega_0 t} + \dots$$

$$+ c_{-1} e^{-j\omega_0 t} + c_{-2} e^{-j2\omega_0 t} + \dots$$

$$f(t) = c_0 + \sum_{n=1}^{\infty} (c_n e^{jn\omega_0 t} + c_{-n} e^{-jn\omega_0 t})$$

$$f(t) = \sum_{h=-\infty}^{\infty} C_n e^{jn\omega_0 t} \rightarrow \text{Exponential fourier series}$$

(63)

Periodic with  $T = 2\pi/\omega_0 \rightarrow$  fundamental period of  $f(t)$ .

$$C_n = \frac{1}{T} \int_{-T/2}^{T/2} f(t) e^{-jn\omega_0 t} dt$$

$$= \frac{1}{T} \int_{-T/2}^{T/2} f(t) \cos n\omega_0 t dt - \frac{j}{T} \int_{-T/2}^{T/2} f(t) \sin n\omega_0 t dt$$

$$= \frac{1}{2} a_n - \frac{j}{2} b_n$$

$$C_n = \frac{1}{2} [a_n - j b_n] \rightarrow \text{complex in nature}$$

$\rightarrow$  valid for only  $n \neq 0$

$$C_{-n} = \frac{1}{2} [a_n + j b_n]$$

$$C_n^* = \frac{1}{2} [a_n + j b_n] = C_{-n}$$

$$C_n^* = C_{-n} \text{ providing } f(t) \text{ to be real}$$

$$C_n^* = \frac{1}{T} \int_{-T/2}^{T/2} f^*(t) (e^{-jn\omega_0 t})^* dt$$

$$= \frac{1}{T} \int_{-T/2}^{T/2} f(t) e^{+jn\omega_0 t} dt$$

$$C_n^* = C_{-n}$$

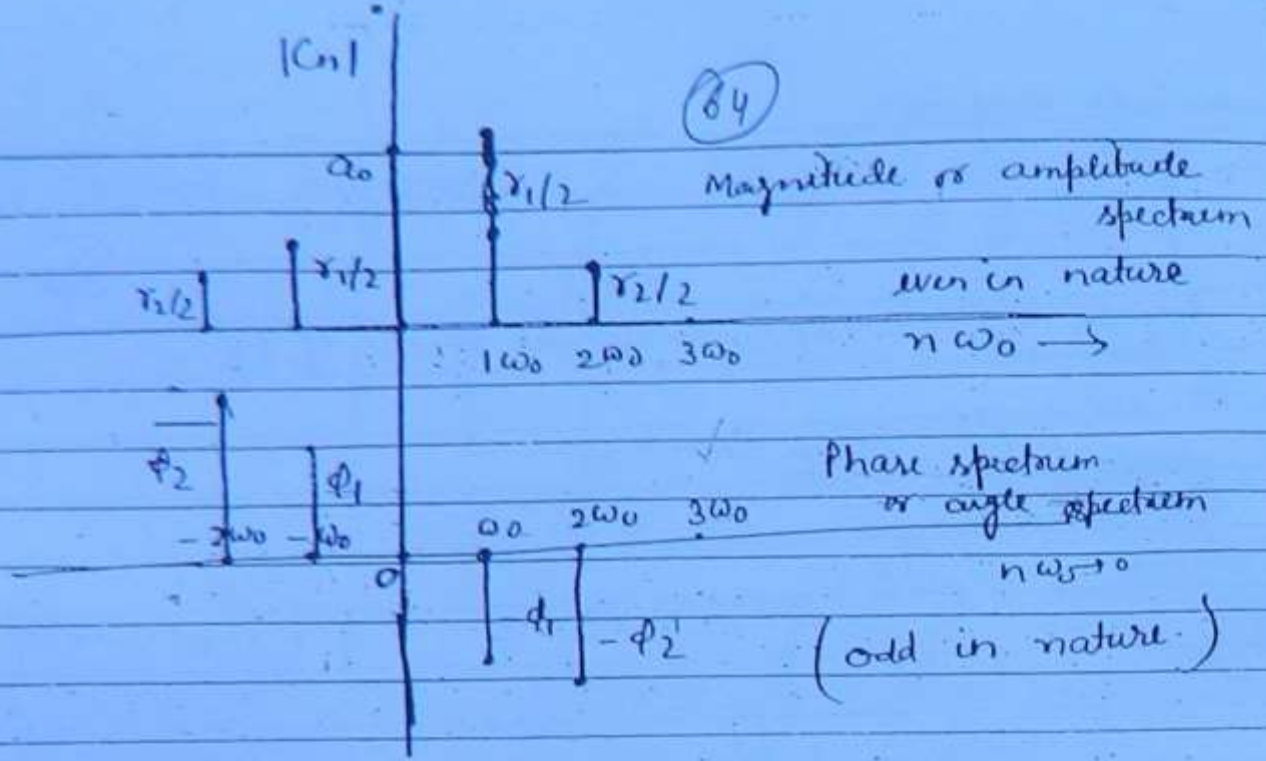
$$|C_n| = \frac{1}{2} \sqrt{a_n^2 + b_n^2}, \quad \angle C_n = -\tan^{-1}(b_n/a_n)$$

$$|C_n| = \frac{1}{2} \sqrt{a_n^2 + b_n^2} = |C_n^*| = |C_{-n}|$$

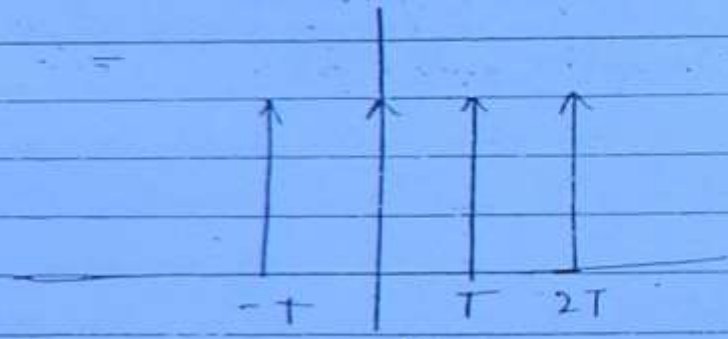
$$= e^{-j\phi_n}$$

$$= -\angle C_{-n}$$





Q Find the fourier series of signal  $f(t)$  shown below



$$f(t) = \sum_{k=-\infty}^{\infty} \delta(t - kT)$$

$$a_0 = \frac{1}{T} \int_{-T/2}^{T/2} f(t) dt = \frac{1}{T}$$

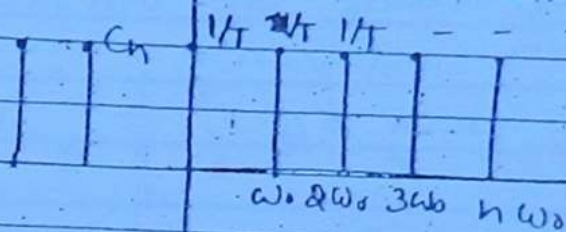
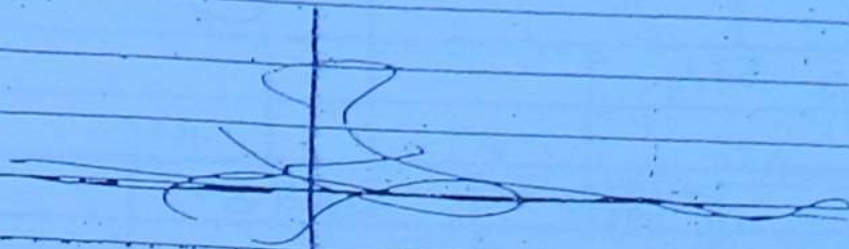
$$C_n = \frac{1}{T} \int_{-T/2}^{T/2} f(t) e^{-jn\omega_0 t} dt$$

$$= \frac{1}{T} \int_{-T/2}^{T/2} \delta(t) e^{-jn\frac{2\pi}{T} t} dt$$

$$= \frac{1}{T} \int_{-T/2}^{T/2} \delta(t) dt = 1/T$$

$$f(t) = \sum_{n=-\infty}^{\infty} \frac{1}{T} e^{jn\omega_0 t}$$

(65)



(E.F.S.) or C.F.S.  
Exponential Fourier spectrum  
or complex Fourier spect

$$C_n = \frac{a_n}{2} - j \frac{b_n}{2}$$

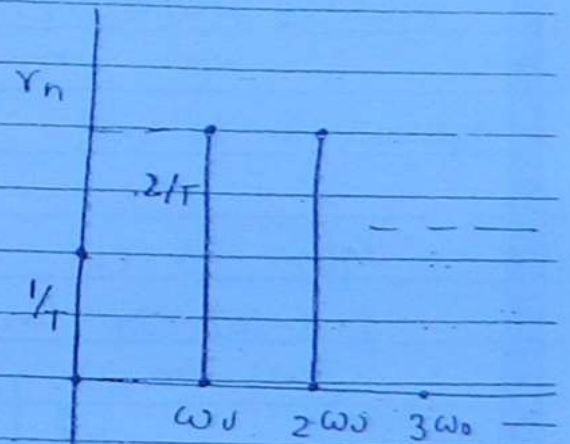
$$C_0 = 1/T = a_0$$

$$a_n = \frac{2}{T}, \quad b_n = 0, \quad \phi_n = 0$$

$$f(t) = \sum_{n=0}^{\infty} \gamma_n \cos(n\omega_0 t - \phi_n)$$

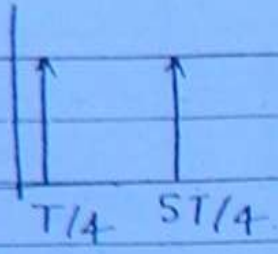
$$f(t) = \frac{1}{T} + \sum_{n=1}^{\infty} \frac{2}{T} \cos(n\omega_0 t)$$

$$= \frac{1}{T} \sum_{n=1}^{\infty} \frac{2}{T} \cos\left(n \cdot \frac{2\pi}{T} t\right)$$



Trigonometric  
Fourier spectrum  
or Real Fourier  
Spectrum

(T.F.S. or R.F.S)



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$$f(t) = \sum_{k=-\infty}^{\infty} \delta(t - T/4 + kT)$$

$$C_n = \frac{1}{T} \int_0^T f(t) e^{-jn\omega_0 t} dt = \frac{1}{T} \int_0^T \delta(t - T/4) e^{-jn\omega_0 t} dt = \frac{1}{T} e^{-jn\pi/2}$$

~~$$f(t) = \frac{1}{T} \sum_{n=-\infty}^{\infty} e^{jn\omega_0 t}$$~~

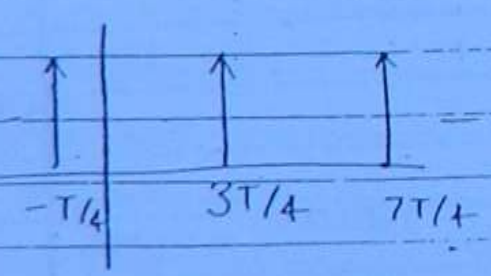
~~$$f(t) = \sum_{n=-\infty}^{\infty} \frac{1}{T} e^{-jn\pi/2} e^{jn\omega_0 t}$$~~

$$f(t) = \sum_{n=-\infty}^{\infty} \frac{1}{T} (-1)^{n/2} e^{jn\omega_0 t}$$

$$(-1)^{n/2}$$

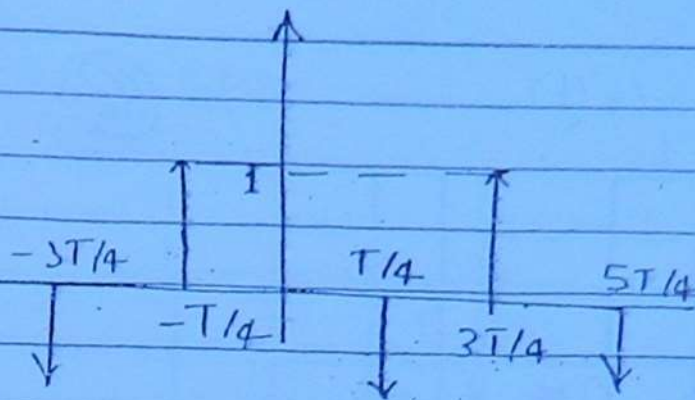
$$f(t) \rightarrow C_n$$

$$f(t-t_0) \rightarrow C_n e^{-jn\omega_0 t_0}$$



$$f(t + T/4) \rightarrow \frac{1}{T} e^{-jn\omega_0 (-T/4)} \text{ or } e^{-jn\omega_0 3T/4}$$

$$\rightarrow \frac{1}{T} e^{jn\omega_0 T/4}$$



(67)

fourier coefficient for given train of pulse  $\rightarrow$

$$C_n = \frac{1}{T} e^{jn\omega_0 T/4} - \frac{1}{T} e^{-jn\omega_0 T/4} = \frac{1}{T} 2j \sin n\omega_0 T/4$$

$$f_1(t) \rightarrow C_{1n}$$

$$f_2(t) \rightarrow C_{2n}$$

$$\text{then } a f_1(t) + b f_2(t) \rightarrow a C_{1n} + b C_{2n}$$

$C_n$  is imaginary for odd signal and odd in nature.

Q. Find the fourier coefficients of  $\sin \omega_0 t$  &  $\cos \omega_0 t$

$$\sin \omega_0 t = \frac{e^{j\omega_0 t} - e^{-j\omega_0 t}}{2j}$$

$$C_n = \frac{1}{2j} \quad \text{for } n = 1$$

0, otherwise

$$C_{-1} = -1/2j$$

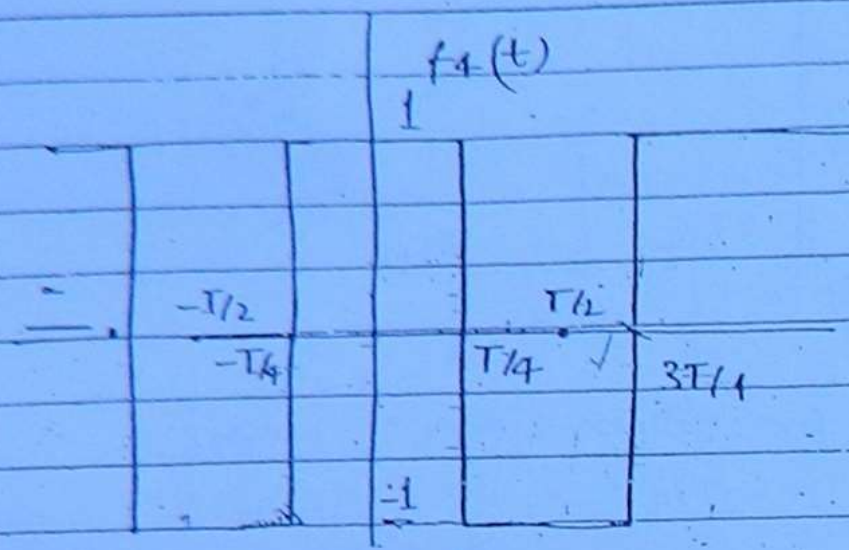
$$\cos \omega_0 t = \frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2}$$

$$C_1 = 1/2$$

$$C_{-1} = +1/2$$

for other n  
0, else  
etc

⊛ Calculate the fourier coefficient of the following signal.



$$C_n = \frac{1}{T} \int_{-T/4}^{3T/4} f(t) e^{-jn\omega_0 t} dt$$

$$= \frac{1}{T} \int_{-T/4}^{T/4} 1 e^{-jn\omega_0 t} dt + \frac{1}{T} \int_{T/4}^{3T/4} e^{-jn\omega_0 t} dt$$

$$= \frac{1}{T} \left[ \frac{e^{-jn\omega_0 t}}{-jn\omega_0} \right]_{-T/4}^{T/4} + \frac{1}{T} \left[ \frac{e^{-jn\omega_0 t}}{-jn\omega_0} \right]_{T/4}^{3T/4}$$

$$= \frac{1}{T} \left[ \frac{1}{jn\omega_0} \left[ e^{jn\omega_0 T/4} - e^{-jn\omega_0 T/4} \right] \right]$$

~~check~~

$$+ \frac{1}{Tjn\omega_0} \left[ e^{-jn\omega_0 3T/4} - e^{-jn\omega_0 T/4} \right]$$

$$= \frac{1}{Tjn\omega_0} \left[ 2e^{-jn\omega_0 3T/4} - 2e^{-jn\omega_0 T/4} \right]$$

$$= \frac{1}{Tjn\omega_0} \left[ 2 \left[ e^{jn\omega_0 T/4} - e^{-jn\omega_0 T/4} \right] \right]$$

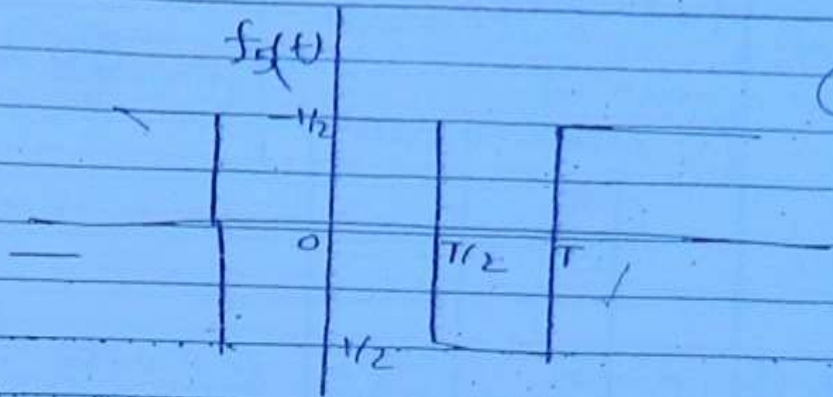
$$= \frac{1}{Tjn\omega_0} \cdot 2j \sin n\omega_0 T/4$$

$$C_n = \frac{4}{Tn\omega_0} \sin n\pi/2 = \frac{2}{n\pi} \sin \frac{n\pi}{2}$$

$$C_0 = 0$$

= 0 for n even

(69)



$f(t)$

$$C_n \rightarrow \frac{1}{n\pi} \frac{\sin n\pi}{2} e^{-jn\omega_0 T/4}$$

$$C_0 = 0 \quad C_n \rightarrow \left[ \frac{1}{n\pi} \frac{\sin n\pi}{2} e^{-jn\pi/2} \right] \rightarrow \frac{1}{2jn\pi}$$

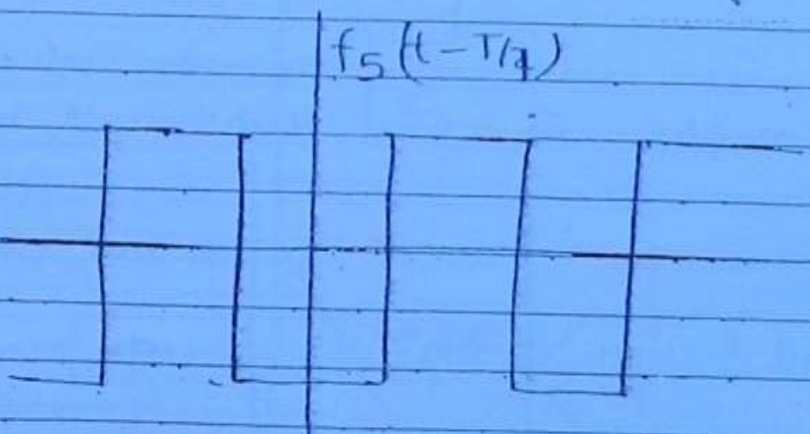
$$f(t) \rightarrow C_n$$

↳ Imaginary

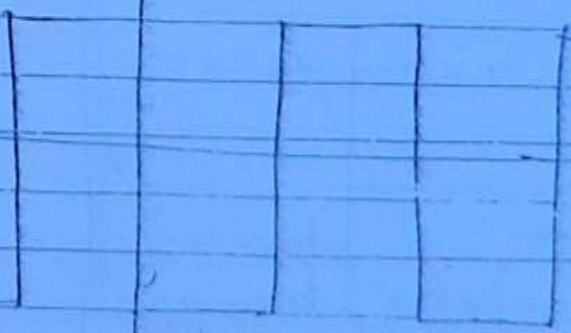
and odd for  $n$  even

$$\frac{d}{dt} f(t) \rightarrow +C_n \cdot jn\omega_0$$

$$C_n = 0$$

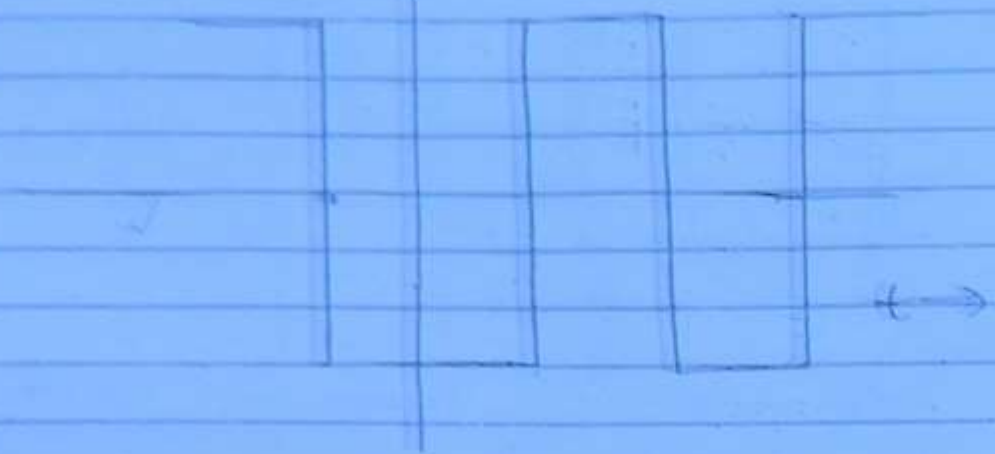


$$f_s(t - T/2) = -f_s(t)$$



$$f_1(t \pm T/2) = -f_1(t)$$

(70)



$$f(t \pm T/2) = -f(t) \quad C_n = 0 \text{ n-odd}$$

↳ hidden symmetry is called as half wave symmetry

### Symmetry table

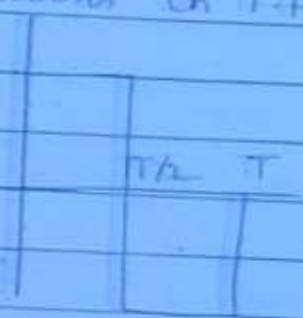
$f(t)$	$C_n$	Trigonometric Coefficient	freq. bands
real neither even nor odd	complex $C_n = C_{-n}^*$	$a_0 \neq 0, a_n, b_n \neq 0$	no dc term cosine terms sine terms
Even	real & even	$b_n = 0$	dc term & cosine terms (most frequent)
odd	Purely imaginary & odd	$a_n = 0, a_0 = 0$	<del>dc term</del> & sine terms
half wave symmetry	$C_n = 0 \quad n = \text{even}$	$a_n = 0 \text{ for } n = 2k$ $b_n = 0 \text{ for } n = 2k$	no dc term odd cosine & odd sine terms
even & half wave symmetry	real & even $C_n = 0 \quad n = \text{odd}$	$b_n = 0$ $a_n = 0$	no dc terms odd harmonics & only cosine terms

odd & half wave symmetry	$a_n = 0$ for even $n$ $a_n = 0$ always	$a_n = 0$ always $b_n = 0$ for even $n$	no dc term odd harmonics & only sine terms (i.e. odd sine term)
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②

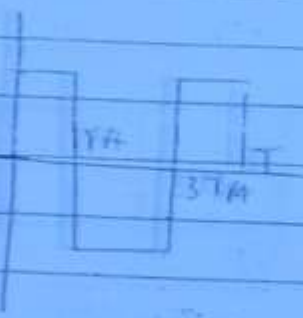
Q. After following signal which of signals will have only odd sine terms in T-F-S.  $\rightarrow$  defined in one time period.

(i)

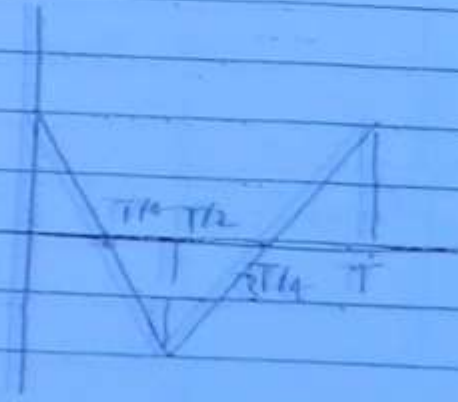


Ans (i) & (iv)

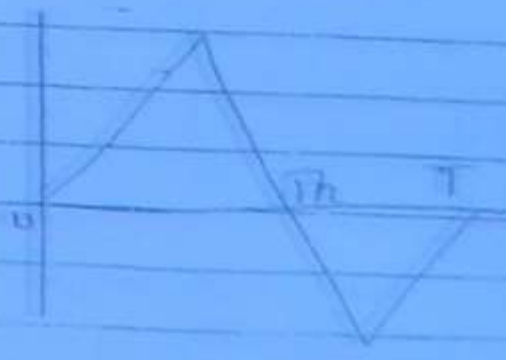
(ii)



(iii)

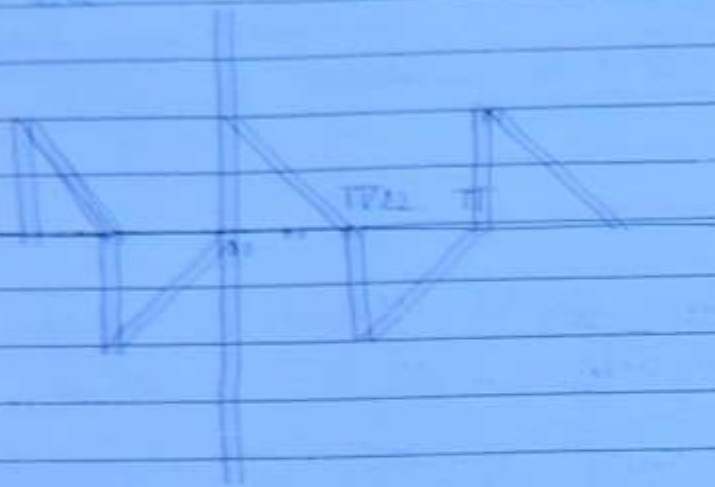


(iv)



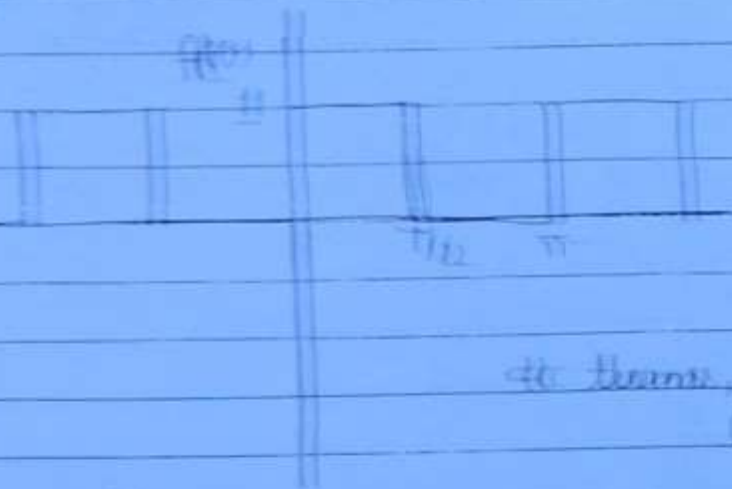


Q. A signal  $f(t)$  is defined as shown below  $\rightarrow$



only odd sine & cosine terms.

Q. A signal  $f(t)$  is defined as below



Further even nos odd & not half wave symmetry

odd terms, sine terms, (odd harmonics)

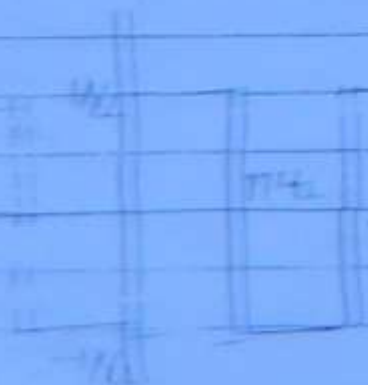
$$C_m = \frac{1}{\pi} \int_0^{\pi/2} 0 \cdot e^{-jm\omega t} dt + \frac{1}{\pi} \int_{\pi/2}^{\pi} 1 \cdot e^{-jm\omega t} dt = \frac{1}{\pi} \int_{\pi/2}^{\pi} e^{-jm\omega t} dt$$

$$= \frac{1}{\pi} \int_{\pi/2}^{\pi} e^{-jm\omega t} dt$$

period  $f(t) = 1/2$

$$C_m = \frac{1}{\pi} \int_{\pi/2}^{\pi} e^{-jm\omega t} dt$$

$$C_m = \frac{1}{\pi} \left( \frac{1 - e^{-jm\omega t}}{-jm\omega} \right) \Big|_{\pi/2}^{\pi}$$



odd & half wave symmetry

half for  $f(t)$

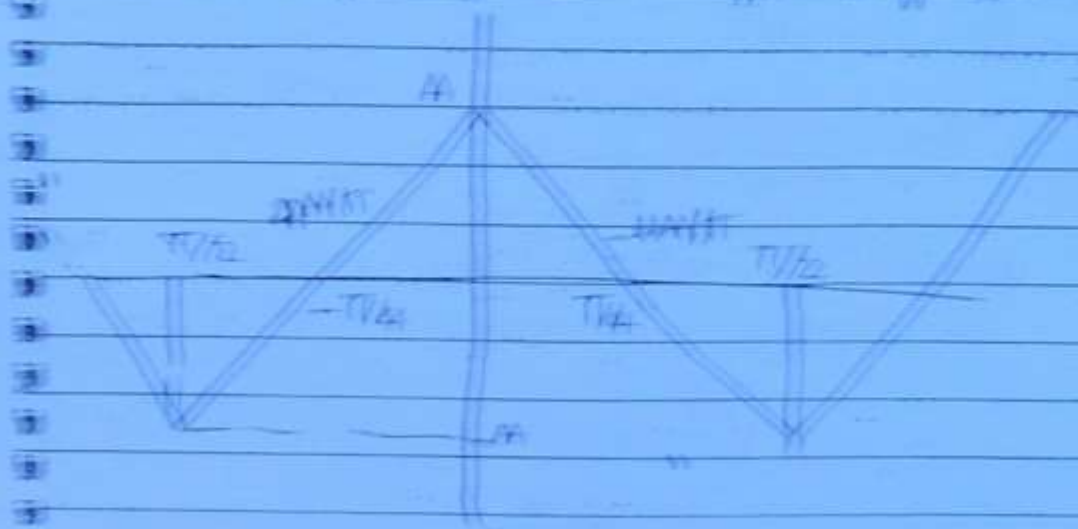
det term =  $\frac{1}{2}$

odd sine terms ( $\frac{1}{2} \sin \frac{1}{2} = 0$ )

Q. If we add some constant to the  $a_n f(t)$  then only the term will change and other Fourier coefficient will remain same -

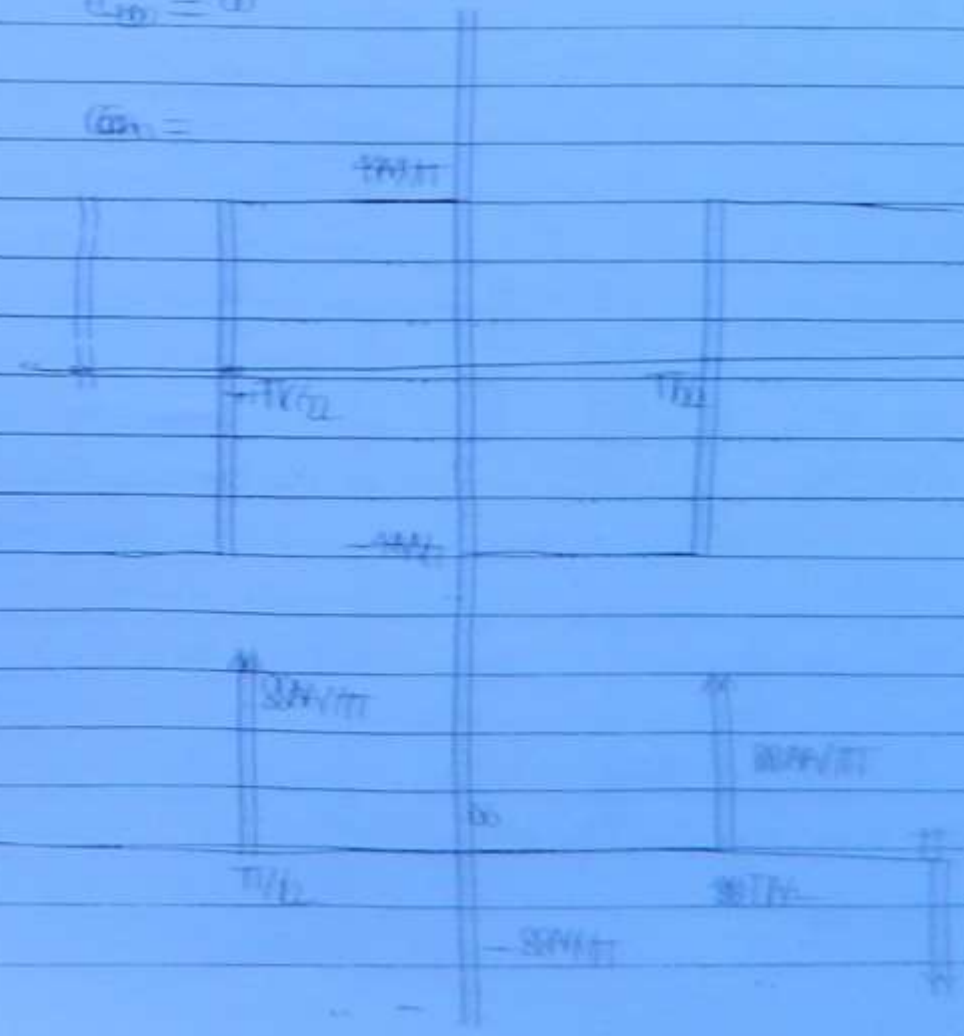
(2)

Q. Calculate the Fourier coefficients of following wave.



$C_{10} = 0$

$C_{0n} =$



444

for this impulse

$$C_n = \frac{8A}{T} \cdot \frac{1}{T} e^{-jn\omega_0 T/2} = \frac{8A}{T} \cdot \frac{1}{T}$$
$$= \frac{8A}{T^2} [e^{-jn\omega_0 T/2} - 1]$$
$$= \frac{8A}{T^2} [e^{-jn\pi} - 1]$$

$$C_n = \frac{8A}{T^2} [\cos n\pi - 1]$$

fourier coefficient of  $f(t)$

$$F_n = \frac{C_n}{(j\omega_0 n)^2}$$
$$= -\frac{8A}{T^2 \omega_0^2 n^2} [\cos n\pi - 1]$$
$$= \frac{8A}{T^2 \omega_0^2 n^2} [1 - \cos n\pi]$$

$$F_n = \frac{2A}{\pi^2 n^2} [1 - \cos n\pi] \quad \text{Ans}$$

$$F_0 = 0$$

↓  
real & even  
because signal  
is real & even

$$F_n = \frac{2A}{\pi^2 n^2} [1 - (-1)^n] \rightarrow$$

" 0 for n even

and only even terms  
because of half wave  
symmetry

$$F_n \propto \frac{1}{n^2} \rightarrow F_n \propto |n|^{-2}$$

Triangular pulse  
for rectangular pulse

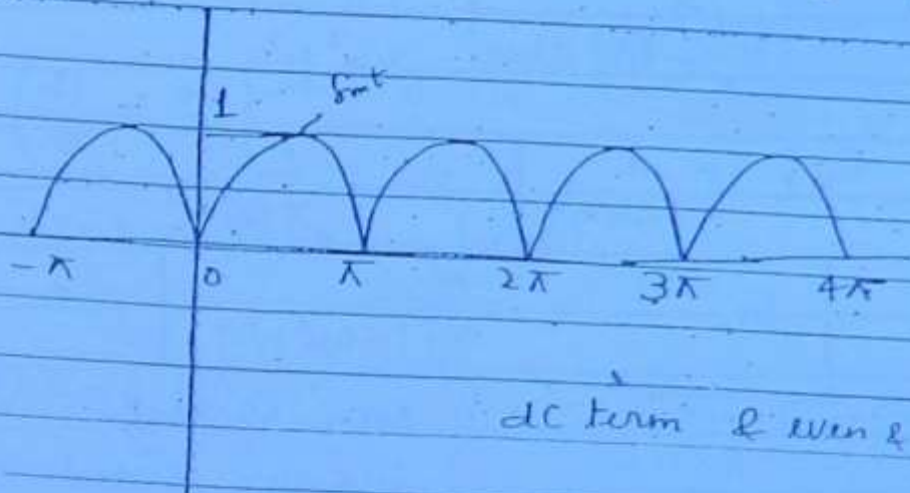
$$C_n \propto \frac{1}{n}$$

if function is varying as parabolic variation in  $t$  means as a function  $t^2$

then fourier series coefficient will be 75

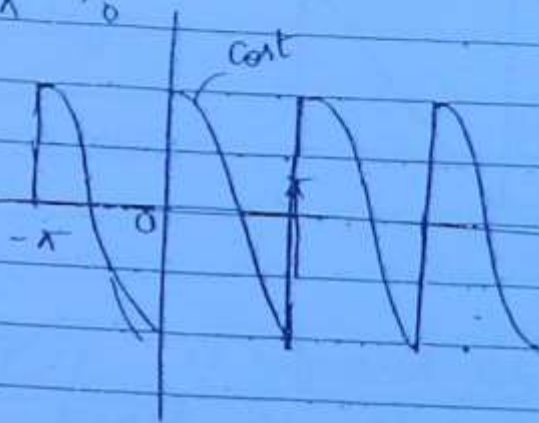
$$C_n \propto \frac{1}{n^3} \rightarrow C_n \propto |n|^{-3}$$

Q. Find the fourier coefficient of following signal

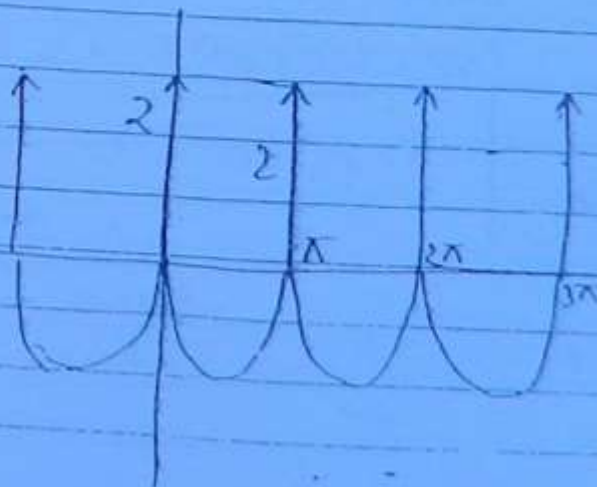


DC term & even & real

$$C_n = \frac{1}{\pi} \int_0^{\pi} \sin t e^{-jnw\pi t} dt \quad \text{we can find}$$



$C_n$



$$F_{-n} = -C_n \text{ for impulse}$$

$$-f_n$$

$$2f_n = 2$$

$$f_n$$

$$C_n \equiv \left( \frac{\text{impulse} - F_n}{T_{0n}} \right)$$

$$C_n = \left( \frac{2}{\pi} - F_n \right)$$

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$$F_n = \frac{C_n}{(j\omega_0 h)^2}$$

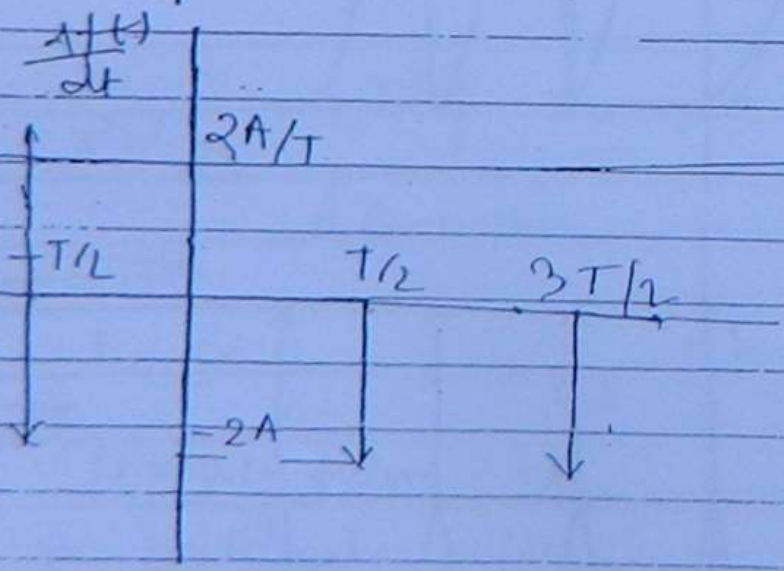
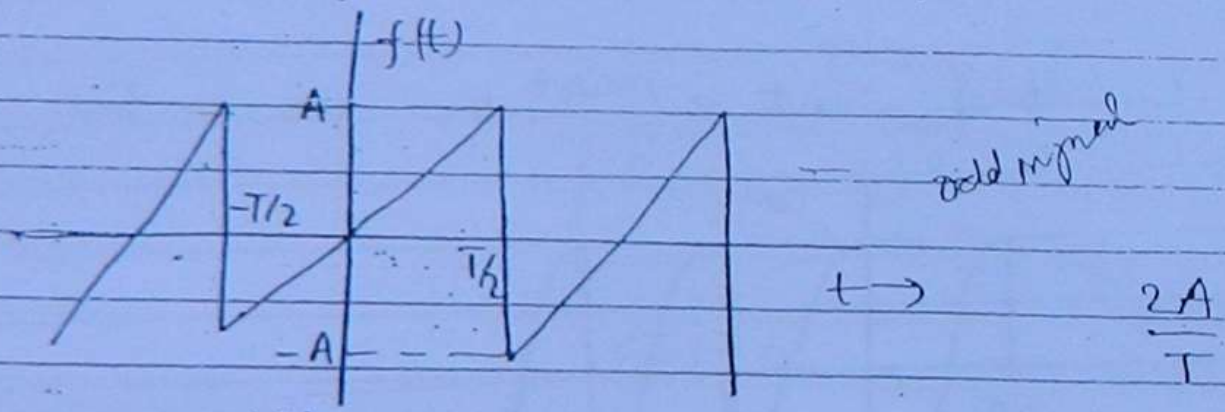
$$= -\frac{2}{\pi \omega_0^2 h^2} + \frac{F_n}{\omega_0^2 h^2}$$

$$F_n \left[ 1 - \frac{1}{\omega_0^2 h^2} \right] = -\frac{2}{\pi \omega_0^2 h^2}$$

$$F_n = \frac{2}{\pi(1 - \omega_0^2 h^2)} = \frac{2}{\pi(1 - 4h^2)}$$

even & real

because signal  $i f(t)$  is real & even



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$$\frac{2A}{T} e^{-jn\omega_0 t}$$

a for  $\frac{d(t)}{dt}$

$$G_n = \frac{2A}{T} \left[ -\frac{2A}{T} e^{-jn\omega_0 T/2} \right]$$

(77)

a

$$G_n = -\frac{2A \cdot 2A}{T} e^{-jn\omega_0 T/2}$$

$G_n'$  = of  $\left( \frac{d(t)}{dt} - \frac{2A}{T} \right) \rightarrow$  only effect of coefficient  $\omega$

$$-\frac{2A}{T} e^{jn\omega_0 t} = \frac{f[n]}{T} \otimes jn\omega_0 \quad \left\{ n \neq 0 \right\}$$

$$f_n \text{ (I)} = - \left( \frac{2A}{T} \frac{e^{-jn\pi}}{jn\omega_0} \right) \rightarrow \frac{2A}{jn2\pi} [e^{-jn\pi}]$$

$$f_0 \text{ (I)} = -\frac{2A}{T} + \frac{2A}{T} = 0 \quad = -\frac{A}{jn\pi} [(-1)^n]_{n \neq 0}$$

$$f[n] = (-1)^{n+1} \frac{A}{jn\pi} \quad n \neq 0$$

$$f_0 = 0$$

image and odd

Q. A signal  $f(t)$  is expressed as a sum of sinusoidal signal as shown below

$$f(t) = 2 + 3 \cos\left(\frac{5\pi}{6}t + \pi/3\right) + 4 \sin\left(6\pi t + \pi/4\right)$$

$$+ 8 \cos\left(\pi/7 t\right)$$

$$= 2 + 3 \left[ e^{j(5\pi/6)t + \pi/3} + e^{-j(5\pi/6)t - \pi/3} \right]$$

$$+ 4 \cdot 2 \left[ e^{j(6\pi t + \pi/4)} - e^{-j(6\pi t + \pi/4)} \right]$$

$$+ \frac{8}{2} \left[ \cos\left(\frac{\pi}{7}t\right) + \cos\left(\frac{\pi}{7}t\right) \right]$$

$\frac{5\pi}{6}, \frac{6\pi}{5}, \pi/3$

Overall

$$\omega_0 = \frac{\pi}{210}$$

$$T = \frac{2\pi}{\omega_0} = 420$$

$$f(t) = a_0 + \sum_{n=1}^{\infty} \delta_n \cos(n\omega_0 t - \phi)$$

$$f(t) = 2 + \frac{3}{2} e^{j\pi/8} e^{j\frac{\pi}{210} \times 5 \times 210 t} + \frac{3}{2} e^{-j\pi/8} e^{-j\frac{\pi}{210} \times 5 \times 210 t} \\ + \frac{2}{j} e^{j\pi/4} e^{j\frac{\pi}{210} \times 6/5 \times 210 t} - \frac{2}{j} e^{-j\pi/4} e^{-j\frac{\pi}{210} \times 6/5 \times 210 t} \\ + \frac{3}{2} e^{j\frac{\pi}{210} \times 2 \times 210 t} + \frac{3}{2} e^{-j\frac{\pi}{210} \times 2 \times 210 t}$$

dc terms, +175<sup>th</sup>, +252<sup>th</sup>, +30<sup>th</sup> harmonics.  
175<sup>th</sup>, 252<sup>th</sup>, 30<sup>th</sup> harmonics.

Q. The following signal  $f(t)$  defined as

$$f(t) = (\cos 2\pi t + \cos 7\pi t)^2$$

$$= \cos^2 2\pi t + \cos^2 7\pi t + 2 \cos 2\pi t \cos 7\pi t$$

$$= \frac{1}{2} [1 + \cos 4\pi t + 1 + \cos 14\pi t]$$

$$+ 2 [\cos 5\pi t + \cos 9\pi t]$$

$\omega \rightarrow 4\pi, 14\pi, 5\pi, 9\pi \rightarrow$  H.C.F of all  $\omega \rightarrow \pi$

dc terms are 1<sup>th</sup>, 14<sup>th</sup>, 5<sup>th</sup>, 9<sup>th</sup> harm

$$f(t) = a_0 + \sum_{n=1}^{\infty} (a_n \cos n\omega_0 t + b_n \sin n\omega_0 t)$$

$$P_t = a_0^2 + \sum_{n=1}^{\infty} \left( \frac{a_n^2}{2} + \frac{b_n^2}{2} \right)$$

$$= a_0^2 + \frac{1}{2} \sum_{n=1}^{\infty} (a_n^2 + b_n^2)$$

$$P_t = a_0^2 + \frac{1}{2} \sum_{n=1}^{\infty} r_n^2$$

$$f(t) = \sum_{n=-\infty}^{\infty} C_n e^{jn\omega_0 t}$$

$$= |C_n|^2$$

$$P = \sum_{n=-\infty}^{\infty} |C_n|^2$$

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$$|C_n|^2 = \frac{a_n^2 + b_n^2}{4} = |C_{-n}|^2$$

$$|C_n|^2 + |C_{-n}|^2 = 2 \frac{a_n^2 + b_n^2}{4}$$

$$P = C_0^2 + \sum_{n=1}^{\infty} \{ |C_n|^2 + |C_{-n}|^2 \}$$

$$= C_0^2 + 2 \sum_{n=1}^{\infty} |C_n|^2$$

$$= C_0^2 + \sum_{\substack{n=-\infty \\ n \neq 0}}^{\infty} |C_n|^2$$

$$P = \sum_{n=-\infty}^{\infty} |C_n|^2$$

Parseval's power relation for periodic power signal.

Q. A periodic saw tooth waveform as one considered in previous problem has a period  $T=2$ , find the no. of fourier coefficient to be considered such that considered fourier coefficients 90% of the total power.

$$\sum_{n=-\infty}^{\infty} |C_n|^2 = P_{total}$$

$$P_{total} = \sum_{\substack{n=-\infty \\ n \neq 0}}^{\infty} \left( \frac{A}{n\pi} \right)^2 = \frac{2A^2}{\pi^2} \sum_{n=1}^{\infty} \left( \frac{1}{n} \right)^2$$

$$P_{total} = \frac{2A^2}{\pi^2}$$

$$P_{total} = \frac{1}{2} \int_{-1}^1 (At)^2 dt$$

$$= \frac{1}{2} \times \frac{A^2}{2 \times 3} [2] = \frac{A^2}{3}$$



Power in n terms

80

$$\frac{2A^2}{\pi^2} \sum_{m=1}^n \left(\frac{1}{m}\right)^2 = 0.9 \times \frac{A^2}{3}$$

$$\sum_{m=1}^n \left(\frac{1}{m}\right)^2 = \frac{0.9}{6} \times \pi^2$$

$$\frac{1}{4} + \frac{1}{9} + \frac{1}{16} + \frac{1}{25} = \frac{3}{20} \pi^2$$

5 terms > 90%  
(OK)

1.25  
9.89 x 3  
1.47  
29.67  
20  
130  
36  
1.38 + 0.06 +

Q. A periodic signal  $f(t) = \sum_{n=0}^{\infty} C_n \cos n\pi e^{+jn\pi/\omega_0 t}$

is this signal is complex valued signal or real signal.

$$C_n = C_{-n}^*$$

$$= \sum_{n=0}^{\infty} C_n \cos n\pi e^{+jn\pi/\omega_0 t}$$

$$= \sum_{n=-\infty}^{\infty} C_n \cos n\pi e^{+jn\pi/\omega_0 t}$$

$$\left. \begin{aligned} C_n &= \sum_{h=-\infty}^{\infty} C_n \cos h\pi \\ C_{-n} &= \sum_{-h=-\infty}^{\infty} C_n \cos h\pi \\ C_{-n} &= \sum_{h=0}^{\infty} C_n \cos h\pi \\ C_n^* &= \sum_{h=0}^{\infty} C_n \cos h\pi \end{aligned} \right\}$$

$$\begin{aligned} C_n &= C_n \cos n\pi \\ \text{for } n &\leq 0 \\ &0 \text{ otherwise} \\ C_{-n} &= C_n \cos n\pi \\ &h \geq 0 \\ C_n & \end{aligned}$$

complex valued signal

A discrete time system defined by (81)

$y[n] - y[n-1] = x[n]$  → Recursive system + response is depending on previous response  
 find its impulse response  
 $h[n] - h[n-1] = \delta[n]$

$n=0 \quad h[0] = 1 + h[-1]$

for

$Y[z] - z^{-1} Y[z] = X[z]$

$H[z] = \frac{1}{1-z^{-1}} = \sum_{n=0}^{\infty} z^{-n} = h[n]$   
 IIR system

$y[n] = x[n] + x[n-1]$  non recursive form  
 $y[n] - y[n-1] = x[n] - x[n-2]$  recursive form  
 same system  
 FIR system

find the value of the integral

(82)

$$\int_{-\infty}^{\infty} [\cos 3t \cdot \delta(3t-3) + e^{-3t} \delta'(2t-2)] dt$$

$$= \frac{1}{3} [-1] + \int_{-\infty}^{\infty} e^{-3t} \delta'(t-1) dt$$

$$= 0 - \frac{1}{3} + \frac{1}{4} \left[ -\frac{d}{dt} e^{-3t} \right]_{t=1}$$

$$= -\frac{1}{3} + \frac{1}{4} + 3e^{-3}$$

$$= -\frac{1}{3} + \frac{3}{4} e^{-3} \text{ Ans}$$

$f[n] \rightarrow$

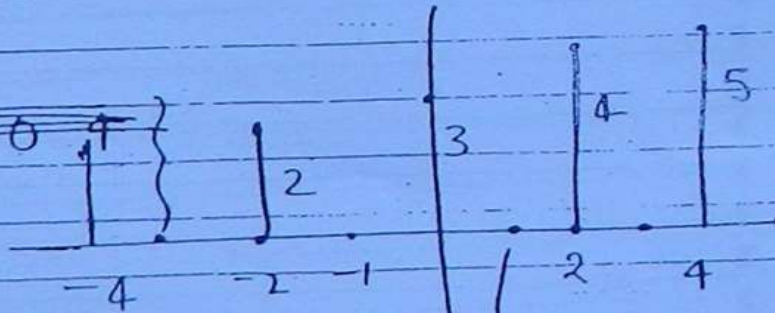
$\{1, 2, 3, 4, 5\}$

$f[2n] \rightarrow$   
↓  
downimation

$\{1, 3, 5\}$

$f[0/2^n]$

~~$\{2, 3, 4\}$~~



we can also ~~fill~~ fill.

these samples by 1 called unit interpolation.

fill with zero called zero interpolation

$$\delta'(-t) \rightarrow -1 \delta'(t) \rightarrow \text{odd function. } \textcircled{83}$$

\* all even derivative of  $\delta(t)$  are even functions of time and all odd derivative of  $\delta(t)$  are odd function of time.

$$\frac{d}{dt} [f(t) \cdot \delta(t-a)] = \frac{d}{dt} [f(a) \delta(t-a)]$$

$$f'(t) \delta(t-a) + f(t) \cdot \delta'(t-a) = f(a) \cdot \delta'(t-a)$$

$$\boxed{f(t) \delta'(t-a) = f(a) \delta'(t-a) - f'(t) \delta(t-a)}$$

$$t \delta'(t) = 0 \cdot -1 \delta(t-0) \\ = -\delta(t)$$

$$\int_{-\infty}^{\infty} f(t) \delta(t-a) dt = f(a)$$

$$\int_{-\infty}^{\infty} f(t) \delta'(t-a) dt = \int_{-\infty}^{\infty} f(a) \delta'(t-a) dt - \int_{-\infty}^{\infty} f'(t) \delta(t-a) dt$$

$$= \int_{-\infty}^{\infty} f(a) \delta'(t-a) dt - f'(a)$$

$$= f(a) \int_{-\infty}^{\infty} \delta'(t-a) dt - f'(a)$$

$$= f(a) [\delta(t-a)]_{-\infty}^{\infty} - f'(a)$$

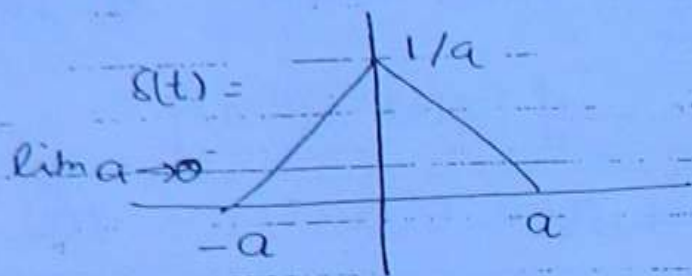
$$= f(a) \times 0 - f'(a)$$

$$= -f'(a)$$

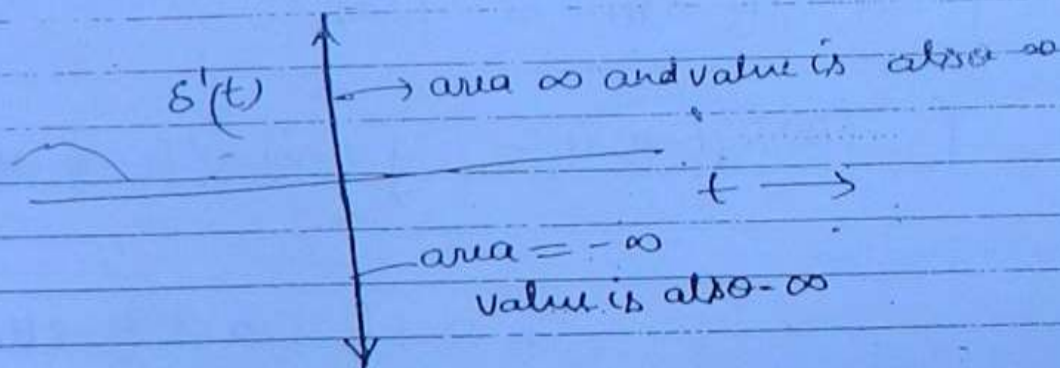
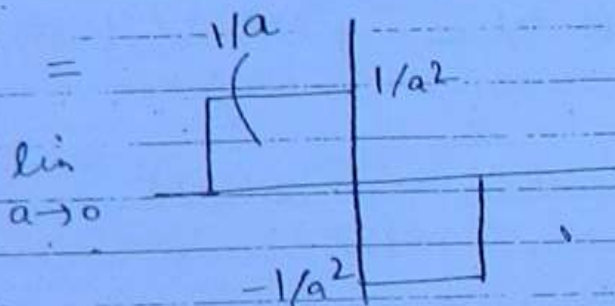
derivative of unit impulse signal

(84)

$$s'(t) = \frac{d}{dt} s(t) =$$



$$\lim_{a \rightarrow 0} \frac{d}{dt} s(t) =$$



$$s(at) = \frac{1}{|a|} s(t)$$

$$\frac{d}{dt} s(at) = \frac{1}{|a|} s'(t)$$

$$a s'(at) = \frac{1}{|a|} s'(t)$$

$$s'(at) = \frac{1}{a|a|} s'(t)$$

# Coolley - Tukey

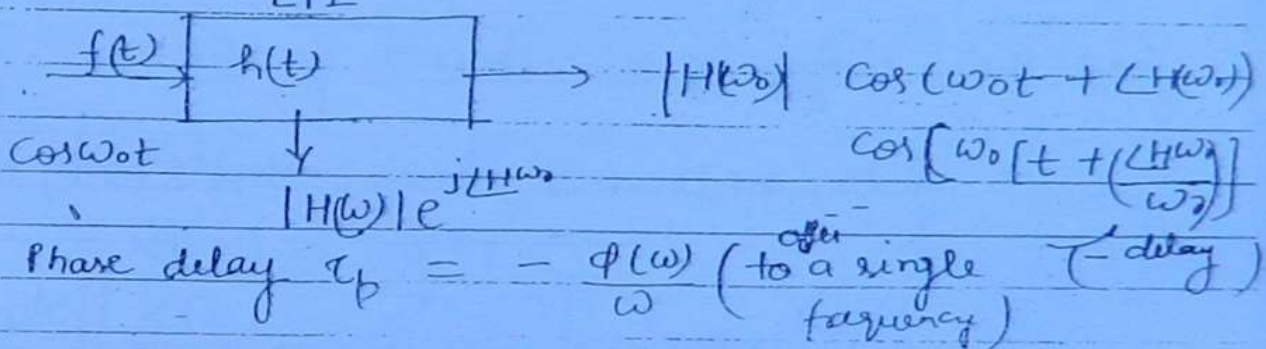
85

FFT (algorithm)

$\frac{N}{2} \log_2 N$  - multiplications

$N \log_2 N$  → additions

## Group delay and phase delay →



$$\phi(\omega) = \angle H(\omega)$$

$$\tau_g = -\frac{d\phi(\omega)}{d\omega} \text{ (offer to group of frequencies)}$$

Q. Calculate the Group delay and the phase delay of a distortionless transmission system and compare them.

$$H(\omega) = e^{-j\omega t_0}$$

$$\text{Phase delay} = t_0$$

$$\text{Group delay} = t_0$$

$$x[n] \otimes_{2N} h[n]$$

↓

$$x[n] \otimes h[n]$$

$$\longrightarrow X[k] H[k]$$

↓ DFT

$Y[k]$  of the LTI system

(86)

$$\sum |x[n]|^2 = \frac{1}{N} \sum_{k=0}^{N-1} |X[k]|^2 \quad \text{Parseval's theorem}$$

Q. DFT of a real valued signal  $x[n]$  is

$$\{10, 2+3j, A, 3-2j, -4, B, 1+j, C\}$$

find the energy of the signal

$$= \{10, 2+3j, 1-j, 3-2j, -4, 3+2j, 1+j, 2-3j\}$$

$$E = \frac{1}{8} \sum_{k=0}^{7} |X[k]|^2$$

$$= \frac{1}{8} [100 + 13 + 2 + 13 + 16 + 13 + 2 + 13]$$

$$= \frac{1}{8} [172]$$

$$E = 21.5 \text{ Joule}$$

$N^2$  - multiplication

→ actually

$4N^2$  multiplication

$N(N-1)$  addition

→ actually

$2N(N-1)$  addition

$$x[n] \xleftrightarrow{\text{DFT}} X[k]$$

$$x[-n]_N \xleftrightarrow{\text{DFT}} X[-k]_N \rightarrow X[N-k]$$

circally reversal

circally reversal

Q.  $x[n] \leftrightarrow \{10, 4+2j, -4, 4-2j\}$

find DFT of  $x[-n]_N$

$$X[-k] = \{10, 4-2j, -4, 4+2j\}$$

$$X[-k]_N = \text{Dm}$$

$$X[-k] = X^*[k]$$

$$X[k] = X^*[-k]$$

even conjugate in nature if  $x[n]$  is a real valued signal as in case of other fourier transforms.

all the properties of fourier transform of CT continuous time signal for complex signals are also valid for DFT.

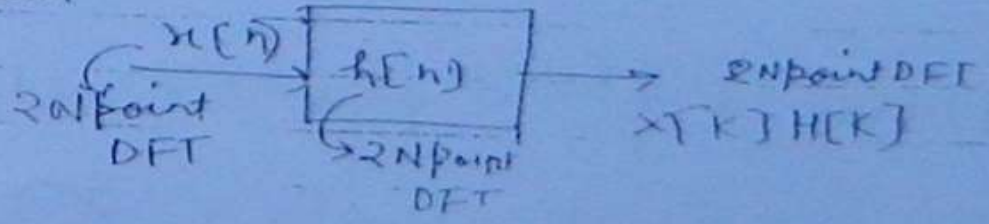
$$x[n] \xrightarrow{N\text{-point DFT}} X[k]$$

$$h[n] \xrightarrow{N\text{-point DFT}} H[k]$$

$$x[n] \otimes h[n] \leftrightarrow X[k] H[k]$$

$\otimes$   $\rightarrow$   $2N$  point DFT

for LTE system





Q. given two signals  $f[n]$  and  $h[n]$  each consisting of  $N$ -sample values if we zero pad each of the signal with  $N$ -zeros and carry out circular convolution of order  $2N$  this will be equal to linear convolution of two signals  $f[n]$  &  $h[n]$ .

88

Time shifting Property of DFT  $\rightarrow$

The DFT of a signal  $F[n] \leftrightarrow \{10, 4-2j, -4, 4+2j\}$

find the DFT of  $f[(n-2)]_4$

$$X[k] = F[k] e^{-j k \omega_0 \cdot 2}$$

$$Y[k] = F[k] e^{-j k \frac{2\pi}{4} \cdot 2}$$

$$Y[k] = F[k] (-1)^k$$

$$Y[k] = \{10, -4+2j, -4, -4-2j\}$$

$$x[n] \rightarrow X[k]$$

$$x[n] e^{j \frac{2\pi}{N} \cdot k_0 n} \rightarrow X[(k-k_0)]_N$$

always circular shift

Q. DFT of a signal  $x[n] = \{1, 2, 3, 4\} \leftrightarrow X[k]$   
find the inverse DFT of  $\leftrightarrow X[k-1]$

$$e^{j \frac{2\pi}{N} \cdot 1 \cdot X[n]}$$

$$e^{j \frac{2\pi}{4} \cdot n}$$

$$e^{j \pi/2 n}$$

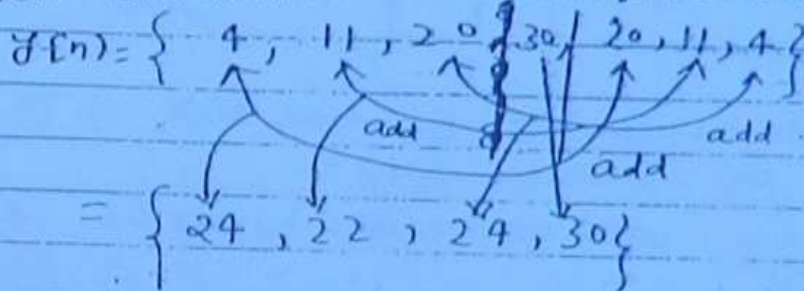
$$[j]^n$$

$$y[n] = \{1, 2j, -3, -4j\}$$

$f[n]$	$h[n]$	4	3	2	1
1		4	3	2	1
2		8	6	4	2
3		12	9	6	3
4		16	12	8	4

(89)

linear convolution result of two signal



$$(1 - e^{-j\omega})^2 = e^{-j\omega/2} [e^{j\omega/2} - e^{-j\omega/2}]$$

divide the result of linear convolution into two parts such that first part having  $\frac{N}{2}$  sample and then add corresponding parts in order and write as a circular convolution result.

No. of sample in each signal

Q. circularly convolve the following two signal

$$f[n] = \{1, 2\}$$

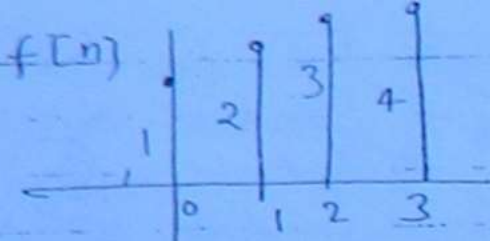
$$h[n] = \{2, 1\}$$

by zero padding each of signal with two zeros

	2	1	0	0
1	2	1	0	0
2	4	2	0	0
0	0	0	0	0
0	0	0	0	0

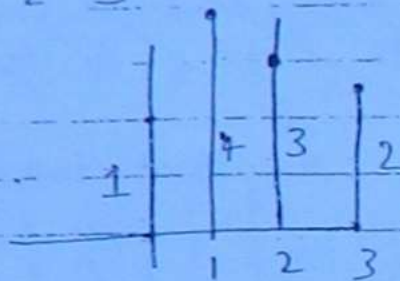
linear conv  $\left[ \begin{array}{cccc|cccc} 2 & 5 & 2 & 0 & 0 & 0 & 0 & 0 \end{array} \right] \leftarrow f[n] \otimes h[n]$

circular conv  $\left[ \begin{array}{cccc|cccc} 2 & 5 & 2 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$



(90)

$f[-n]_4 \rightarrow$



Keep the value at  $n=0$  as it is write other samples in reverse order.

as 2, 3, 4 will we will write as 4 3 2  
 $n = (1 \ 2 \ 3)$  at  $n = (1 \ 2 \ 3)$

Q.

Evaluate the circular convolution of 2 signals

$$f[n] = \{1, 2, 3, 4\}$$

$$h[n] = \{4, 3, 2, 1\}$$

$$h[-n] = \{4, 1, 2, 3\}$$

$$f[n] \otimes h[n]$$

symbol for circular convolution

$$y[n] = \sum_{k=0}^{N-1} f[k] h[(n-k)]_4$$

$$\therefore y[0] = 4 + 2 + 6 + 12 = 24$$

$$h[-n+1] = \{3, 4, 1, 2\}$$

~~24~~

$$\therefore y[1] = 3 + 8 + 3 + 8 = 22$$

$$h[-n+2] = \{2, 3, 4, 1\}$$

$$y[2] = 2 + 6 + 12 + 4 = 24$$

$$h[-n+3] = \{1, 2, 3, 4\}$$

$$\therefore y[3] = 1 + 4 + 9 + 16 = 30$$

$$y[n] = \{24, 22, 24, 30\}$$

$F[0]$  is always  $f[0] + \dots + f[N-1]$   
 $F[N/2]$   $f[0] - f[1] + f[2] - \dots$  (9)

$N$  is even

$F[k] = F^*[N-k]$  symmetry satisfied

these symmetries are valid till  $f[n]$  is a real valued signal.

DFT of a real valued signal is given as

$$\left\{ \begin{matrix} 10, A, 2+3j, B, -4, 3-2j, C, 1+j \\ 0, 1, 2, 3, 4, 5, 6, 7 \end{matrix} \right\}$$

find A, B, C.

$A = 1-j$

$B = 3+2j$

$C = 2-3j$

using  $F[k] = F^*[N-k]$

Q. Find the DFT of the following 8-point signal

$f[n] = \{ 1, \dots, 1 \}$

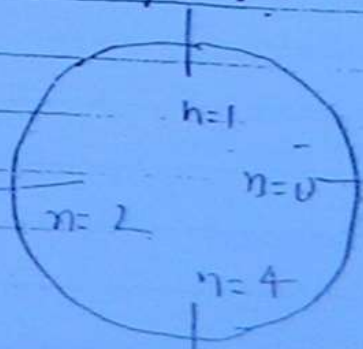
$F[0] = 8$

$F[1] = [1 + e^{-j\omega_0} + e^{-2j\omega_0} + \dots + e^{-7j\omega_0}]$

$F[4] = 0$   $F[1] = \frac{1}{e^{-j\omega_0/2}} \left[ \frac{1 - e^{-8j\omega_0}}{1 - e^{-j\omega_0}} \right]$

$F[1] = \frac{e^{-4j\omega_0}}{e^{-j\omega_0/2}} \left[ \frac{2j \sin 4\omega_0}{\sin \omega_0/2} \right]$   
 $= e^{-7j\omega_0/2} \frac{2j \sin 4\omega_0}{\sin \omega_0/2}$

Circular shift:  $\rightarrow$



$f[(n-1)]_8$

$f[(N-n)]_8$

shifting 0 1 unit but not linear  
 because it is circular.

$f[(N-n)]_8$

~~N-1-k~~

If  $N$ -sample values are picked up uniformly from DFT of a discrete time signal in its unique period of  $2\pi$ , we get the discrete Fourier transform.

(92)

Evaluate DFT of  $f[n] = \{1, 2, 3, 4\}$

$$F[k] = \sum_{n=0}^{N-1} f[n] e^{-j k \omega_0 n} \quad \omega_N = e^{-j \omega_0} \quad \downarrow \text{twiddle factor}$$

$$F[0] = \sum_{n=0}^3 f[n] e^{-j \omega_0 n}$$

$$= [1 + 2e^{-j\omega_0} + 3e^{-2j\omega_0} + 4e^{-3j\omega_0}]$$

$$= [1 + 2e^{-j\pi/2} + 3e^{-j\pi} + 4e^{-3j\pi/2}]$$

$$= [-2 - 2j + 4j]$$

$$F[1] = -2 + 2j$$

$$F[2] = \sum_{n=0}^3 f[n] e^{-2j\omega_0 n}$$

$$= [1 + 2e^{-2j\omega_0} + 3e^{-4j\omega_0} + 4e^{-6j\omega_0}]$$

$$= [1 + (-2) + 3 - 4]$$

$$F[2] = -2$$

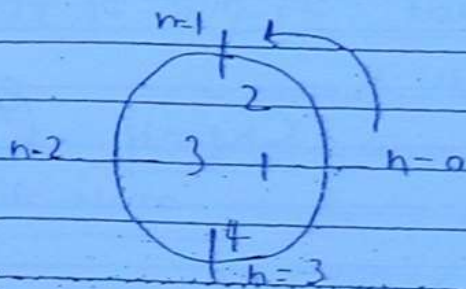
$$F[3] = [1 + 2e^{-3j\omega_0} + 3e^{-6j\omega_0} + 4e^{-9j\omega_0}]$$

$$= [1 + 2j - 3 - 4j]$$

$$= -2 - 2j$$

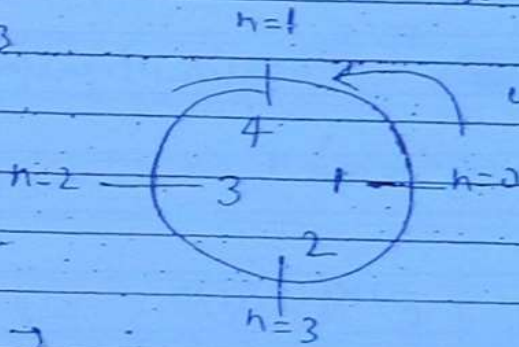
$$f[n] = \begin{cases} 1, 2, 3, 4 \end{cases}$$

(93)



will be done  
Representation  $\rightarrow$  shifting on this

to find  $f[(n-h)]_4$



write sample in clockwise values.

circular convolution  $\rightarrow$

$$f[n] \rightarrow (0 \rightarrow 3) \quad h[n] \rightarrow (0 \rightarrow 3)$$

$$y[n] = h[n] \otimes_4 f[n] \rightarrow 0 \rightarrow 6 \text{ - linear convolution}$$

$$= \sum_{k=0}^3$$

$$y[n] = f[n] \otimes_4 h[n] \quad - \quad \left. \begin{matrix} n=0 & n=3 \end{matrix} \right\}$$

circular convolution of order 4

\*  $C_k$  is defined as discrete time fourier series coefficient of signal  $f[n]$  and it is also discrete and periodic with the same period as that of  $f[n]$ .

(e.g.)  $C_k = C_{k+N} = C_{k+mN}$  (94)  
 $m$  is an intger

D.F.T.: Discrete ~~time~~ Fourier transform  $\rightarrow$

$$f[n] = \sum_{k=0}^{N-1} C_k e^{jK(2\pi/N)n} \quad -\infty < n < \infty$$

$$C_k = \frac{1}{N} \sum_{h=0}^{N-1} f[h] e^{-jK(2\pi/N)h} \quad K \rightarrow -\infty \text{ to } \infty$$

discrete time F.T. pairs

D.F.T.  $F[K] = \sum_{n=0}^{N-1} f[n] e^{-jK(2\pi/N)n}$  for  $K=0$  to  $N-1$   
 $0 \leq K \leq N-1$

$F[K] = NC_k$

$$f[n] = \sum_{k=0}^{N-1} \frac{1}{N} F[k] e^{jK(2\pi/N)n}$$

$$f[n] = \frac{1}{N} \sum_{k=0}^{N-1} F[k] e^{jK(2\pi/N)n}$$

$0 \leq n \leq N-1$

discrete F.T. pairs

- Shifting is circular and

$f[(n-2)]$  4 samples

ho of samples taken i.e. from 0 to 3

$$\frac{df(t)}{dt} \leftrightarrow j\omega F(\omega)$$

$$f[n] \leftrightarrow F(\omega)$$

$$f[n] - f[n-1] \leftrightarrow (1 - e^{-j\omega}) F(\omega) \quad (95)$$

$$u[n] \leftrightarrow \frac{1}{(1 - e^{-j\omega})} + \pi \delta(\omega)$$

$$-\pi \leq \omega \leq \pi$$

$$\leftrightarrow \pi \frac{1}{(1 - e^{-j\omega})} + \sum_{k=-\infty}^{\infty} \pi \delta(\omega - 2\pi k)$$

$$-\infty < \omega < \infty$$

$$\int_{-\infty}^t f(t) dt \leftrightarrow \frac{F(\omega)}{j\omega} + \pi \delta(\omega) \cdot F(0)$$

$$f[n] \leftrightarrow F(\omega)$$

$$\sum_{k=-\infty}^n f[k] \leftrightarrow \frac{F(\omega)}{(1 - e^{-j\omega})} + \pi \delta(\omega) F(0)$$

⊗ Duality Property of F.T. :

× D.T.F.T. and continuous time fourier series forms dual of each other.

× Discontinuity in one domain leads to periodicity in the second domain and vice versa.

fourier series for discrete <sup>time</sup> signals →

periodic N

$$f[n] = \sum_{k=0}^{N-1} C_k e^{jK\omega_0 n} = \sum_K C_k e^{jK \frac{2\pi}{N} n}$$

↓  
over period N

$$C_k = \frac{1}{N} \sum_n f[n] e^{-jK\omega_0 n}$$

over period N



We can use the properties of F.T. (continuous or discrete) only if dirichlet condition must be satisfied.

$$E = \int_{-\infty}^{\infty} |F(\omega)|^2 d\omega$$

Parseval's

(96)

$$E = \frac{1}{2\pi} \int_{-\pi}^{\pi} |F(\omega)|^2 d\omega$$

$$E = \frac{1}{2\pi} \int_{-2}^2 |f(t)|^2 dt$$

$$\left[ F = \frac{A}{2\pi} = \frac{2}{\pi} \right]$$

⊛ Convolution property of D.T.F.T.

$$f(n) \otimes h(n) \longleftrightarrow F(\omega) H(\omega)$$

Find the D.T.F.T of  $y(n) = \frac{1}{(1 - ae^{-j\omega})^2}$

$$a^n u(n) \otimes a^n u(n)$$

$$f(n) = \sum_{k=-\infty}^{\infty} f(k) f(n-k)$$

$$= \sum_{k=-\infty}^{\infty} a^k u(k) a^{n-k} u[n-k]$$

$$= \sum_{k=0}^{\infty} a^k a^{n-k} u[n-k]$$

$$= a^n \sum_{k=0}^{\infty} a u[n-k]$$

$$= a^n \sum_{k=0}^n u[n-k] \quad \text{for } n \geq 0 \quad \begin{matrix} n-k > 0 \\ k < n \\ 0 < n < \infty \end{matrix}$$

$$f(n) = (n+1) a^n u(n)$$

$$f(n) = (n+1) a^n u(n) \quad \text{Ans}$$

$$f(\omega) = \frac{1}{2\pi} \int_{-\pi}^{\pi} F(\omega) d\omega$$

(97)

$$= \frac{1}{2\pi} \cdot 2\omega_0$$

$$f(\omega) = \frac{\omega_0}{\pi}$$

$$f[n] = \frac{\sin \omega_0 n}{\pi n} \quad \text{for } n \neq 0$$

$$= \frac{\omega_0}{\pi} \quad \text{for } n = 0$$

Q. Two signals  $f[n]$  &  $h[n]$  are convolved to get the signal  $y[n]$ , the no. of nonzero samples in  $f[n]$  is 5 and no. of nonzero samples in  $h[n]$  is 3. The maximum possible sample values of  $f[n]$  &  $h[n]$  are  $l$  &  $k$  respectively. If D.T.F.T of  $y[n]$  is  $Y(\omega)$  what is maximum possible value of  $Y(0)$ ?

Ans.

$$Y(0) = 5 \cdot 3 \cdot k$$

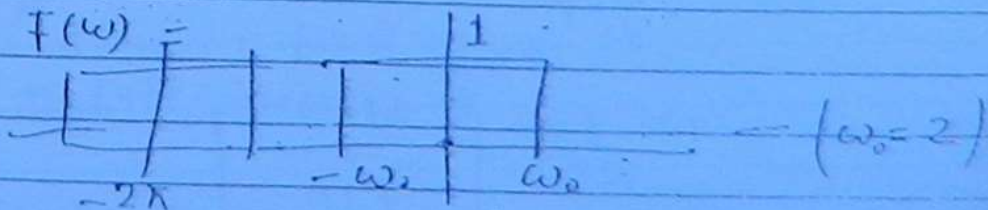
$$Y(\omega) = \sum_{n=-\infty}^{\infty} y[n] e^{-j\omega n}$$

$$Y(0) = 15lk$$

$$Y(0) = \sum_{n=-\infty}^{\infty} y[n]$$

Find the energy of the signal  $f[n] = \frac{\sin \omega_0 n}{\pi n}$  for  $n \neq 0$

$$\frac{2}{\pi} \quad n=0$$



$$E = \sum_{n=-\infty}^{\infty} f^2[n] = \frac{1}{\pi^2} + \sum_{\substack{n=-\infty \\ n \neq 0}}^{\infty} \frac{\sin^2 2n}{\pi^2 n^2}$$

Q. d D.F.F.T. of a signal  $f[n] \leftrightarrow 2 - 4e^{-j\omega}$

(98)

Find the D.T.F.T.  $nf[n-2]$

$$f[n-2] \rightarrow e^{-j2\omega} [2 - 4e^{-j\omega}]$$

$$nf[n-2] \leftrightarrow j [-4je^{-j2\omega} - 4je^{-j\omega}]$$

$$\leftrightarrow j [-4je^{2j\omega} + 12je^{-3j\omega}]$$

$$\leftrightarrow [4e^{-2j\omega} - 12e^{-3j\omega}]$$

$$\leftrightarrow 4e^{-2j\omega} [1 - 3e^{-j\omega}]$$

$\leftrightarrow$

$$f[n] \leftrightarrow F(\omega)$$

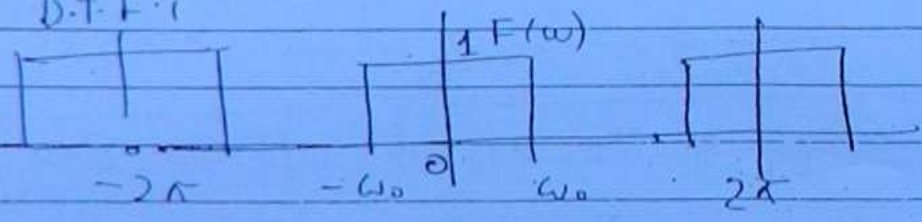
(99)

$$\sum_{n=-\infty}^{\infty} f[n] = F(0)$$

$$\int_{-\pi}^{\pi} F(\omega) d\omega = 2\pi f[0]$$

Find the inverse D.T.F.T. of for following

D.T.F.T



$$f[n] = \frac{1}{2\pi} \int_{-\omega_0}^{\omega_0} 1 \cdot e^{j\omega n} d\omega$$

$$= \frac{1}{2\pi} \left[ \frac{e^{j\omega n}}{jn} \right]_{-\omega_0}^{\omega_0}$$

$$= \frac{1}{2jn} [2j \sin \omega_0 n]$$

$$f[n] = \frac{1}{\pi n} \sin \omega_0 n = \frac{\omega_0}{\pi} \text{Sa}[\omega_0 n]$$

$$\sin \omega n \longleftrightarrow \frac{\pi}{j} [\delta(\omega - \omega_0) - \delta(\omega + \omega_0)]$$

$\pi(\omega < \pi)$

(99)

$$\text{or } \frac{\pi}{j} \sum_{k=-\infty}^{\infty} \delta(\omega - \omega_0 - 2\pi k) - \delta(\omega + \omega_0 - 2\pi k)$$

$-\infty < \omega < \infty$

$$\delta f[n] \longleftrightarrow F(\omega)$$

$$f[n - n_0] \longleftrightarrow e^{-j\omega n_0} F(\omega)$$

$$e^{j\omega_0 n} f[n] \longleftrightarrow F(\omega - \omega_0)$$

Find DTFT of  $f[n] = u[n] - u[n-9]$

$$\begin{array}{|c|} \hline 1 \\ \hline \end{array} \quad \begin{array}{|c|} \hline -1 \\ \hline \end{array}$$

9

$$= \sum_{n=0}^8 f[n] e^{-j\omega n}$$

$$= \frac{1 - e^{-j\omega 9}}{1 - e^{-j\omega}}$$

$$= \frac{e^{-j\omega 9/2} 2j \sin \omega 9/2}{e^{-j\omega/2} 2j \sin \omega/2}$$

$$= e^{-j\omega 4} \frac{\sin 9\omega/2}{\sin \omega/2}$$

$$F(\omega) \Rightarrow e^{-j4\omega} \frac{\sin 9\omega/2}{\sin \omega/2}$$

If D.T.F.T of  $f[n] \Leftrightarrow F(\omega)$ , find D.T.F.T of  $F(\omega - \pi)$

$$e^{j\pi n} f[n] \Leftrightarrow F(\omega - \pi)$$

$$(-1)^n f[n] \Leftrightarrow F(\omega - \pi)$$

$$(-1)^n e f[n] \Leftrightarrow F(\omega - \pi)$$

$$n f[n] \longleftrightarrow j \frac{dF(\omega)}{d\omega}$$

find DTFT of

$$n a^n u[n] \longleftrightarrow j \frac{d}{d\omega} \frac{1}{1 - a e^{-j\omega}}$$

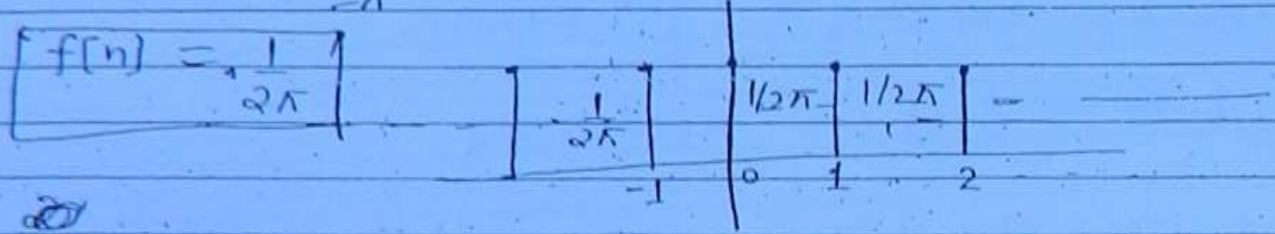
$$f[n] = \frac{1}{2\pi} \int_{-2\pi}^{2\pi} F(\omega) e^{j\omega n} d\omega$$

100

②  $F(\omega) = \delta(\omega)$   $\xrightarrow{-\pi < \omega < \pi}$   $\delta(\omega)$   $\xrightarrow{\sigma \rightarrow}$   $\delta(\omega)$

$F(\omega) = \sum_{k=-\infty}^{\infty} \delta(\omega - 2\pi k)$

$$f[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} \delta(\omega) e^{j\omega n} d\omega$$



$$\int_{-2\pi}^{2\pi} \delta(\omega) \quad -\pi < \omega < \pi$$

$$1 \longleftrightarrow 2\pi \delta(\omega)$$

$$1 \longleftrightarrow 2\pi \sum_{k=-\infty}^{\infty} \delta(\omega - 2\pi k) \quad -\infty < \omega < \infty$$

D.T.F.T of  $F(\omega) = 2\pi \delta(\omega - \omega_0)$

$$= f[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} 2\pi \delta(\omega - \omega_0) e^{j\omega n} d\omega \quad \omega - \omega_0 = W$$

$$= \frac{1}{2\pi} \int_{-\pi - \omega_0}^{\pi - \omega_0} \delta(W) e^{j(\omega_0 + W)n} dW$$

$$f[n] = e^{j\omega_0 n} \cdot 1$$

$$e^{j\omega_0 n} \longleftrightarrow 2\pi \delta(\omega - \omega_0) \quad -\pi < \omega < \pi$$

$$e^{j\omega_0 n} \longleftrightarrow 2\pi \sum_{k=-\infty}^{\infty} \delta(\omega - \omega_0 - 2\pi k) \quad -\infty < \omega < \infty$$

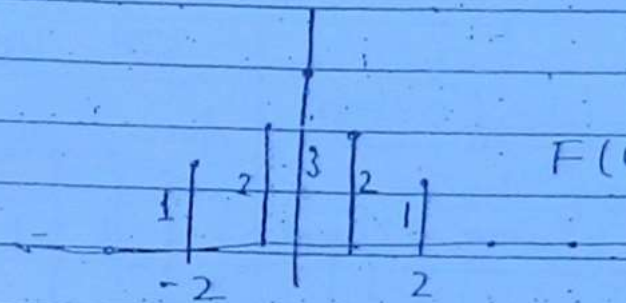
$$\cos \omega_0 n \longleftrightarrow \pi [\delta(\omega - \omega_0) + \delta(\omega + \omega_0)] \quad -\pi < \omega < \pi$$

$$\cos \omega_0 n \longleftrightarrow \pi \sum_{k=-\infty}^{\infty} [\delta(\omega - \omega_0 - 2\pi k) + \delta(\omega + \omega_0 - 2\pi k)]$$

$$F(\omega) = e^{j\omega N} \cdot e^{-j\omega(2N+1)/2} \left[ \frac{e^{j\omega(2N+1)/2} - e^{-j\omega(2N+1)/2}}{2} \right]$$

$$(10) = e^{-j\omega N} \cdot \frac{\sin \omega(2N+1)}{2} \cdot \frac{e^{-j\omega/2} [e^{j\omega/2} - e^{-j\omega/2}]}{2}$$

$$F(\omega) = \frac{\sin \omega(2N+1)}{\sin \omega/2}$$

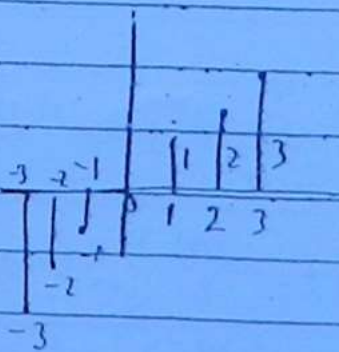


$$F(\omega) = \sum_{n=-2}^2 f[n] e^{-j\omega n}$$

$$= 3 + 2e^{-j\omega} + 2e^{j\omega} + 1e^{-j\omega \times 2} + 1e^{j\omega}$$

$$= 3 + 2\cos \omega + 2\cos 2\omega$$

$$F[\omega] = 3 + 4\cos \omega + 2\cos 2\omega$$



$$F[\omega] = 2j \sin \omega + 4j \sin 2\omega + 6j \sin 3\omega$$

Ans

D.T.F.T. is a continuous function of  $\omega$  repeating with a period of  $2\pi$  i.e.

We generally consider D.T.F.T. in an interval of width of  $2\pi$  extending from  $-\pi$  to  $\pi$  for all analytical (mathematical) purposes.

$$f[n] = a^n u[n]$$

$$a^n u[n] \Leftrightarrow \left[ \frac{1}{1 - ae^{-j\omega}} \right]$$

$$|a| < 1$$

(102)

$$\delta[n] \Leftrightarrow 1$$

$$a^{-n} u[-n-1] \Leftrightarrow \frac{1}{1 - ae^{-j\omega}} \quad |a| > 1$$

$$a^{|n|} = a^n u[n] + a^{-n} u[-n-1]$$

$$a^{|n|} \Leftrightarrow \frac{1}{1 - ae^{-j\omega}} + \frac{1}{1 - \frac{1}{a}e^{-j\omega}} \quad |a| < 1$$

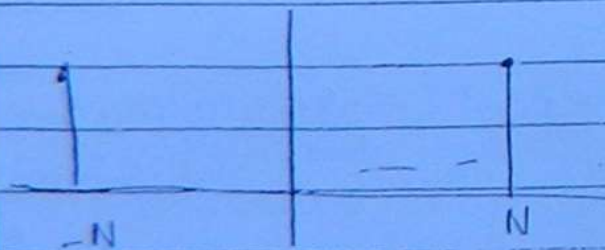
$$= \frac{a - e^{-j\omega}}{(1 - ae^{-j\omega})(1 + ae^{-j\omega})} \quad \left| \frac{1}{a} \right| > 1$$

$$= \frac{(1 - ae^{-j\omega})(a - e^{-j\omega})}{e^{j\omega}(1 - a^2)} \quad (|a| < 1)$$

$$\frac{(e^{j\omega} - a)(a - e^{-j\omega})}{(e^{j\omega} - a)(a - e^{-j\omega})}$$

$$= \frac{1 - a^2}{(a - e^{j\omega})(a - e^{-j\omega})} = \frac{(1 - a^2) \operatorname{Im}}{a^2 - 2a \cos \omega + 1}$$

$$|a| < 1$$



$$\leftrightarrow F(\omega) = \sum_{n=-N}^N \delta[n] e^{-j\omega n}$$

$$h = m$$

$$n + N = m$$

$$F(\omega) = \sum_{m=0}^{2N} e^{-j\omega(m-N)}$$

$$= e^{j\omega N} \sum_{m=0}^{2N} e^{-j\omega m}$$

$$= e^{j\omega N} \left[ \frac{1 - e^{-j\omega(2N+1)}}{1 - e^{-j\omega}} \right]$$

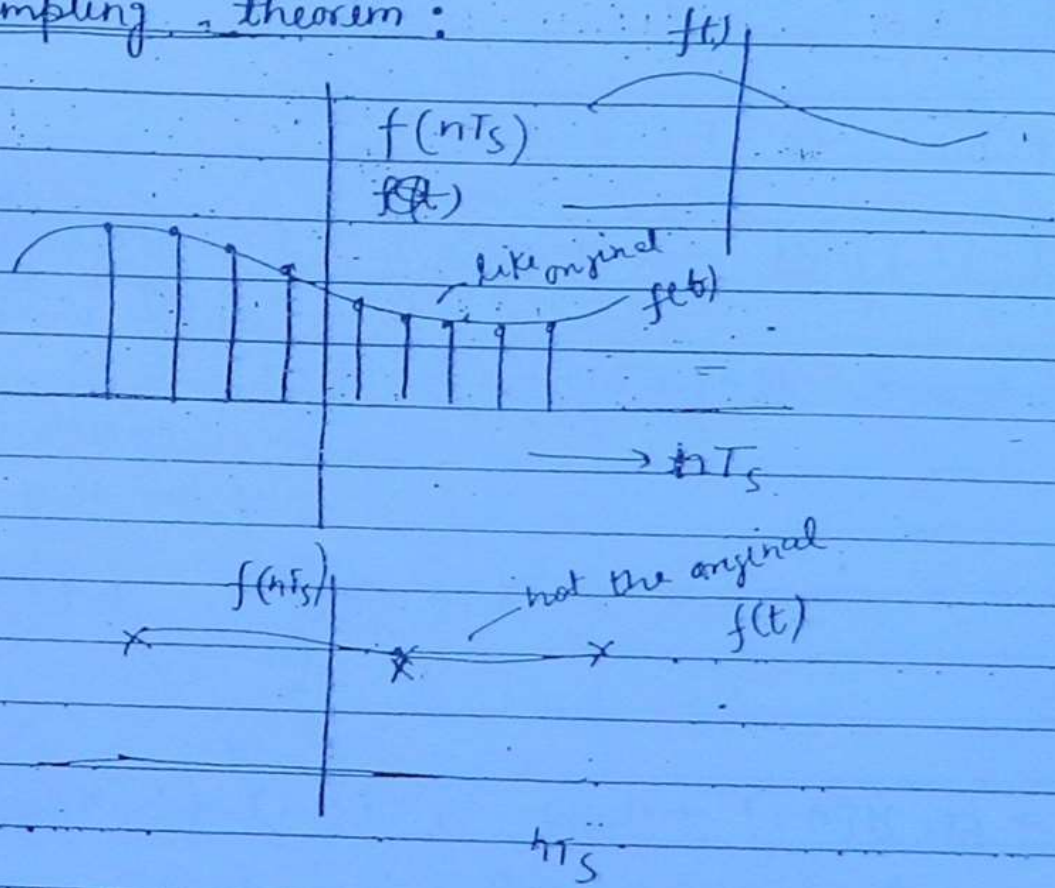
$$F(\omega) = \frac{e^{j\omega N} - e^{-j\omega N}}{1 - e^{-j\omega}}$$

Initial value theorem can be applied any  $F(z)$  there is no restriction.

\* For application of Final value theorem all the poles of  $(z-1)F(z)$  or  $(1-z^{-1})F(z)$  must lie inside the unit circle (strictly i.e.  $|z| \neq 1$ )

103

Sampling theorem:



11<sup>th</sup> NOV 10:

$$F(\omega) = \sum_{n=-\infty}^{\infty} f[n] e^{-j\omega n}$$

discrete time F.T.

$F(j\Omega)$   
 $F(e^{j\Omega})$   
 all used for D.T.F.T.  
 omega corresponds to discrete angular frequency



$$Y(z) = \frac{1}{(1-2z^{-1})(1-3z^{-1})} = \frac{-1/2}{(1-2z^{-1})} + \frac{3}{(1-3z^{-1})}$$

12/23

$$y[n] = -2 \cdot 2^n u[n] + 3 \cdot 3^n u[n]$$

(104)

$$y[n] = 3^{n+1} u[n] - 2^{n+1} u[n]$$

Q. Property

$$f[n] \rightarrow F(z)$$

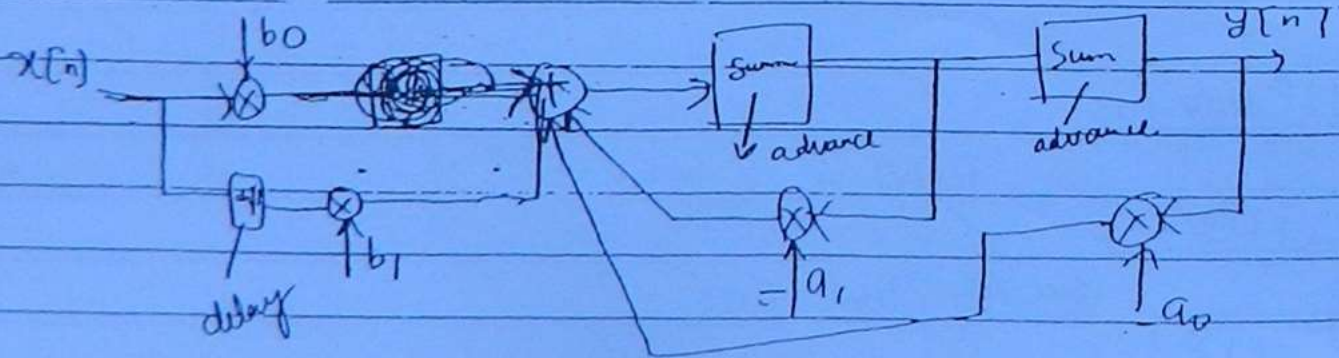
$$f[n] - f[n-1] \rightarrow (1-z^{-1})F(z) \quad \text{ROC remains same but only exclude } z=0 \text{ from ROC.}$$

$$\sum_{k=-\infty}^n f[k] \leftrightarrow f[n] * u[n] \leftrightarrow F(z) \cdot U(z)$$

ROC intersection of the two

$$\leftrightarrow \frac{1}{(1-z^{-1})} \cdot F(z)$$

$$a_2 y[n-2] + a_1 y[n-1] + a_0 y[n] = b_1 x[n-1] + b_0 x[n]$$



$$\left\{ \begin{array}{l} a^n u[n] \rightarrow \frac{1}{1-az^{-1}} \\ -a^n u[-n-1] \rightarrow \frac{1}{1-az^{-1}} \end{array} \right\}$$

$$\frac{z}{(z+3)^2} \rightarrow \frac{1}{3} \frac{z/3}{\left(\frac{z}{3}+1\right)^2} \rightarrow \frac{-1}{3} \frac{z/3}{\left[\left(\frac{z}{3}\right)-1\right]^2} \quad (105)$$

$$\rightarrow -\frac{1}{3} \left(\frac{1}{3}\right)^n n u[n]$$

$$\left\{ \begin{array}{l} n u[n] \rightarrow \frac{z}{(z-1)^2} \quad \text{Roc } |z| > 1 \\ a^n n u[n] \rightarrow \frac{z/a}{(z/a-1)^2} \quad \text{Roc } |z| > a \end{array} \right\}$$

$$n^2 u[n] \rightarrow \frac{z(z+1)}{(z-1)^3}$$

Q. Z-transform of a signal  $f[n]$  is defined as

$$F(z) = 2 - 4z^{-1} + 8z^{-2}$$

$$f[n] = \left\{ \begin{array}{c} 2, -4, 8 \\ \uparrow \end{array} \right\}$$

$$nf[n] = \left\{ \begin{array}{c} 0, -4, 16 \\ \uparrow \end{array} \right\}$$

$$Z\{nf[n]\} = G(z) = -4z^{-1} + 16z^{-2}$$

$$-2 \frac{dF(z)}{dz}$$

$$-(2-1)z^{-2}$$

Convolution Property of z-transforms  $\rightarrow$

$$f[n] \rightarrow F(z)$$

$$h[n] \rightarrow H(z)$$

$$f[n] \otimes h[n] \rightarrow F(z) \cdot H(z)$$

Q. Find the response of a discrete time system with impulse response  $h[n] = 2^n u[n]$

$$f[n] = 3^n u[n]$$

Shifting

$$f[n] \rightarrow F[z]$$

$$f[n-n_0] \rightarrow z^{-n_0} F[z]$$

106

ROC remains same the only  $z=0$  or  $\infty$  can be excluded.

$$\cos \omega_0 n u[n] \rightarrow \frac{z^2 - 2z \cos \omega_0}{z^2 - 2z \cos \omega_0 + 1} \quad |z| > 1$$

$$\sin \omega_0 n u[n] \rightarrow \frac{z \sin \omega_0}{z^2 - 2z \cos \omega_0 + 1} \quad |z| > 1$$

$$-\cos \omega_0 n u[-n-1] \rightarrow \frac{z^2 - 2z \cos \omega_0}{z^2 - 2z \cos \omega_0 + 1} \quad |z| < 1$$

$$-\sin \omega_0 n u[-n-1] \rightarrow \frac{z \sin \omega_0}{z^2 - 2z \cos \omega_0 + 1} \quad |z| < 1$$

$$a^n \cos \omega_0 n u[n] \rightarrow \frac{z(z/a)^2 - 2z/a \cos \omega_0}{(z/a)^2 - 2z/a \cos \omega_0 + 1} \quad |z| > |a|$$

Multiplication by  $n$ :

$$n u[n] \rightarrow -z \frac{d}{dz} \left[ \frac{z}{z-1} \right] = -z \left[ \frac{1}{z-1} + \frac{z}{(z-1)^2} \right] = -z \left[ \frac{z+1}{(z-1)^2} \right]$$

$$f[n] \rightarrow F(z)$$

$$n f[n] \rightarrow -z \frac{dF(z)}{dz} \quad \text{ROC remains same}$$

Find Inverse Z-T.  $F(z) = \frac{z}{(z-2)(z+3)^2}$

$$\frac{F(z)}{z} = \frac{1}{25(z-2)} - \frac{1}{25(z+3)} + \frac{1}{5(z+3)^2}$$

$$\frac{3}{(z+3)} \rightarrow -z \left[ \frac{3}{(z+3)^2} - \frac{1}{z+3} \right]$$

$$F(z) = \frac{1}{25} \frac{z}{z-2} - \frac{1}{25} \frac{z}{z+3} - \frac{1}{5} \frac{z}{(z+3)^2}$$

$$= \frac{1}{25} 2^n u[n] - \frac{1}{25} (-3)^n u[n] - \frac{1}{5} \frac{z}{(z+3)^2}$$

$$\frac{1}{z+3} = \frac{z}{(z+3)^2}$$

$$\frac{z}{(z+3)^2} \left( \frac{z}{z+3} \right)$$

$$|z| > 3 \quad \frac{1}{15} (-3)^n u[n]$$

when ROC not given consider right

$$f[n] = \frac{1}{3} [2]^n u[n] - \frac{1}{3} (-1)^n u[n] \quad \left\{ \begin{array}{l} \text{Right sided} \\ \text{not stable} \\ \text{causal, DTFT} \\ \text{can't be defined} \end{array} \right.$$

(107)  $|z| > 2$

or  $-\frac{1}{3} [2]^n u[-n-1] + \frac{1}{3} (-1)^n u[-n-1] \quad \left\{ \begin{array}{l} \text{left sided} \\ \text{not stable} \\ \text{not causal} \\ \text{DTFT not defined} \end{array} \right.$

$|z| < 1$

or  $-\frac{1}{3} [2]^n u[-n-1] - \frac{1}{3} (-1)^n u[n]$

$1 < |z| < 2 \quad \left\{ \begin{array}{l} \text{two sided, DTFT not defined} \\ \text{not stable} \\ \text{not causal} \end{array} \right.$

Find the G.Z.T. of above signal if z-transform  $F(z)$  is defined for  $z = 3 + j5$

$$|z| = |z| = \sqrt{9+25} = \sqrt{34}$$

$|z| > 2$

$$f[n] = \frac{1}{3} 2^n u[n] - \frac{1}{3} (-1)^n u[n]$$

$|z| > 2$

Linearity:

$$a_1 f_1[n] + a_2 f_2[n] \rightarrow a_1 F_1(z) + a_2 F_2(z)$$

ROC is intersection of individual ROC's

①  $a^n f_1[n] \rightarrow F(z/a) \quad \text{ROC } |z/a|$

$e^{j\omega_0 n} f[n] \rightarrow F(z/e^{j\omega_0}) \quad \text{ROC } |z| \text{ remains same}$

because  $\left| \frac{z}{e^{j\omega_0}} \right| = |z|$

If the DTFT for the previous question is defined

for  $|b| < 1$

if it is defined then it will be stable.

DTFT of the power

(108)

Inverse Z-transform:

$$f[n] = \frac{1}{2\pi j} \oint f(z) z^{n-1} dz$$

Q:

$$F[z] = \frac{z}{(z^2 - z - 2)}$$

$$= \frac{z}{(z-2)(z+1)}$$

$$= \frac{2}{3(z-2)} + \frac{1}{3(z+1)}$$

$$\therefore = \frac{2}{3}$$

$$F[z] = \frac{z^{-1}}{1 - z^{-1} - 2z^{-2}} = \frac{-z^{-1}}{2z^{-2} + z^{-1} - 1}$$
$$= \frac{z^{-1}}{z^2(2z^{-2} + z^{-1} - 1)}$$

$$= \frac{-z^{-1}}{(2z^{-1} - 1)(z^{-1} + 1)}$$

$$= \frac{z^{-1}}{(1 - 2z^{-1})(1 + z^{-1})} = \frac{1}{3(1 - 2z^{-1})} + \frac{1}{3(1 + z^{-1})}$$

$$f[n] = \{1\} \quad = 1 \quad \text{ROC entire } z\text{-plane}$$

(109)

$$f[n] = \{1, 2, 3\} \quad F[z] = 1 + 2z^{-1} + 3z^{-2} \quad \text{entire } z\text{-plane}$$

except  $|z| = 0$

$$f[n] = \{1, 2, 3\} \quad F[z] = 3 + 2z + 1z^2$$

entire  $z$ -plane

except  $|z| = \infty$

$$f[n] = \{1, 2, 3\} \quad = z + 2 + 3z^{-1}$$

ROC entire  $z$  plane

except  $|z| = 0, \infty$

\* A discrete time signal - having finite no. of non-zero sample will have an ROC which is the entire  $z$ -plane except possibly  $\odot r=0$ , or  $r=\infty$ , or both  $\odot r=0$  and  $\odot r=\infty$ .

\* If the ROC is to be outward directed, ROC must be extending till  $\odot r=\infty$   $\odot$  including  $r=\infty$  circle.

Q.  $f[n] = b^{|n|}$

$$= b^n u[n] + b^{-n} u[-n-1]$$

$$= \frac{z}{z-b}$$

$$+ \frac{z}{z-1/b}$$

$$b > 1$$

$$0 < b < 1$$

$$|z| > |b|$$

$$|z| < |1/b|$$

$$\text{if } |b| < 1$$

$$\boxed{\text{ROC } |b| < |z| < |1/b|}$$

if  $|b| > 1$  then  $z$ -transform can't be defined.

\* Combination of left sided signal will have always a defined z-transform with an ROC which is inward directed bounded by the circle whose radius is the magnitude of the least pole. (1/0)

Q.  $f[n] = (3/4)^n u[n] + (5/6)^n u[n] + (7/8)^n u[-n-1] + (9/10)^n u[-n-1]$

$$F(z) = \frac{z}{z-3/4} + \frac{z}{z-5/6} - \frac{z}{z-7/8} - \frac{z}{z-9/10}$$

$$\left( 5/6 < |z| < 7/8 \right), \dots$$

$$\left[ 6^{1/3} \cdot 5^{1/2} \right]$$

$$(6^2)^{1/6} \quad (5^3)^{1/6}$$

$$(36)^{1/6} \quad (125)^{1/6}$$

\* Combination of right sided and left sided signal will have an ROC which is a finite circular strip bounded on the lower side by a circle whose radius is the magnitude of the greatest pole of all the right sided signals and on upper side by a circle whose radius is the magnitude of the least pole of all the left sided signal.

find the z-transform of signal

$$f[n] = 2^n u[n] + 5^n u[n] - 2^n u[-n-1] - 5^n u[-n-1]$$

$$\left. \begin{array}{l} |z| > 5 \\ |z| < 2 \end{array} \right\} \left. \begin{array}{l} \text{Simultaneous} \\ \text{not possible} \end{array} \right\} \text{not defined.}$$

of the impulse response of such a ~~stable~~ stable & causal system must lie inside the unit circle.

\* For a discrete time signal  $f[n]$ , Fourier transform can be defined as  $F(\omega) = \sum_{n=-\infty}^{\infty} f[n] e^{-j\omega n}$ , this is defined as

discrete time Fourier transform or DTFT in short. (11)

⊕ DTFT of a discrete time signal  $F[n]$  is same as z-transform, with  $r=1$ .

⊕ So in the z-transform expression if we substitute  $r=1$ .  $z = re^{j\omega}$  then  $r=1$  it will result in discrete time Fourier transform. i.e. If we substitute  $z = e^{j\omega}$  in z-transform expression we get the DTFT provided  $\odot$  z-transform is defined for  $r=1$  i.e. ROC of the z-transform is including the unit circle.

⊕ DTFT is z-transform evaluated along the unit circle.

$$\left(\frac{3}{2}\right)^n u[n] \rightarrow \frac{z}{z-3/2} \quad |z| > 3/2$$

$$\left(\frac{3}{2}\right)^n u[n] + \left(\frac{5}{2}\right)^n u[n] \rightarrow \frac{z}{z-3/2} + \frac{z}{z-5/2} \quad \text{ROC } |z| > 5/2$$

\* Combination of right sided ~~right~~ discrete time signal will always have a defined z-transform with an ROC which is outward directed bounded by a circle whose radius is the magnitude of the highest pole.

$$-2^n u[-n-1] \rightarrow \frac{z}{z-2} \quad |z| < 2$$

$$-5^n u[-n-1] - 2^n u[-n-1] \rightarrow \frac{z}{z-5} + \frac{z}{z-2}$$



s-plane will be map to all the circles having radius greater than 1, and  $j\omega$  axis of s-plane will be map to a circle of unit radius.

$$F(\omega) = \sum_{n=-\infty}^{\infty} f[n] e^{-j\omega n}$$

DTFT

Discrete time fourier transform

(112)

- \* ROC of z-transform is a set of concentric circles, generally a circular strip.
- \* ROC of the z-transform can't include any poles but is bounded by the circle whose radius is the magnitude of pole.
- \* ROC of right sided signal is outward directed i.e. outside some circle.
- \* ROC of left sided signal is inward directed i.e. inside some circle.
- \* If a system with impulse response  $h[n]$  is to be stable condition:  $\sum_{n=-\infty}^{\infty} |h[n]| < \infty$  and for this to be satisfied the region of convergence of the z-transform of the impulse response must be including unit circle.
- \* A system with impulse response  $h[n]$  is causal, if  $h[n] = 0$  for  $n < 0$ . And in this case the region of convergence of z-transform of impulse response must be outward directed.
- \* If a system with impulse response  $h[n]$  is to both stable & causal ROC must be including the unit circle and must be outward directed. And ROC can't include any poles.
- So for a system with impulse response  $h[n]$  to be stable, we must all the poles of the z-transform

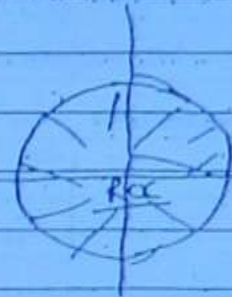
Find z-transform of  $f[n] = u[-n-1]$

$$F[z] = z + z^2 + \dots$$

(1/3)

$$F[z] = z \frac{1}{1-z} \quad |z| < 1$$

$$F[z] = \frac{-1}{(1-z^{-1})} \quad |z| < 1 \text{ ROC, } r < 1$$



$$a^n u[n] = \frac{1}{(1-az^{-1})}$$

$$|az^{-1}| < 1 \quad |z| > |a|$$

$$|z| > |a|$$

$$|z| > |a|$$

$$-a^n u[-n-1] = \frac{1}{(1-az^{-1})}$$

$$|z| < |a|$$

$$|z| < |a|$$

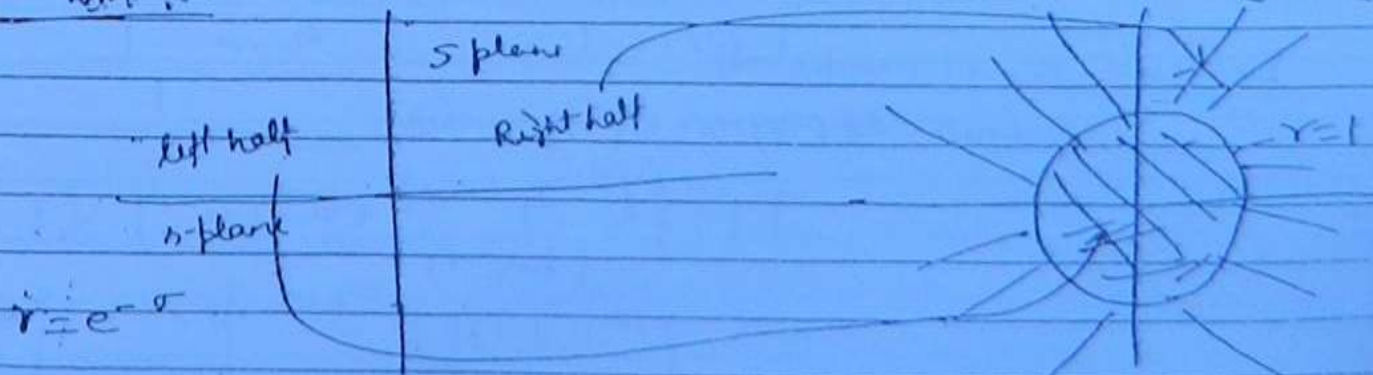
$$|z| < |a|$$

$$f[n] \rightarrow F[z]$$

according to

$$a^n f[n] \rightarrow F[z/a] \quad \text{ROC} \rightarrow |z/a|$$

2<sup>nd</sup> Nov 10



left half of s-plane will be map to all circle having radius 0.5

For a discrete time signal  $f[n]$ , z-transform is defined as  $F(z) = \sum_{n=-\infty}^{\infty} f[n] z^{-n}$  (114)

where  $z$  is complex variable defined as  $z = r e^{j\omega}$ . This can be understood as Laplace transform a discrete time signal  $f[n]$ , the complex variable  $s = \sigma + j\omega$  from its rectangular form is replaced by a complex variable  $z = r e^{j\omega}$  in polar form. If the z-transform of the signal  $f[n]$  is to be defined, the condition is

$$\left| \sum_{n=-\infty}^{\infty} f[n] z^{-n} \right| < \infty$$

$$\left( \sum_{n=-\infty}^{\infty} |f[n] z^{-n}| \right) < \infty$$

$$\sum_{n=-\infty}^{\infty} |f[n] r^{-n}| < \infty$$

Based on the nature of given discrete time signal  $f[n]$  there will be a set of  $r$  values for which above condition is satisfied, this region of  $r$  values for which the z-transform of a signal  $f[n]$  is defined is called as region of convergence of z-transform and it is specified in terms of  $r$  or  $|z|$  (ROC).

find z-transform of

$$f[n] = \delta[n]$$

$$F(z) = 1$$

$$f[n] = u[n]$$

$$F(z) = \frac{1}{(1-z^{-1})} \quad \text{ROC: } |z^{-1}| < 1$$

$$\text{ROC: } |z| > 1$$

Calculate the final value of  $F(s) = \frac{S+2}{(S^2+3S+2)}$

(115)

$$\lim_{S \rightarrow 0} SF(s) = \lim_{S \rightarrow 0} \frac{S(S+2)}{(S+2)(S+1)}$$

$$= 0$$

Z-transform:

$\hookrightarrow \infty$

$$F(z) = \sum_{n=-\infty}^{\infty} f[n] z^{-n}$$

$$z = e^{j\omega}$$

$$F(z) = \sum_{n=-\infty}^{\infty} f[n] e^{-\sigma n} e^{-j\omega n}$$

$$r e^{\sigma}$$

$$s = (\sigma + j\omega)$$

$$\downarrow \quad \downarrow$$

$$z = r e^{j\omega}$$

$$= \sum_{n=-\infty}^{\infty} f[n] r^{-n} (e^{j\omega})^{-n}$$

$$= \sum_{n=-\infty}^{\infty} f[n] r^{-n} z^{-n}$$

$$= \sum_{n=-\infty}^{\infty} f[n] [r e^{j\omega}]^{-n}$$

$$r e^{j\omega} = z$$

$$F(z) = \sum_{n=-\infty}^{\infty} f[n] z^{-n}$$

for Z-transform to be defined

summation must be converging

$$\left| \sum_{n=-\infty}^{\infty} f[n] z^{-n} \right| < \infty$$

$$\sum_{n=-\infty}^{\infty} |f[n] z^{-n}| < \infty$$

$$\sum_{n=-\infty}^{\infty} |f[n] r^{-n}| < \infty \quad \text{for a set of } r \text{ values}$$

when ever result comes  $\infty \rightarrow$  not defined  
 $\infty - \infty$  because  $\infty$  is a undefind quantity

Initial value theorem  $\rightarrow$

(116)  $\lim_{t \rightarrow 0} f(t) = \lim_{s \rightarrow \infty} sF(s)$

Initial value theorem  $\left\{ \begin{array}{l} f(0^-) = \lim_{s \rightarrow \infty} sF(s) \end{array} \right.$

Final Value theorem  $\left\{ \begin{array}{l} \lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s) \end{array} \right.$

$F(s) = \frac{\omega_0}{s^2 + \omega_0^2}$   $\rightarrow$  impulse  
 $\left\{ \begin{array}{l} 1 \leq f(t) < 1 \end{array} \right.$

⊕ Initial value theorem can be applied only if degree of numerator of L.T. is less than the degree of denominator

$$F(s) = \frac{s+2}{s^2+3s+2} = \frac{A}{(s+1)} + \frac{B}{s+2}$$

I.L.T.  $\uparrow$   
exists

$$F(s) = \frac{s^2+2s+3}{s^2+3s+2} = s^2 \frac{1+s}{s^2+3s+2} + \frac{1-s}{s^2+3s+2}$$

⊕ if the degree of numerator is greater than or equal to degree of denominator, we will have derivatives of impulses or impulses themselves in S.L.T. whose value is not known at  $t=0$  hence initial value theorem can't be applicable.

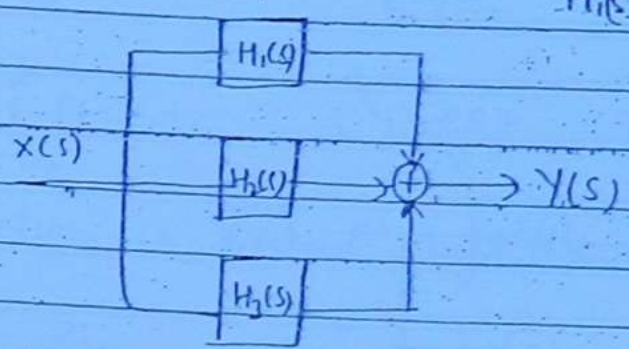
⊕ Final value theorem of L.T. can be applied only if all the poles of  $sF(s)$  lie in left half of the  $s$ -plane (strictly left half i.e. excluding  $j\omega$  axis)

# Parallel Representation.

$$H(S) = \frac{A}{(S+a_0)} + \frac{B}{(S+B)} + \frac{C}{s^2+B^2}$$

(117)

$$H_1(S) + H_2(S) + H_3(S)$$



(\*)  $F(S) = \int_{-\infty}^{\infty} f(t) e^{-st} dt$   
 two sided L.T.  
 Bilateral L.T.

$F(S) = \int_0^{\infty} f(t) e^{-st} dt$  one sided L.T.  
 also called as unilateral L.T.

When analysis is started from  $t=0$  (ft may exist before  $t=0$ )  
 In unilateral transform ROC does not play important role while it plays an important role in bilateral transform.

(\*) Unilateral transform for a signal  $f(t)$  is defined as  
 $F(S) = \int_0^{\infty} f(t) e^{-st} dt \rightarrow$  also called as one sided

L.T. and unilateral transform for any signal  $f(t)$ , is unique and hence region of convergence need not be specified to denote the uniqueness of L.T.

$f(t) \leftrightarrow F(S)$  ( $F(S)$  is unilateral transform of  $f(t)$ )  
 $f(t-t_0) \cdot u(t-t_0) \leftrightarrow F(S) e^{-St_0}$

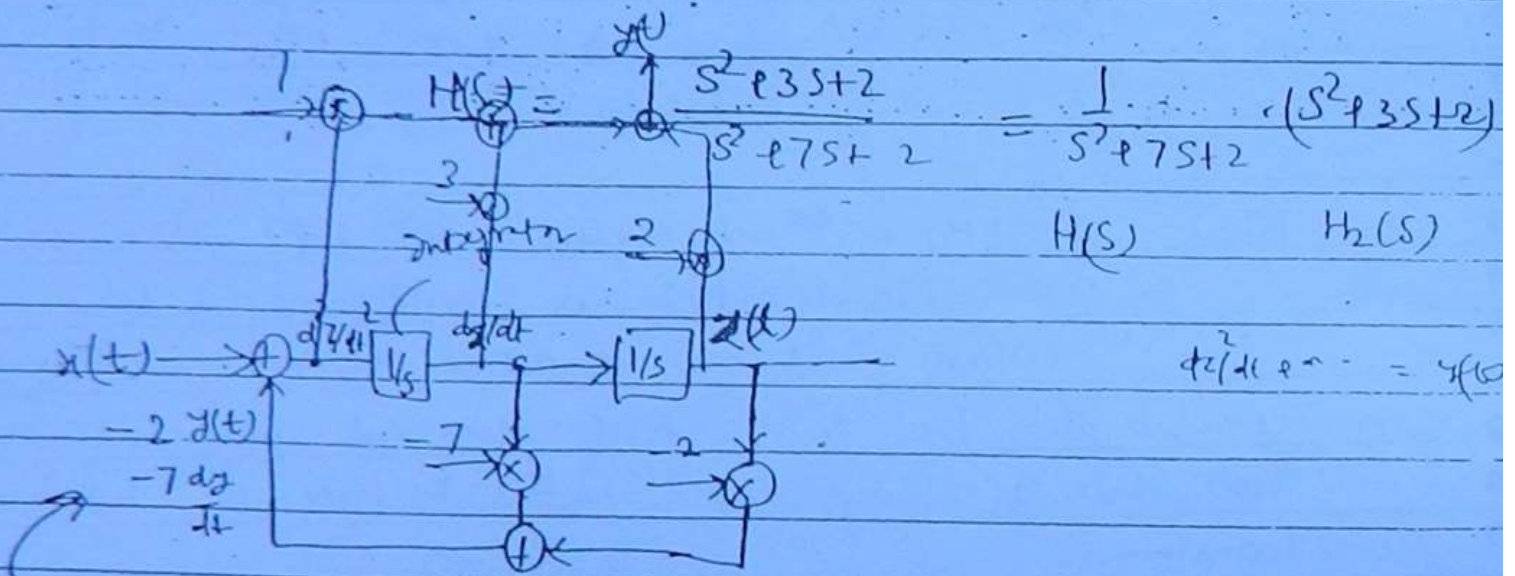
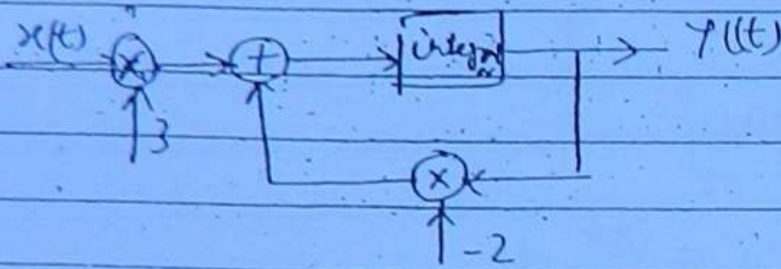
$\frac{df(t)}{dt} \rightarrow SF(S) - f(0^-)$   
 analysis starts at  $t=0$   
 a ... ..

$$\frac{dy}{dt} + 2y(t) = 3x(t)$$

$$H(s) = \frac{3}{s+2}$$

$$\frac{dy}{dt} = -2y(t) + 3x(t)$$

$$h(t) = 3e^{-2t} u(t)$$



cascade representation of LTI systems:

$$f(t) \leftrightarrow F(s)$$

$$\frac{d f(t)}{dt} \rightarrow s F(s) - f(0^-)$$

$$\frac{d^2 f(t)}{dt^2} \rightarrow s^2 F(s) - \cancel{s f(0^-)} - \cancel{f'(0^-)}$$

$$\int_{-\infty}^t f(\tau) d\tau \rightarrow \frac{F(s)}{s}$$

Q. A system is defined by the following differential eqn

$$\frac{d^2 y}{dt^2} - 2 \frac{dy}{dt} + 10 y(t) = 2 \frac{dx}{dt} + 3 x(t)$$

Is this linear T-I system. Yes this is LTI system.

$$H(s) = \frac{2s+3}{(s^2-2s+10)}$$

$$= \frac{2s+3}{s^2 - (s-1)^2 + 9}$$

And  $h(t)$  for it to be stable

$$H(s) = \frac{2[s-1] + 5}{(s-1)^2 + 9}$$

$$H(s) = \frac{2(s-1)}{(s-1)^2 + 9} + \frac{5}{(s-1)^2 + 9} \quad \sigma < 1$$

$$h(t) = \frac{1}{3} \left[ -2e^t \cos 3t u(-t) + 5e^t \sin 3t u(-t) \right]$$

$\sigma < 1$

Find impulse response of above system is to be causal

$$= 2e^t \cos 3t u(t) + \frac{5}{3} e^t \sin 3t u(t) \quad \sigma > 1$$

$\sigma > 1$



Q.  $h(t) = e^{-t} u(t)$ ,  $f(t) = e^{-3t} u(t) + e^{-2t} u(-t)$

$$H(s) = \frac{1}{s+1}, \quad F(s) = \left[ \frac{-1}{s+3} + \frac{1}{s+2} \right] \quad \text{Re } s < -1$$

$$F(s) = \left[ \frac{1}{s+3} - \frac{1}{s+2} \right] \quad -3 < \sigma < -2$$

$$Y(s) = H(s) \cdot F(s)$$

not defined for any common  $\sigma$

So  $\boxed{y(t) = 0 \text{ for all } t}$

Convolution Property of L.T.

$$f(t) \leftrightarrow F(s)$$

$$h(t) \leftrightarrow H(s)$$

$$f(t) * h(t) \leftrightarrow F(s) \cdot H(s)$$

(1/19)

Q. Find the response of an L.T.I system with impulse response  $h(t) = e^{2t} u(t)$

for I/P  $f(t) = e^{3t} u(t)$

$$Y(s) = H(s) \cdot F(s) = \frac{1}{(s-2)(s-3)}$$

$$Y(s) = \frac{1}{s-3} - \frac{1}{s-2}$$

$$y(t) = e^{3t} u(t) - e^{2t} u(t) \quad \sigma > 3$$

$$y(t) = (e^{3t} - e^{2t}) u(t) \quad \text{Ans}$$

$$-e^{3t} u(-t) + e^{2t} u(-t)$$

Q. Find the response of a system with impulse response  $h(t) = e^{-t} u(t)$  for I/P  $f(t) = e^{-2|t|}$

$$Y(s) = \frac{1}{(s+1)(s^2-4)} \quad -1 < s < 2$$

$$Y(s) = \frac{-4}{(s+1)(s-2)(s+2)} \quad [-1 < s < 2]$$

$$= \frac{4}{3(s+1)} - \frac{1}{3(s-2)} - \frac{1}{(s+2)}$$

$$y(t) = \frac{4}{3} e^{-t} u(t) + \frac{1}{3} e^{2t} u(t) - e^{-2t} u(t) \quad \text{Ans}$$

$$e^{-2t} \frac{1}{s+2}$$

$$e^{-2t} u(t) + e^{2t} u(-t)$$

$$\frac{1}{s+2} - \frac{1}{(s-2)}$$

$$-2 < s < 2$$

Find I.L.T. of  $F(s) = \frac{\log s^2 + a^2}{(s^2 + b^2)}$  (20)

$$= \log s^2 + a^2 - \log s^2 + b^2$$

$$G(s) = \frac{dF(s)}{ds} = \frac{1 \cdot 2s}{s^2 + a^2} = \frac{2s}{s^2 + a^2}$$

$$g(t) = [2 \cos at \cdot u(t) - 2 \cos bt \cdot u(t)]$$

$$\therefore f(t) = -\star f(t) g(t) / t$$

$$f(t) = \frac{2}{t} [\cos bt - \cos at] u(t)$$

Am

$$t f(t) \rightarrow -\frac{d}{ds} F(s)$$

$$t f(t) \rightarrow -g(t)$$

$$f(s) = -\frac{g(t)}{t}$$

division by  $t$  property  $\rightarrow$

$$\frac{f(t)}{F} \Leftrightarrow \int_s^\infty F(s) ds$$

Find L.T.  $\frac{\sin t \cdot u(t)}{t} = \text{Sa}[t]$

$$= \int_s^\infty \frac{1}{(s^2 + 1)} ds = [\tan^{-1} s]_s^\infty$$

$$L\left[\frac{\sin t}{t}\right] = \frac{\pi}{2} - \tan^{-1} s = \cot^{-1} s$$

$\frac{d}{ds} \tan^{-1} s = \frac{1}{1+s^2}$   
 $\int \frac{1}{1+s^2} ds = \tan^{-1} s + C$   
 $\int_0^\infty \frac{1}{1+s^2} ds = \frac{\pi}{2}$

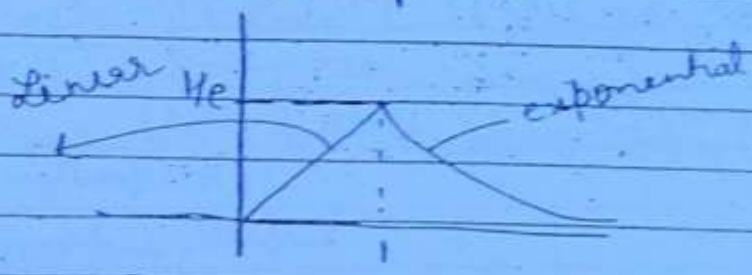
$$\frac{1}{(s-2)(s+3)^2} = \frac{1}{25(s-2)} + \frac{1}{25(s+3)} + \frac{1}{5(s+3)^2} \quad (12)$$

$$= \frac{1}{25} e^{2t} u(t) - \frac{1}{25} e^{-3t} u(t) - \frac{1}{5} e^{-3t} t u(t)$$

ROC ( $\sigma > 2$ )

Ans ✓

Q. Find L.T. of the following signal



$$f(t) = \frac{1}{e} t [u(t) - u(t-1)] + e^{-t} [u(t-1)]$$

$$= \frac{1}{e} \left[ \frac{1}{s^2} - \frac{e^{-s}}{s^2} - \frac{e^{-s}}{s} \right] + e^{-1} \frac{e^{-s}}{(s+1)}$$

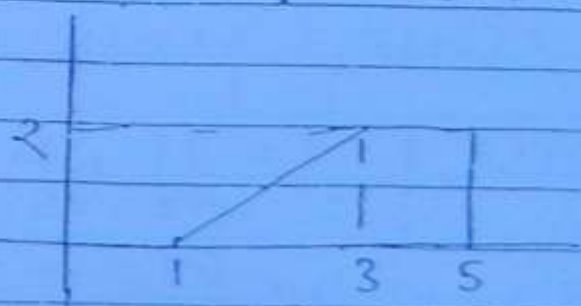
ROC  $\sigma > 0$  Ans ✓

$$= \frac{1}{e} \left[ \frac{1}{s^2} - \frac{e^{-s}}{s^2} - \frac{e^{-s}}{s} \right] + \frac{e^{-(s+1)}}{(s+1)}$$

$$= \frac{1}{e s^2} [1 - e^{-s} - s e^{-s}] + \frac{e^{-(s+1)}}{s+1} \quad \sigma > 0$$

Q. find L.T. of signal f(t) given below

Ans ✓



$$= \frac{e^{-s}}{s^2} - \frac{e^{-3s}}{s^2} + \frac{2}{s} e^{-3s} + \frac{2e^{-3s}}{s} - \frac{2e^{-5s}}{s} + \frac{2e^{-5s}}{s} [u(t-5) - u(t-5)]$$

$\sigma > 0$  as

Q. Find the I.L.T. of  $F(s) = \frac{e^{-(s+1)}}{s^2 - 2s + 5} = \frac{e^{-(s+1)}}{(s-1)^2 + 4}$

$= \frac{e^{-(s+1)}}{(s-1)^2 + 4}$

$\frac{e^{-1}}{2} \times \frac{e^{-1}}{2} \cdot e^t \sin 2(t-1) \cdot u(t-1)$  Ans

$\frac{1}{2} e^{-(t-2)} \sin 2(t-1) u(t-1)$  Ans,  $\sigma > 1$ , Causal system

$\frac{e^{-1} x e^t \sin 2(t-1) u(-t+1)}{2}$  Ans, Impulse response

$\frac{1}{2} e^{-(t-2)} \sin 2(t-1) u(-t+1) \rightarrow \sigma < 1$  (excluding  $-\infty$ ) corresponds to stable system's impulse response

Multiplication by t property

$f(t) \leftrightarrow F(s)$

$t^n f(t) \leftrightarrow (-1)^n \frac{d^n}{ds^n} F(s)$  ROC remains same

$t^n u(t) \leftrightarrow \frac{(-1)^n}{s^{n+1}} = \frac{(-1)^n}{s^{n+1}}$

Q. Find I.L.T. of  $F(s) = \frac{1}{(s-2)(s+3)^2}$

$= \frac{A}{s-2} + \frac{B}{s+3} + \frac{C}{(s+3)^2}$

$1 = A(s+3)^2 + B(s-2)(s+3) + C(s-2)$

$A = 1/25, \quad 1 = \frac{9}{25} + \frac{70}{25} - 6B$

$C = -1/5$

$6B = -\frac{6}{25} = -1/25$

Linearity:

Time shifting property  $\Rightarrow$

(123)

$$f(t) \leftrightarrow F(s)$$

$$f(t-t_0) \rightarrow e^{-st_0} F(s)$$

$$f(t+t_0) \rightarrow e^{+st_0} F(s)$$

$$\delta(t) \rightarrow \delta(t-t_0) \cdot 1$$

$$\delta(t-t_0) \rightarrow e^{-st_0} \text{ entire } s \text{ plane excluding } s \rightarrow \infty$$

$$\delta(t+t_0) \rightarrow e^{+st_0} \text{ entire } s \text{ plane including } s \rightarrow \infty$$

$$e^{-at} u(t) \rightarrow \frac{1}{s+a}, \sigma > -a$$

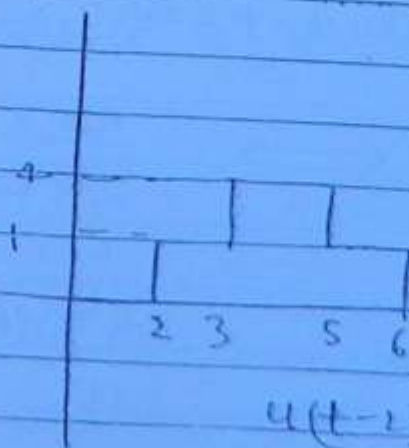
$$e^{-a(t-1)} u(t-1) \rightarrow \frac{1}{s+a} e^{-s}, \sigma > -a$$

$\therefore$  Shifting right will cancel the  $\sigma \rightarrow -\infty$  from ROC.

but  $-\infty$  is already excluded from ROC so ROC remains same

\* If a signal  $f(t)$  to represent impulse response of a <sup>causal</sup> stable system ROC of its Laplace transform must be right sided extending till  $\infty$ , including  $\sigma = \infty$ .

B) Find L.T. of  $f(t)$  shown below.



$$u(t-2) + 2u(t-3) - 3u(t-5)$$

$$+ u(t-6)$$

$$= \frac{e^{-2s}}{s} + \frac{2e^{-3s}}{s} - \frac{3e^{-5s}}{s} + \frac{e^{-6s}}{s}$$

\* For a given Laplace transform  $F(s)$ , we can define as many inverse L.T. as there are no. of ROC's.

No. of I.L.T.'s = No. of possible ROC. 124

Q How many inverse L.T. exist for  $F(s) = \frac{5}{(s+1)^2 (s-2) (s+3)^3}$ .

4 I.L.T. will exist.

for a given  $F(s)$  if there are  $n$  poles then there will be  $(n-1)$  two sided I.L.T. & 2  $\rightarrow$  one is right sided <sup>or finite duration</sup> & one is left sided <sup>or infinite duration</sup> so total  $(n+1)$  I.L.T. will exist.

Properties

$f_1(t) \rightarrow F_1(s)$   
 $f_2(t) \rightarrow F_2(s)$

$a f_1(t) + b f_2(t) \rightarrow a F_1(s) + b F_2(s)$   
 ROC  $\Phi$  ROC<sub>1</sub>  $\cap$  ROC<sub>2</sub>

(2)  $e^{j\omega_0 t} f(t) \rightarrow F(s + j\omega_0)$  ROC will remain same

(3)  $e^{-j\omega_0 t} f(t) \rightarrow F(s - j\omega_0)$  ROC will remain same.

$\frac{1}{2} e^{j\omega_0 t} u(t) + \frac{1}{2} e^{-j\omega_0 t} u(t)$   
 $\cos \omega_0 t u(t) \leftrightarrow \frac{s}{s^2 + \omega_0^2} \quad \sigma > 0$   
 $\sin \omega_0 t u(t) \leftrightarrow \frac{\omega_0}{s^2 + \omega_0^2} \quad \sigma > 0$

$$f(t) = \int_{\sigma - j\infty}^{\sigma + j\infty} \frac{1}{2\pi j} F(s) e^{st} ds$$

find inverse laplace transform of  $F(s) = \frac{1}{(s^2 + 5s + 6)}$

(25)

$$= \frac{1}{(s+3)(s+2)}$$

$$= \frac{1}{s+2} - \frac{1}{s+3}$$

$$= e^{-2t} u(t) - e^{-3t} u(t)$$

Ans  $\sigma > -2$

$$\text{or } -e^{-2t} u(-t) + e^{-3t} u(-t)$$

$\sigma < -3$

Ans

$$\text{or } -e^{-2t} u(t) - e^{-3t} u(t)$$

ROC

$$-3 < \sigma < -2$$

Q. Find I.L.T. of the above  $F(s)$  if  $s = -\frac{1}{2} + j\frac{3}{2}$  is in ROC. i.e. L.T. is defined.

$$f(t) = e^{-2t} u(t) - e^{-3t} u(t) \quad \text{Ans}$$

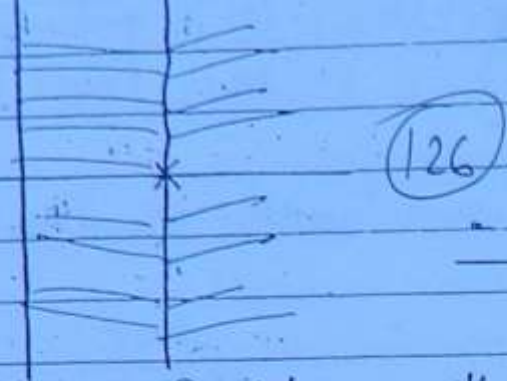
$$(\sigma > -2)$$

~~$$* \text{ at } -\frac{1}{2} + j\frac{3}{2}$$~~

(\*) at  $s = -\frac{1}{2} + j\frac{3}{2}$  for L.T. to be defined this must be present in ROC.



Q.  $f(t) \rightarrow F(s)$



(126)

a signal  $f(t)$  has Laplace transform  $F(s)$  with exactly two poles at  $s = -2$  &  $s = +1$ . Another signal  $g(t)$  is defined as  $g(t) = e^{3t} f(t)$ , if  $g(t)$  can represent impulse response of a stable system  $f(t)$  is

$\downarrow$  if  $e^{3t} f(t)$  is stable  $\rightarrow$  left sided  $\rightarrow$  Right sided if  $(e^{-3t} f(t))$  is stable  
 New poles  $1$   $\rightarrow e^{3t} f(t)$   
 New poles  $-5$   $\rightarrow e^{-3t} f(t)$

Q. Repeat the above question if  $g(t)$  is defined as  $g(t) = e^{-t} f(t)$

Q. New poles  $-3$   $0$   
 (a)  $g(t)$  can't define impulse response of a stable system

$$F(\sigma + j\omega) = F(s) = \text{F.T.} [f(t) e^{-\sigma t}]$$

$$f(t) e^{-\sigma t} = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\sigma + j\omega) e^{+j\omega t} d\omega$$

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(s) e^{st} d\omega$$

$$f(t) = \frac{1}{2\pi} \int_{-j\infty}^{j\infty} F(s) e^{st} ds$$

$$f(t) = \frac{1}{2\pi} \int_{-j\infty}^{j\infty} F(s) e^{st} ds$$

⊛ Combination of right sided signal & left sided signal which can be called as two sided signal. It will have finite stripe in ROC bounded on the lower side by the greatest poles of all right sided signal and on the higher side by least poles all the left sided signals.

(127)

$$e^{2t} u(t) + e^{5t} u(t) + e^{-2t} u(t) + e^{-5t} u(t)$$

$$\frac{1}{(s-2)} + \frac{1}{(s-5)} + \frac{-1}{(s+2)} + \frac{-1}{s+5}$$

$$\sigma > 2 \quad \sigma > 5 \quad \sigma < -2 \quad \sigma < -5$$

does not exist because no common values of  $\sigma$  for which all laplace transform exist

laplace transform of a dc. sign  $f(t) = 1$

$$= \int_{-\infty}^{\infty} |e^{-\sigma t}| dt < \infty \rightarrow \text{not possible}$$

this condition will not be satisfied for any  $\sigma$  therefore laplace transform does not exist

$\text{Sym}(t) \Leftrightarrow$  not defined

$$f(t) \cdot e^{-b|t|} = e^{-bt} u(t) + e^{bt} u(-t)$$

$$\text{L.T.} = \frac{1}{s+b} - \frac{1}{(s-b)} = \frac{-2b}{(s^2 + b^2)}$$

$$\sigma > -b \quad \sigma < b = \frac{2b}{(b^2 - s^2)}$$

ROC  $\rightarrow -b < \sigma < b$   
 $b > 0$  thus it is possible

$$e^{at} [u(t) - u(t-1)] = \frac{e^{as}}{(s-a)} - \frac{e^{-as}}{(s-a)} \rightarrow$$

any pole, so all the poles of Laplace transform of impulse response of such a causal & stable system must be lying on the left of s-plane.

$$e^{2t} u(t) = \frac{1}{(s-2)} \quad \text{[28]}$$

$$e^{2t} u(t) + e^{5t} u(t) \rightarrow \frac{1}{(s-2)} + \frac{1}{(s-5)} \quad \text{ROC } \sigma > 5$$

(\*) Combination of any no. of right sided signal will always have defined Laplace transform, which is some of all the individual Laplace transform with an ROC which is right sided bounded by greatest among all the poles.

$$- e^{2t} u(t) = \frac{1}{(s-2)} \quad \boxed{\text{Re}(s) < 2} \quad \text{ROC } \sigma < 2$$

(\*) Any combination of left sided signals will have a defined Laplace transform, which is some of all individual Laplace transforms with an ROC which is left sided bounded by least among all the poles.

$$(*) f(t) = e^{-2t} u(t) + e^{-5t} u(t) + e^{2t} u(t) + e^{5t} u(t)$$

$$\frac{1}{s+2} + \frac{1}{s+5} - \frac{1}{(s-2)} - \frac{1}{(s-5)} \quad \text{[10]}$$

$$\text{Re}(s) > -2 \quad \text{Re}(s) > -5 \quad \text{Re}(s) < 2 \quad \text{Re}(s) < 5$$

$$s > -2, \quad s < 2$$

$$-2 < \text{Re}(s) < 2$$

$$-2 < \sigma < 2$$

if it is causal  $h(t) = 0 \quad t < 0$

right sided signal

729

and Laplace transform for right sided signal is  
right has ROC <sup>which should be</sup> right sided.

(\*) If system is both stable & causal then ROC must be right sided & include  $\sigma = 0$  line and it can't include any poles. So for system to be causal & stable all the poles must lie on left half of  $S$  plane ( $\therefore$  ROC will be right side to poles having highest  $\sigma$ ).

(\*) ROC of left sided signal is also left sided

(\*) if F.T. of a signal is to be defined Laplace transform of corresponding must be having an ROC including  $\sigma = 0$  line or  $j\omega$  axis and corresponding F.T. can be obtained by replacing  $S$  in Laplace transform expression by  $j\omega$ .

(\*) A system with impulse response  $h(t)$  is called a stable system if  $\int_{-\infty}^{\infty} |h(t)| dt < \infty$  which is the same

condition for the F.T. of  $h(t)$  to be defined. So

if a system with impulse response  $h(t)$  is to be a stable system it must be having a Laplace transform with its ROC including  $\sigma = 0$  line

(\*) If a system with impulse response  $h(t)$  is to be causal  $h(t) = 0 \quad t < 0$  i.e.  $h(t)$  must be generally right sided. So if a system with impulse response  $h(t)$  is to be causal its Laplace transform must be having an ROC which is right sided extending till  $\sigma = \infty$

(\*) If a system with impulse response is to be both causal and stable ROC must be right sided including  $\sigma = 0$  line.

Calculate Laplace T.  $-u(-t) = 1/s$  ROC  $\sigma < 0$

~~(\*)~~

$f(t) \rightarrow F(s)$   $\text{Re}\{s\}$

(130)

$e^{at} f(t) \rightarrow F(s-a)$   $\text{Re}\{s-a\}$

$e^{-at} u(t) \leftrightarrow \frac{1}{(s+a)}$   $\text{Re}\{s+a\} > 0$   
 $\text{Re}\{s+a\} > 0$   
 $\sigma > (-a)$

$e^{at} u(t) \rightarrow \frac{1}{(s-a)}$   $\sigma > a$   
 $\text{Re}\{s-a\} > 0$

$-u(-t) \rightarrow \frac{1}{s}$   $\text{Re}\{s\} < 0$

$-e^{-at} u(-t) \rightarrow \frac{1}{(s+a)}$   $\text{Re}\{s+a\} < 0$  ROC  
 $\sigma < -a$  ROC

$-e^{at} u(t) \leftrightarrow \frac{1}{(s-a)}$   $\text{Re}\{s-a\} < 0$   
 $\sigma < a$

(\*) For a system having impulse response  $h(t)$ , and having Laplace transform  $H(s)$ , for system to be stable, ROC of  $H(s)$  must include  $\sigma = 0$  line for stability

$$\int_{-\infty}^{\infty} |h(t)| dt < \infty$$

this is also condition for F.T. to exist and from Laplace transform we can get F.T. only if  $\sigma = 0$  line is included in its ROC.

So if it includes  $\sigma = 0$  in its ROC, then F.T. exists and system will be stable

F.T. means which can be directly found by integration

transform is defined. This region of  $\sigma$  value is called as region of convergence [ROC].

We specify ROC for the Laplace transform in terms of  $\sigma$  or real part of  $s$ .

(3)

Find Laplace T.  $f(t) = \delta(t)$

$$L[f(t)] =$$

$$\int_{-\infty}^{\infty} |f(t) e^{-\sigma t}| dt < \infty$$

$$\int_{-\infty}^{\infty} |\delta(t) e^{-\sigma t}| dt < \infty$$

$$\text{for all } \int_{-\infty}^{\infty} \delta(t) dt = 1 < \infty$$

for all values of  $\sigma$  Laplace transform will be defined.

$$L[\delta(t)] = 1 \quad \text{ROC} \rightarrow \text{all value of } \sigma$$

Laplace transform of  $u(t)$ .

$$\int_{-\infty}^{\infty} |f(t) e^{-\sigma t}| < \infty$$

$$\int_{-\infty}^{\infty} |u(t) e^{-\sigma t}| < \infty$$

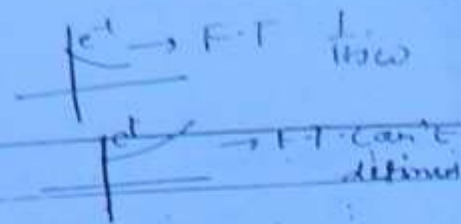
for ~~all~~  $\sigma > 0$

$$\int_0^{\infty} |e^{-\sigma t}| < \infty$$

for  $\sigma > 0 \rightarrow$  this integral converges

$$L[u(t)] = \int_0^{\infty} e^{-st} dt = \frac{1}{s} \quad \text{POC}$$

but  $F(s)$  must be converging.



$$|F(s)| < \infty$$

(132)

$$\left| \int_{-\infty}^{\infty} f(t) e^{-st} dt \right| < \infty \quad \rightarrow (s = \sigma + j\omega)$$

$$\int_{-\infty}^{\infty} |f(t) e^{-\sigma t}| dt < \infty$$

condition to find ROC.

$\sigma$  is real part of  $s$

$\text{Re}\{s\} \rightarrow \sigma$  ROC is defined in terms of  $\text{Re}\{s\}$ .

(\*) For a signal  $f(t)$  Laplace transform is defined

$$X = \int_{-\infty}^{\infty} f(t) e^{-st} dt$$

where  $s$  is a complex variable and is equal to  $(\sigma + j\omega)$ .  
So if we substitute  $\sigma = 0$  in Laplace transform, it is equivalent to F.T. or Laplace transform is more general form of F.T.

(\*) We can also understand Laplace transform as  $\int_{-\infty}^{\infty} [f(t)] e^{-\sigma t}$  where  $\sigma$  is called damping factor.

(\*) For a Laplace transform to be defined, Laplace transform integral must be converging

i.e.

$$\int_{-\infty}^{\infty} |f(t) e^{-st}| dt < \infty$$

$$\int_{-\infty}^{\infty} |f(t) e^{-\sigma t}| dt < \infty \quad (\because |e^{-j\omega t}| = 1)$$

So based on the nature of the given signal  $f(t)$ , there will be a region of  $\sigma$ -values for which the Laplace transform is defined.

Q. Repeat the previous problem for i/f PSD

$$PSD_{i/f} = K$$

$$= \frac{1}{2\pi} K \int_{-\infty}^{\infty} \frac{1}{1+\omega^2} d\omega$$

(133)

$$P_y \left[ \frac{PSD}{2\pi} = K/2 \right]$$

$$\text{input power} = \frac{1}{2\pi} \int_{-\infty}^{\infty} K d\omega$$

$$P_c = \infty$$

energy

if  $f(t)$ ,  $g(t)$  are complex valued signal

$$R_{fg}(\tau) = \int_{-\infty}^{\infty} f(t) g^*(t-\tau) dt$$

$$R_{ff}(\tau) = \int_{-\infty}^{\infty} f(t) f^*(t+\tau) dt$$

if  $f(t)$  &  $g(t)$  are complex valued power signal

$$R_{fg}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} f(t) g^*(t-\tau) dt$$

$$R_{ff}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} f(t) f^*(t-\tau) dt$$

$$R_{ff}(\tau) = \int_{-T/2}^{T/2} f(t) f^*(t-\tau) dt$$

periodic with period T

Laplace transform :->

we can choose  
σ value  
property

for a  $f(t)$  if F.T. is not defined

$f(t)e^{-\sigma t}$  by multiplying a exponential  
then F.T.

$$F(s) = \int_{-\infty}^{\infty} f(t) e^{-(s+j\omega)t} dt = \int_{-\infty}^{\infty} f(t) e^{-st} dt$$



Q. Calculate the PSD of the signal  $f(t) = A \sin(\omega_0 t + \phi)$

$$R(\tau) = \frac{A^2 \cos \omega_0 \tau}{2}$$

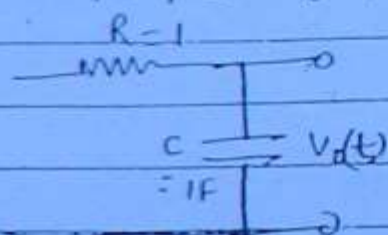
(134)

$$F[R(\tau)] = \frac{A^2}{2} [\pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)]$$

$$\begin{aligned} \text{Total power} &= \frac{1}{2\pi} \int_{-\infty}^{\infty} (\text{PSD}) d\omega = \frac{1}{2\pi} \frac{A^2 \pi}{2} \left[ \int_{-\infty}^{\infty} \delta(\omega - \omega_0) d\omega + \int_{-\infty}^{\infty} \delta(\omega + \omega_0) d\omega \right] \\ &= \frac{A^2}{4} [1+1] \\ &= A^2/2 \end{aligned}$$

Q. RC system given below is given an i/p signal whose power spectral density is known to be

$$\text{PSD}_x = \pi [\delta(\omega - 1) + \delta(\omega + 1)]$$



$$H(\omega) = \frac{1}{j\omega + 1}$$

find Power at o/p of system

$$P_{\text{out}} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \text{PSD}_x \cdot |H(\omega)|^2 d\omega$$

$$\text{PSD}_y = \text{PSD}_x |H(\omega)|^2$$

for LTI system

$$P = \frac{1}{2\pi} \int_{-\infty}^{\infty} \pi [\delta(\omega - 1) + \delta(\omega + 1)] \frac{1}{(\omega^2 + 1)} d\omega$$

$$= \frac{1}{2} \left[ \int_{-\infty}^{\infty} \delta(\omega - 1) \frac{1}{2} d\omega + \int_{-\infty}^{\infty} \delta(\omega + 1) \frac{1}{2} d\omega \right]$$

$$P = \frac{1}{2} \left[ \frac{1}{2} + \frac{1}{2} \right] = 1/2 \text{ watt}$$

Ans

$$f(t) = A \cos(\omega_0 t + \phi) \rightarrow \text{Autocorrelation function.}$$

(135)

$$= \frac{1}{(2\pi/\omega_0)} \int_{-\pi/\omega_0}^{\pi/\omega_0} A^2 \cos(\omega_0 t + \phi) \cdot \cos[\omega_0 t + \phi - \omega_0 \tau] dt$$

$$= \frac{A^2 \omega_0}{2\pi} \left[ \int_{-\pi/\omega_0}^{\pi/\omega_0} \left[ \cos^2(\omega_0 t + \phi) \cos \omega_0 \tau - \cos(\omega_0 t + \phi) \sin(\omega_0 t + \phi) \sin \omega_0 \tau \right] dt \right]$$

$$= \frac{A^2 \omega_0}{2\pi} \left[ \int_{-\pi/\omega_0}^{\pi/\omega_0} \cos^2(\omega_0 t + \phi) \cos \omega_0 \tau dt \right]$$

$$= \frac{A^2 \omega_0}{2\pi} \left[ \cos \omega_0 \tau \left[ t + \phi + \frac{\sin 2(\omega_0 t + \phi)}{2\omega_0} \right] \right]_{-\pi/\omega_0}^{\pi/\omega_0}$$

$$= \frac{A^2 \omega_0 \cos \omega_0 \tau}{2\pi} \cdot \omega_0 \times \frac{2\pi}{\omega_0}$$

$$R(\tau) = \frac{A^2}{2} \cos \omega_0 \tau$$

for  $A \sin(\omega_0 t + \phi)$

$$\hookrightarrow R_{ff}(\tau) = \frac{A^2}{2} \cos \omega_0 \tau$$

Properties of Autocorrelation  $\rightarrow$

①  $R(\tau) = R(-\tau)$  - even

②  $R(0) \geq R(\tau)$

③  $R(0)$  - Power of the signal

④  $F[R(\tau)] \rightarrow$  PSD of  $f(t)$

⑤  $R(\tau)$  is also periodic if  $f(t)$  is periodic and period will be same as  $f(t)$

Calculate

Property of Autocorrelation function  $\rightarrow$

$R(\tau)$  is even

136

$$R(\tau) = R(-\tau)$$

②  $R(0) > R(\tau)$

③  $R(0) = E_f$

④  $R(\tau) \rightarrow 0$   
 $\tau \rightarrow \infty$

⑤  $F[R(\tau)] = \text{ESD}_f = F(\omega) F^*(\omega)$

⑥  $R_{fg}(\tau) \Rightarrow F(\omega) \cdot G^*(\omega)$

⑦  $R_{fg}(\tau) = R_{gf}(-\tau)$

⑧  $R_{ff}(\tau) = R_{ff}(-\tau)$

\* when  $f(t), g(t)$  are power signal

$$R_{fg}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} f(t) g(t-\tau) dt$$

$$R(\tau) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} f(t) f(t-\tau) dt$$

for periodic signal

$$R_{ff}(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} f(t) f(t-\tau) dt$$

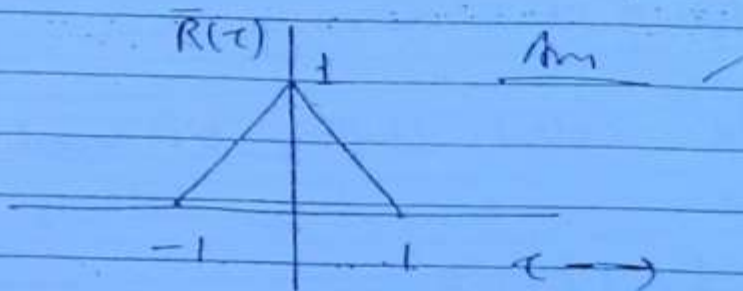
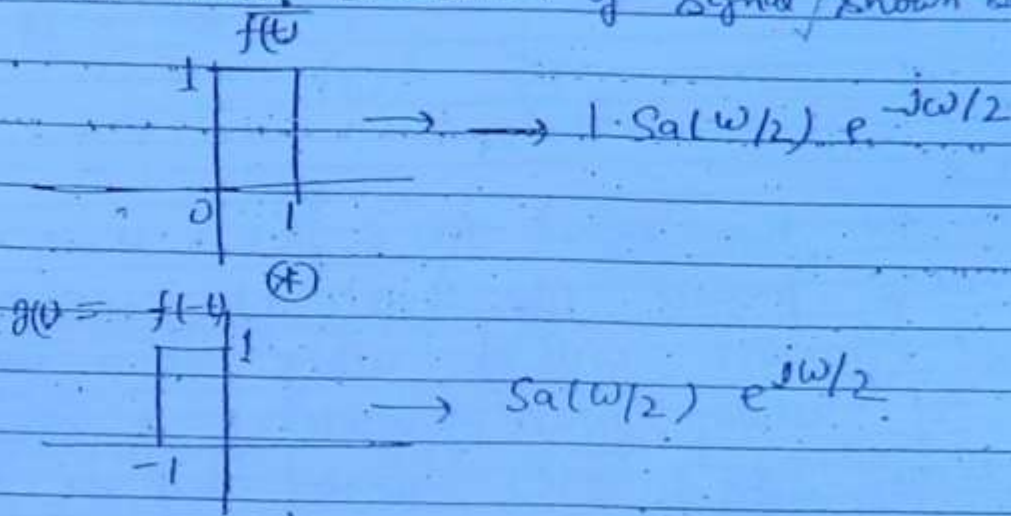
T is period of periodic signal

$$R(\tau) = \int_{-\infty}^{\infty} f(t) f(t-\tau) dt$$

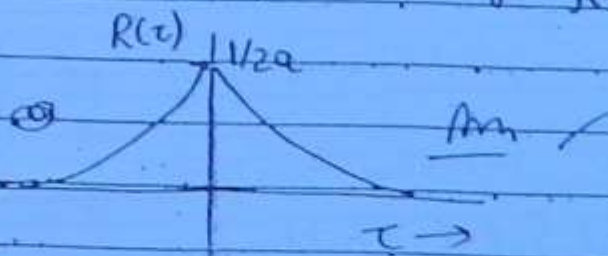
$$R(\tau) = [f(t) \otimes f(-t)]_{t=\tau}$$

(137)

Q. Find the auto correlation of signal shown below.



Q. Find auto correlation function of  $f(t) = e^{-at} u(t)$ .



$$f(-t) = e^{at} u(t)$$

$$F [e^{-at} \otimes e^{at} u(t)] = \frac{1}{(a-jw)} \cdot \frac{1}{(a+jw)}$$

$$= \frac{1}{(a^2 + w^2)}$$

$$R(t) \rightarrow \frac{e^{-a|t|}}{2a} \rightarrow R(\tau) \rightarrow \frac{e^{-a|\tau|}}{2a}$$

$$-2a\omega_c = \ln 0.1$$

$$2a\omega_c = \ln 10$$

$$\omega_c = \frac{\ln 10}{2a} \text{ rad/sec}$$

(138)

Correlation →

for two signal  $f(t)$  &  $g(t)$ , if we take area under product  $f(t)$  &  $g(t-\tau)$  will be larger or smaller will be acting as a major measure of relation b/w  $f(t)$  &  $g(t-\tau)$  & correlation of the signal  $f(t)$  &  $g(t)$  denoted by the symbol

$$R_{fg}(\tau) = \int_{-\infty}^{\infty} f(t) g(t-\tau) dt$$

$\tau \rightarrow$  can be called shifting -  $\Rightarrow$  searching parameter

$$R_{fg}(\tau) = \left[ f(t) \otimes g(-t) \right]_{(t=\tau)}$$

$$f(\tau) g(-\tau + \tau)$$

$$g(-\tau)$$

$$f(\tau) g(\tau)$$

$$f(t) * g(-t)$$

$$* R(\tau) = \int_{-\infty}^{\infty} f(t) f(t-\tau) dt$$

The above correlation integral

The cross correlation of  $f(t)$  &  $g(t)$  defined above

is mathematically similar in it's evaluation to

the convolution of signal  $f(t)$  &  $g(t)$

if  $g(t)$  is happen to an even signal, functionally

cross correlation & convolution will be same.

The above correlation if  $g(t) = f(t)$  we can define

it as autocorrelation denoted by the symbol  $R(\tau)$

Q. An ideal L.P.F. is given an i/p  $f(t) = \frac{2a}{a^2+t^2}$  if

the response is to have 90% of the i/p Find B.W L.P.F.

~~Q = 2a~~

(139)

$$f(t) = \frac{2a}{a^2+t^2}$$

$$\frac{1}{(a+j\omega)}$$

$$e^{-at} u(t) \otimes e^{at} u(t) \rightarrow \frac{1}{(a+j\omega)}$$

$$e^{-at} u(t) \otimes e^{at} u(t) \rightarrow \frac{1}{(a+j\omega)} \cdot \frac{1}{(a-j\omega)}$$

$$\rightarrow \frac{1}{a^2+\omega^2}$$

$$e^{-a|t|} \rightarrow \frac{2a}{a^2+\omega^2}$$

$$\frac{2a}{a^2+\omega^2} \xrightarrow{\text{F.T.}} 2\pi e^{-a|\omega|}$$

$$\text{ESDF} = |2\pi e^{-a|\omega|}|^2$$

$$= 4\pi^2 e^{-2a|\omega|}$$

$$\therefore \frac{4\pi^2}{2\pi} \int_{-\infty}^{\infty} e^{-2a|\omega|} d\omega = 2\pi \left[ \left\{ \frac{1}{2a} (1) \right\} + \frac{1}{2a} \right]$$

$$E_f = \frac{2\pi}{a}$$

$$\frac{2\pi}{a} \times 0.9 = \frac{1}{2\pi} \int_{-w_c}^{w_c} 4\pi^2 e^{-2a|\omega|} d\omega$$

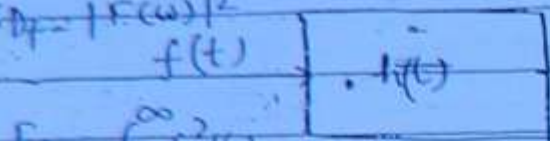
$$\frac{0.9}{a} = \frac{1}{2\pi} \left[ 1 - e^{-2aw_c} \right] + \frac{1 - e^{-2aw_c}}{2\pi}$$

$$1.8 = 2 - 2e^{-2aw_c} \quad \therefore e^{-2aw_c} = 0.2$$

\* When the two signals are multiplied the B.W. of resultant signal is equal to some of B.W. of individual signal being multiplied.

(140)

$$ESD_f = |F(\omega)|^2$$



$$y(t) = f(t) \otimes h(t)$$

$$E_f = \int_{-\infty}^{\infty} f^2(t) dt$$

$$ESD_y = |Y(\omega)|^2 = |F(\omega)|^2 \cdot |H(\omega)|^2$$

$$E_f = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(\omega)|^2 d\omega$$

$$ESD_y = ESD_f \cdot |H(\omega)|^2$$

not given assume ideal

\* Q An ideal L.P.F. with cutoff frequency 1 rad/sec is given an i/p  $e^{-t}u(t)$ , calculate energy at response of the system

$$\left[ \begin{array}{l} \text{energy at i/p} \\ = 1/2 J \end{array} \right]$$

$$|F(\omega)|^2 = \frac{1}{1+\omega^2} = ESD_f$$

$$ESD_y = ESD_f \cdot |H(\omega)|^2$$

$$ESD_y = \frac{1}{1+\omega^2} \cdot 1 \quad \text{for } 0 < \omega < 1$$

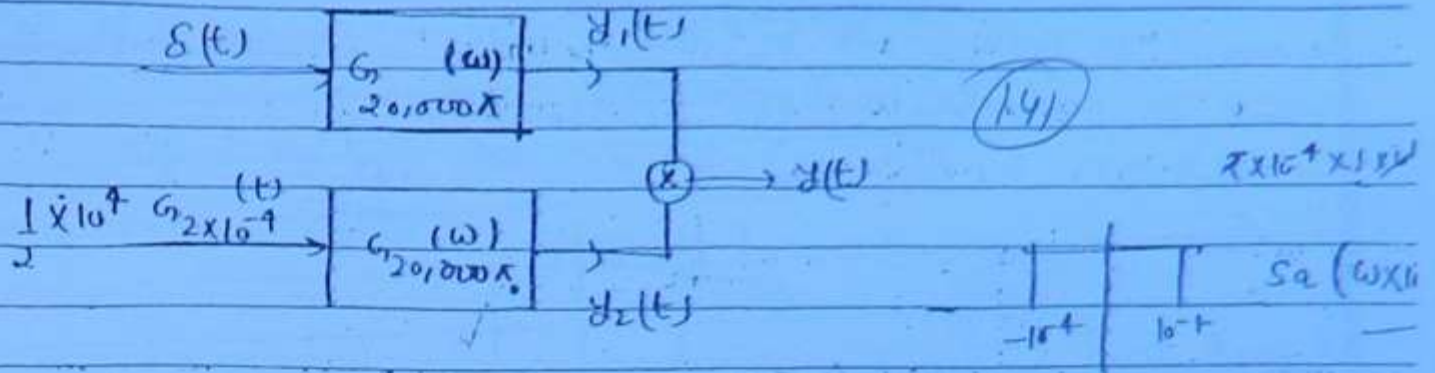
$$E_y = \frac{1}{2\pi} \int_{-\infty}^{\infty} ESD_y d\omega$$

$$= \frac{1}{2\pi} \int_{-1}^1 \frac{1}{1+\omega^2} d\omega$$

$$= \frac{1}{2\pi} (\tan^{-1} \omega)_{-1}^1$$

$$E_y = \frac{1}{2\pi} \cdot \frac{2\pi}{4} = \frac{1}{4} J$$

Ans



$$Y_1(\omega) = G_{20,000\pi}(\omega)$$

$$Y_2(\omega) = Sa(\omega \times 10^{-4}) \times G_{20,000\pi}(\omega)$$

$$= Sa(\omega \times 10^{-4}) \text{ from } -10,000\pi \rightarrow 10,000\pi$$

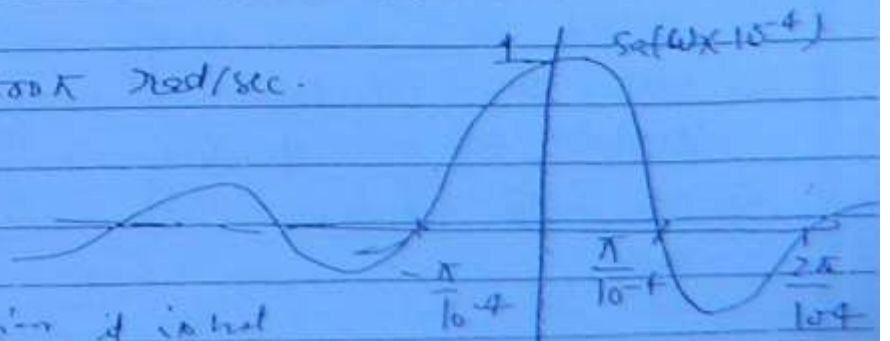
B.W.  $y_1(t) = 10,000\pi \text{ rad/sec}$

$$= \frac{10,000\pi}{2\pi} = 5000 \text{ or } 5000 \text{ rad Hz}$$

B.W.  $y_2(t) = 10,000\pi \text{ rad/sec}$

$$\left\{ \begin{array}{l} |Y_2(\omega)| \geq \frac{1}{\sqrt{2}} \\ \left| \frac{\sin \omega \times 10^{-4}}{\omega \times 10^{-4}} \right| \geq \frac{1}{\sqrt{2}} \\ \omega \times 10^{-4} \text{ can be } > \frac{1}{\sqrt{2}} \end{array} \right. \quad \begin{array}{l} \sin x \gg \left(\frac{1}{\sqrt{2}}\right) \\ \frac{\sin x}{2} \gg \left(\frac{1}{\sqrt{2}}\right) \\ 2 \gg \left(\frac{\pi}{\sqrt{2}}\right) \end{array}$$

B.W.  $y(t) = 20,000\pi \text{ rad/sec}$



there is a question if input

is let us calculate B.W. B.W. are not frequency absolute B.W.



$$\text{Total enrgy} = 1/2 a$$

$$\therefore \frac{1}{4a} = \int_0^{\infty} \frac{e^{-2at} dt}{2\pi}$$

(142)

$$= \frac{1}{2a^2}$$

$$F(\omega) = \frac{1}{a + j\omega}$$

$$\frac{1}{4a} = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} \frac{1}{(a^2 + \omega^2)} d\omega$$

$$\frac{1}{2 \cdot 4a} = \frac{1}{2\pi} \left[ \frac{1}{a} \tan^{-1} \frac{\omega}{a} \right]_{-\omega_c}^{\omega_c}$$

$$\frac{\pi}{2} = \tan^{-1} \frac{\omega_c}{a} + \tan^{-1} \frac{\omega_c}{a}$$

$$\pi/2 = 2 \tan^{-1} \frac{\omega_c}{a}$$

$$\frac{\omega_c}{a} = 1$$

$$\omega_c = a \text{ rad/sec Am}$$

$$\omega_c =$$

$$f_c = \frac{a}{2\pi} \text{ Hz}$$

\* The above  $\omega_c$  value calculated can also be called as 50% energy B.W. of the signal likewise we can calculate % energy B.W. for the above signal for the specified energy required.

Q. In the following setup calculate the B.W. of signal  $x_1(t)$ ,  $x_2(t)$  &  $x_3(t)$

→ means significant frequencies present in signal

B.W. of a signal: The width of the group of frequencies for which the magnitude spectrum of a given signal is not zero is defined as B.W. of signal.

$$f(t) = \text{Sa}(t) \xrightarrow{\text{FT}}$$

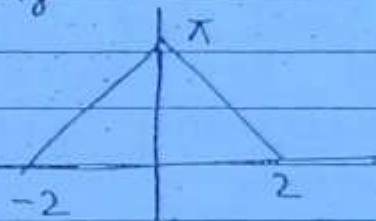


(143)

$$\text{B.W.} = 1 \text{ rad/sec}$$

$$= \frac{1}{2\pi} \text{ Hz}$$

$$\text{Sa}^2(t) \xrightarrow{\text{FT}}$$



$$\text{B.W.} = 2 \text{ rad/sec}$$

$$= \frac{1}{\pi} \text{ Hz}$$

$$f(t) = e^{-at} u(t)$$

$$\frac{-i}{a+i\omega}$$

$$|F(\omega)| = \frac{1}{a}$$



B.W. ideally  $= \infty$ .

$$|F(\omega)| = \frac{1}{\sqrt{a^2 + \omega^2}}$$

$$\frac{1/a}{\sqrt{1 + \omega^2/a^2}}$$

$$\text{at } \omega = a \rightarrow |F(\omega)| = \frac{1}{\sqrt{2}} \left( \frac{1}{a} \right)$$

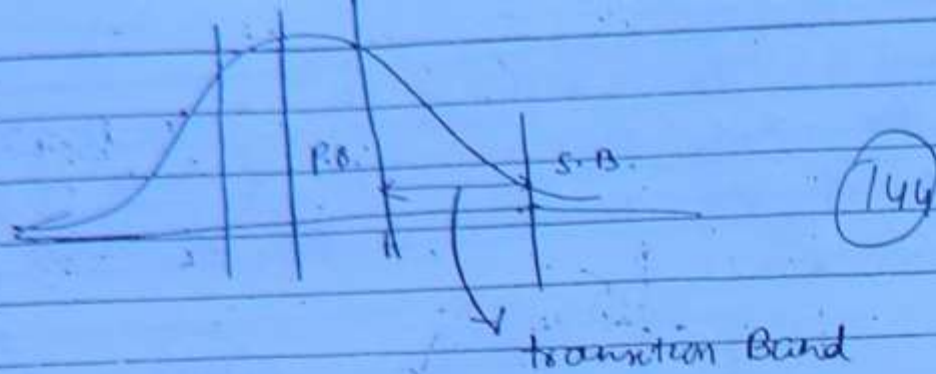
$$\text{B.W.} = a \text{ rad/sec}$$

3d.B B.W. of signal.

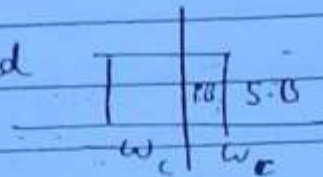
$$= \frac{a}{2\pi} \text{ Hz} \quad \text{Ans}$$

\* 3d.B B.W. of a signal, the width the group of frequencies for which  $|F(\omega)| \geq \frac{1}{\sqrt{2}} |F(\omega)|_{\text{max}}$

Q. for a signal  $f(t) = e^{-at} u(t)$ , calculate the range of frequencies to be considered such that these frequencies considered contribute 50% total energy of signal.



△ Ideal L.P.F. has no transition band



\* Ideal filters have sharp cutoff frequencies separating the pass band & stop band where as practical filters have a group of frequencies separating pass band & stop band defined transition band. Moreover the magnitude response of practically possible system can't be ~~max~~ maximum absolutely flat over a range of frequency rather it can be zero for a range of frequency. ideally speaking B.W. of the above system is ∞ but it is

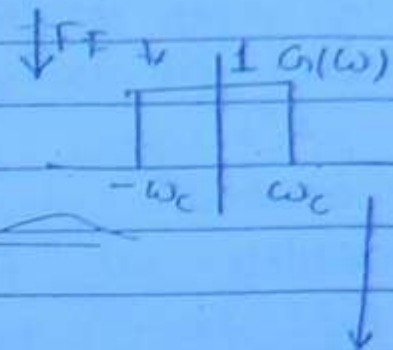
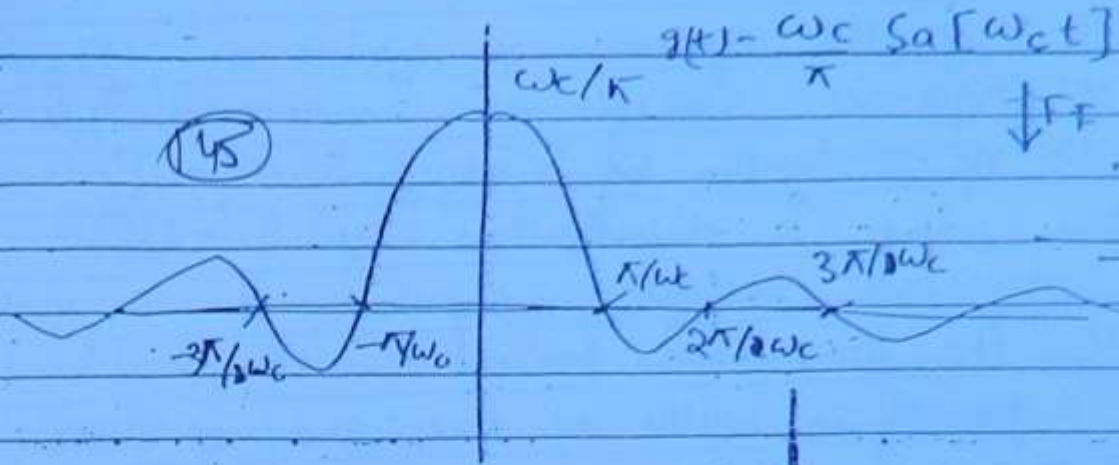
$|H(\omega)| > \frac{1}{\sqrt{2}} |H(\omega)|_{\max}$ , easily seen that this system is capable of making available only the frequency for which

\* For all practical purposes  $|H(\omega)| > \frac{1}{\sqrt{2}} |H(\omega)|_{\max}$  at the O/P. C.F. Lower group of frequency of i/p

\* For all practical purposes we define the width of these group of frequencies as 3dB B.W. of the system where 3dB B.W. is defined as width of those group of frequencies for which  $|H(\omega)| \geq \frac{1}{\sqrt{2}} |H(\omega)|_{\max}$ .

$$B.W. = \omega = \frac{1}{2\pi RC} \quad \text{--- } \frac{1}{RC} \text{ Radians/Sec}$$

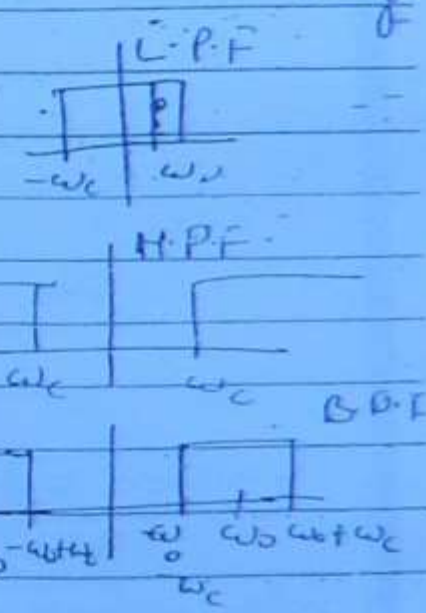
(45)



ideal system  
we can't realize physically

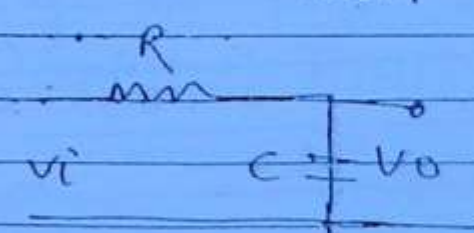
$h(t) \neq 0 \quad t < 0$   
non causal  
So we can't realize this system physically.

all are ideal systems not possible

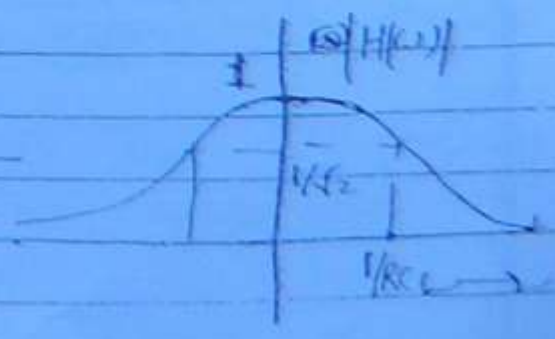


$$= \frac{1}{sC} \frac{x}{R + 1/sC}$$

$$H(\omega) = \frac{1}{RCs + 1} = \frac{1}{j\omega RC + 1}$$



$$|H(\omega)| = \frac{1}{\sqrt{\omega^2 R^2 C^2 + 1}}$$



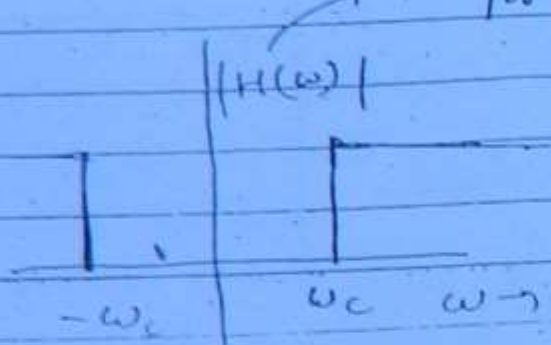
$\omega \ll 1/RC \rightarrow |H(\omega)| = 1$

$\omega \gg 1/RC \rightarrow |H(\omega)| \rightarrow 0$

\* Bandwidth of the system is defined as the width of group of frequencies which are made available at the O/P of a system by a system. (146)

A system which is distortionless system has a constant magnitude response imply that it can make available all the frequencies present in the I/P at the O/P right from 0 to  $\infty$ . So width of these group of frequencies is  $\infty$ . Hence  $BW = \infty$

ans for a real  $h(t)$



$$|H(w)| \quad H(w)$$

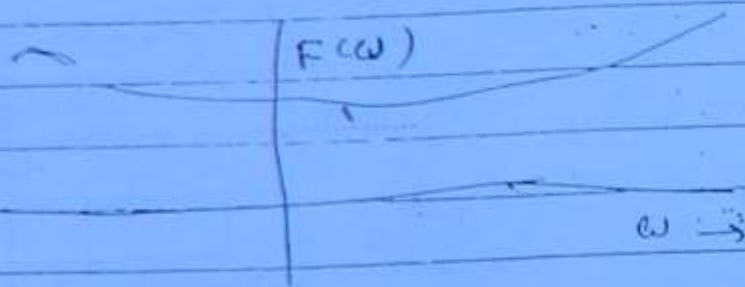
cs will be always

even

$$|H(w)| = \sqrt{H_R^2 + H_I^2}$$

$\downarrow$  (even)<sup>2</sup> +  $\downarrow$  (odd)<sup>2</sup>  
+ve +ve  
+ve

$H_R$  is even compo  
 $H_I$  is odd compo  
for  $h(t)$  to be real



$$\therefore |H(w)| = \sqrt{H_R^2 + H_I^2}$$

$H_R \rightarrow$  even function of  $w$

$H_I \rightarrow$  (odd function)

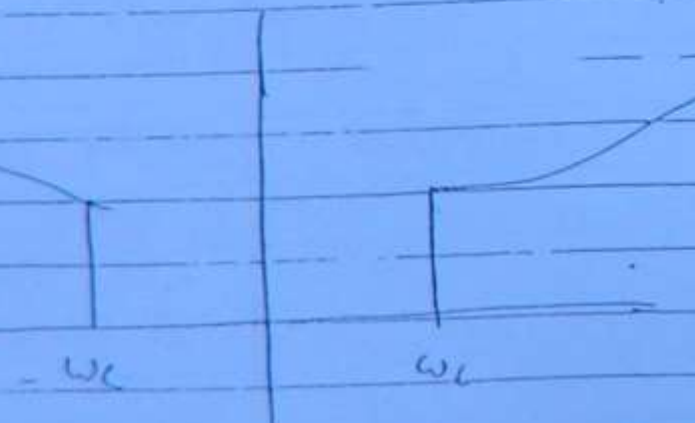
= even fun

$\therefore |H(w)| \rightarrow$  even fun of  $w$

$B.W = \infty$  so for a

real  $h(t)$

$|H(w)|$  will be always symmetric about  $w$ -axis.



$$H(\omega) =$$

$h(t) = A \delta(t - t_0) \rightarrow$  for a distortionless transmission system.

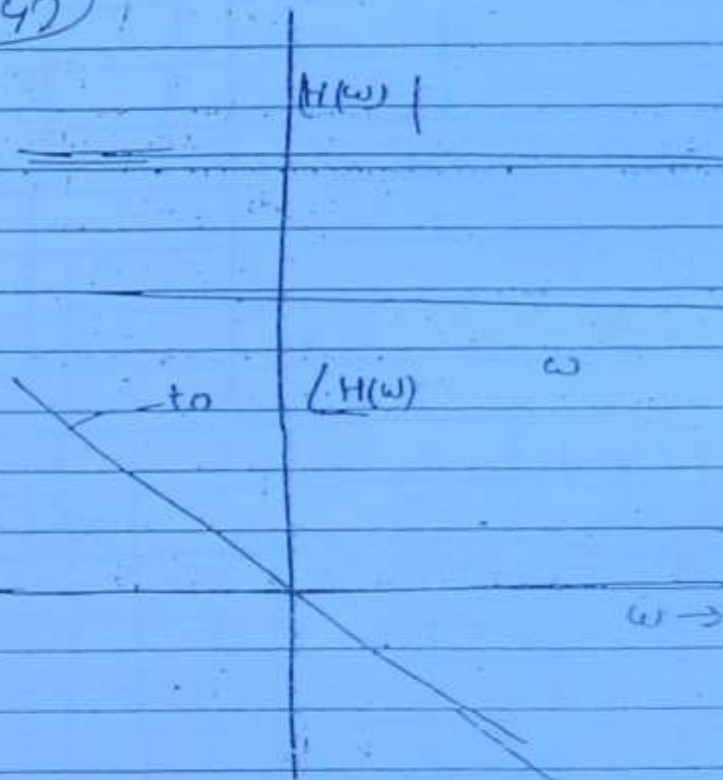
$$H(\omega) = A e^{-j\omega t_0} \quad \times 20$$

$$\left\{ \begin{array}{l} |H(\omega)| = A \\ \angle H(\omega) = -\omega t_0 \end{array} \right.$$

(92)

$|H(\omega)|$

condition for distortionless transmission.



\* A system is said to be distortionless system, if it allows only two change in the I/P. a scalar multiple of A to I/P and an uniform delay  $t_0$ . i.e. response to an I/P  $f(t)$  should be of the form  $A f(t - t_0)$ .

Transfer function:  $H(\omega) = A e^{-j\omega t_0}$

which insures constant magnitude response & linear phase response with  $-\omega$  slope

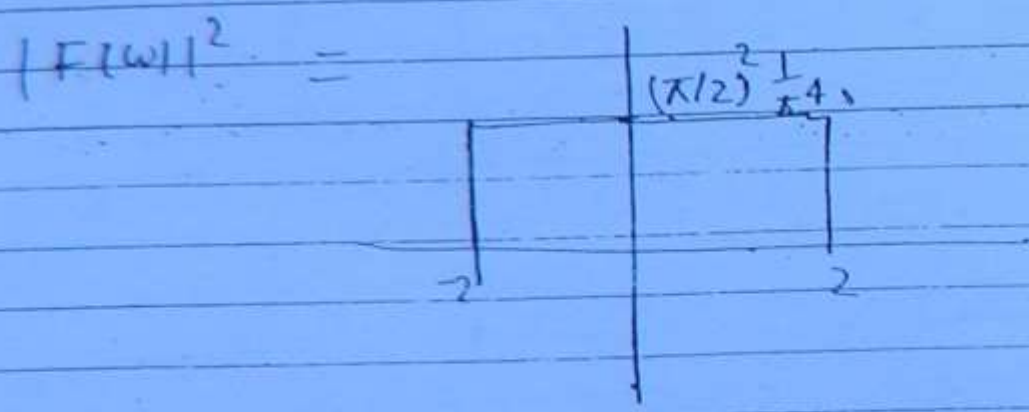
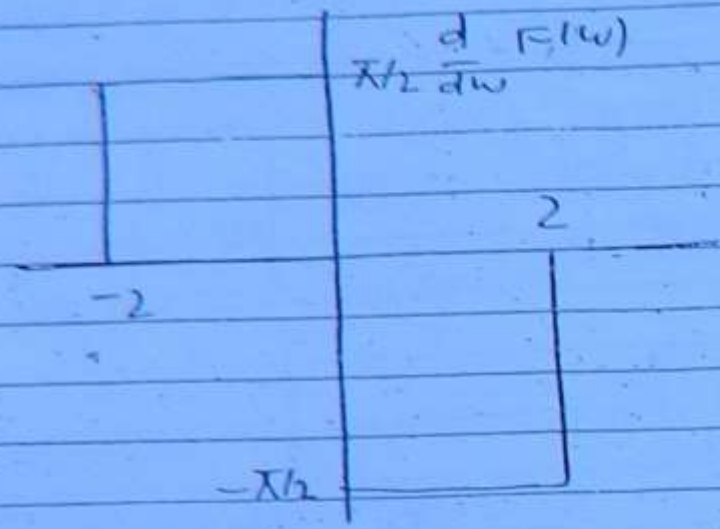
$$|H(\omega)| = A$$

$$\angle H(\omega) = -\omega t_0$$

- (\*) Constant magnitude response insures that all frequency components present at I/P will be carried to the O/P without change in shape.
- (\*) And linear phase response insures sequence of information in time domain i.e. all time components are given uniform time delay.

$$F(\omega) \equiv \frac{1}{\pi^2} \int_{-\infty}^{\infty} \frac{d F_1(\omega)}{d\omega}$$

(148)

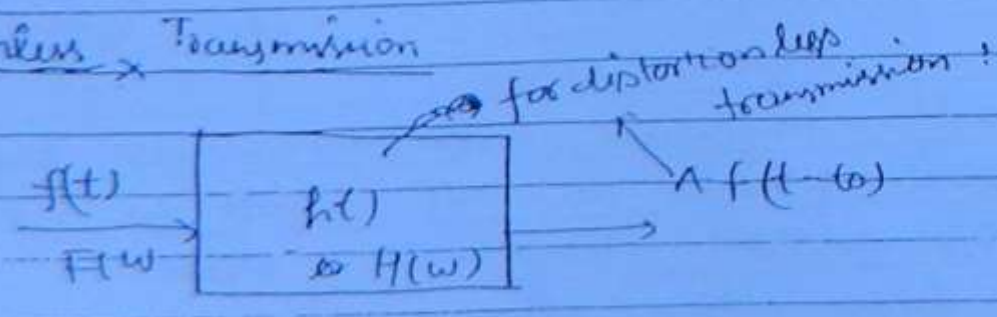


$$E = \frac{1}{2\pi} \times 4 \times \frac{1}{2\pi^3} \cdot \frac{\pi}{2}$$

$$E = \frac{\pi}{2} \frac{1}{\pi^4} \frac{Am}{2\pi^3}$$

$$= \frac{1}{2\pi^3} Am$$

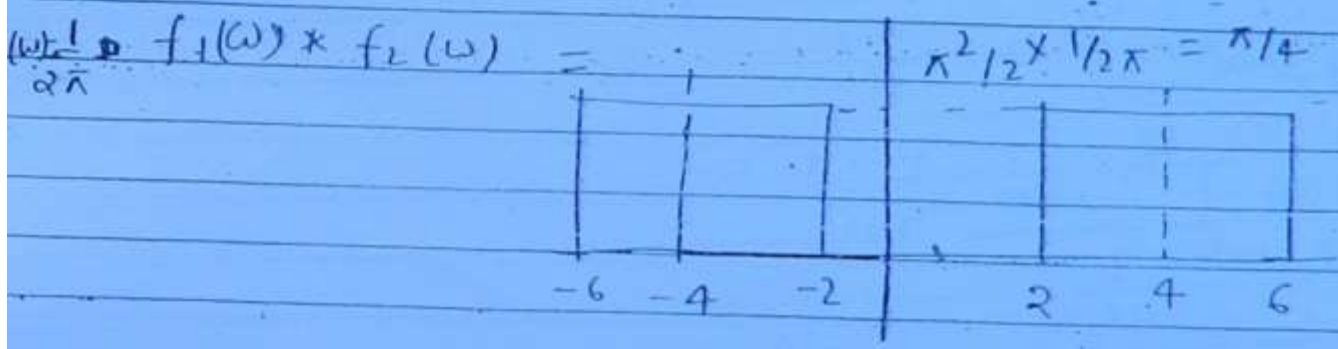
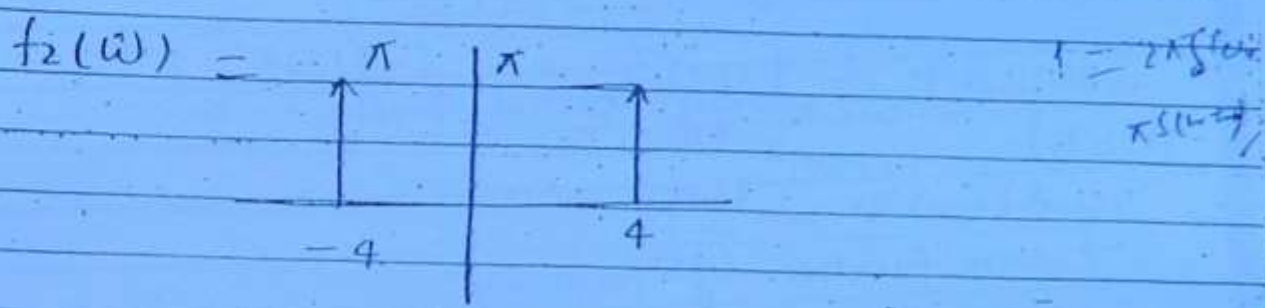
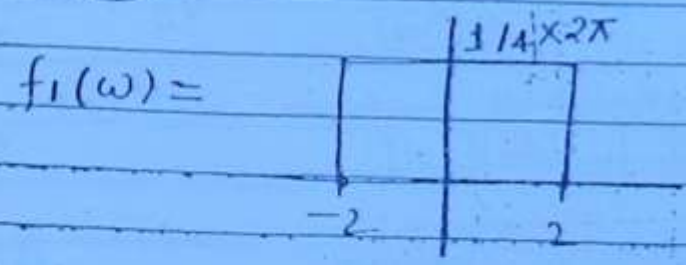
Distortionless Transmission



\* Calculate energy of the signal  $f(t) = \text{Sa}[2t] \cos 4t$

(149)

$f_1(t)$      $f_2(t)$

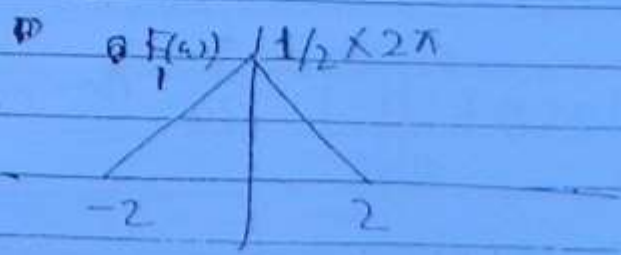


$$\int_{-\infty}^{\infty} f^2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(\omega)|^2 d\omega$$

$$= \frac{1}{2\pi} \left[ \frac{\pi^2}{4} \times 2 \times 4 \right]$$

$$E = \int_{-\infty}^{\infty} f^2(t) dt = \frac{\pi}{4}$$

\* Calculate the energy of the signal  $f(t) = \frac{t}{\pi} \left( \frac{\sin t}{t} \right)^2$



$\frac{t}{\pi^2} \text{Sa}^2(t)$   
 $f(t)$



$$E = \int_{-\infty}^{\infty} f(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(\omega)|^2 d\omega$$

(150)

$$= \int_{-\infty}^{\infty} |F(f)|^2 df$$

$$= \int_{-\infty}^{\infty} |F(\omega)|^2 d\omega$$

energy per unit frequency

$|F(\omega)|^2 \rightarrow$  energy density spectrum

or

energy spectral density

$$(ESD)_f = |F(\omega)|^2$$

$\rightarrow$  even function of frequency

$$f(t) = e^{-at} u(t)$$

$$E = \frac{1}{2a}$$

$$F(\omega) = \frac{1}{a + j\omega}$$

$$|F(\omega)| = \frac{1}{\sqrt{a^2 + \omega^2}}$$

$$|F(\omega)|^2 = \frac{1}{a^2 + \omega^2} = \text{ESD}$$

$$\therefore E = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{1}{a^2 + \omega^2} a \omega = \frac{1}{2} \frac{1}{2\pi a^2} \frac{1}{2\pi a} \left[ \tan^{-1} \omega/a \right]_{-\infty}^{\infty}$$

$$= \frac{1}{2\pi a}$$

$$= \frac{1}{2a} \text{ Ans}$$

Time Integration property of F.T. :

$$f(t) \rightarrow F(\omega)$$

(157)

$$\int_{-\infty}^t f(\tau) d\tau \rightarrow f(t) * u(t)$$

(1)

$$F\left[\int_{-\infty}^t f(\tau) d\tau\right] \rightarrow F(\omega) \left[\frac{1}{j\omega} + \pi \delta(\omega)\right]$$

$$\frac{F(\omega)}{j\omega} + \pi F(\omega) \delta(\omega)$$

$$\frac{F(\omega)}{j\omega} + \pi F(0) \delta(\omega)$$

$$= \frac{F(\omega)}{j\omega} \quad \text{when} \quad \int_{-\infty}^{\infty} f(t) dt = 0$$

$$0 \equiv F(0)$$

(\*)  $f(t)$  real valued signal

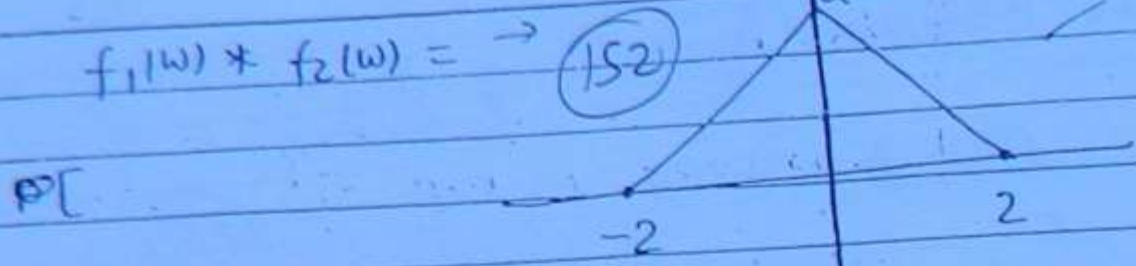
$$E = \int_{-\infty}^{\infty} |f(t)|^2 dt = \int_{-\infty}^{\infty} f^2(t) dt$$

$$= \int_{-\infty}^{\infty} f(t) f(t) dt$$

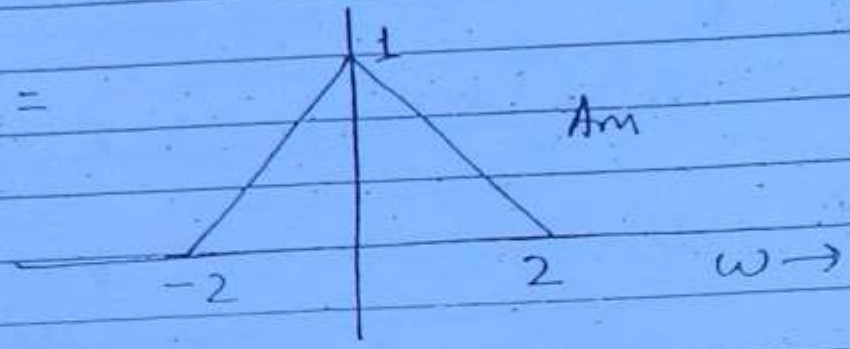
$$= \int_{-\infty}^{\infty} f(t) \left[ \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{j\omega t} d\omega \right] dt$$

$$= \int_{-\infty}^{\infty} \left[ \int_{-\infty}^{\infty} f(t) e^{j\omega t} dt \right] d\omega F(\omega) d\omega$$

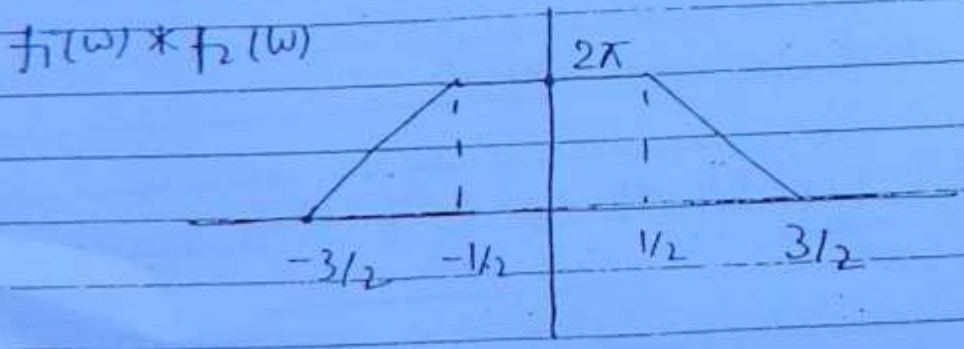
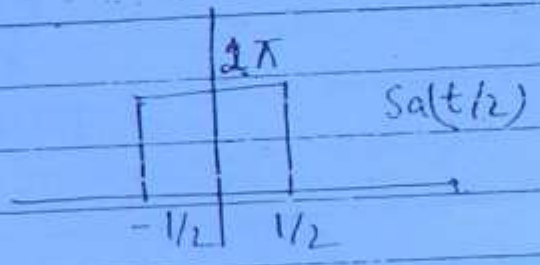
$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} F(-\omega) F(\omega) d\omega = \frac{1}{2\pi} \int_{-\infty}^{\infty} F^*(\omega) F(\omega) d\omega = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(\omega)|^2 d\omega$$



$$F[f_1(t) \cdot f_2(t)] = \frac{1}{2\pi} [P f_1(\omega) * f_2(\omega)]$$

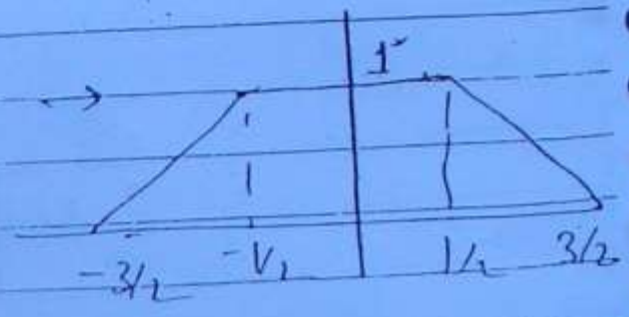


ii)  $f_2(t) = \text{Sa}(t/2)$   
 $F_2(\omega) =$



(check 20)

$$F(\omega) = \frac{1}{2\pi} [f_1(\omega) * f_2(\omega)] \rightarrow$$



$$\hat{f}(t) = \hat{f}(t) * \frac{1}{\pi t} \quad (153)$$

$$\hat{F}(\omega) = -F(\omega) \text{sgn}(\omega) \quad [-j \text{sgn}(\omega)]$$

$$= -F(\omega) \text{sgn}^2(\omega) = -F(\omega)$$

$$\hat{\hat{f}}(t) = -\cancel{f(t) * \frac{1}{\pi t} \text{sgn}(t)}$$

$$\hat{\hat{f}}(t) = f(t)$$

$$H[\text{Sin} \omega t] = H[H(\cos \omega t)]$$

$$= -\cos \omega t$$

$$\left\{ \begin{aligned} H\left[\frac{1}{\pi t}\right] &= -\text{sgn}^2(\omega) \\ &= -1 \quad \omega > 0 \\ &= 1 \quad \omega < 0 \end{aligned} \right.$$

$$\delta(t) \otimes \frac{1}{\pi t} = \delta(t) \cdot \frac{1}{\pi t}$$

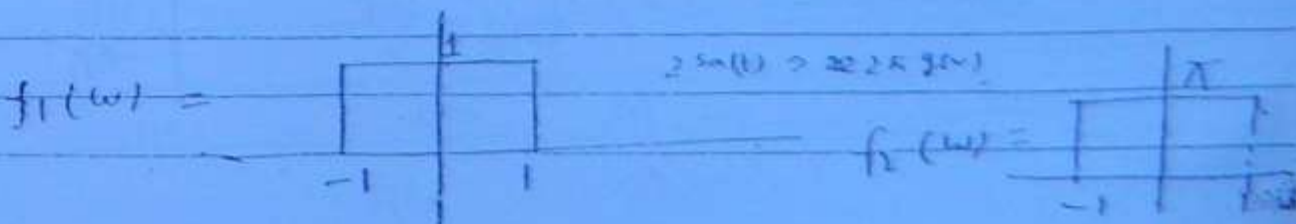
$$H[\delta(t)] = H\left[\delta(t) \cdot \frac{1}{\pi t}\right]$$

$$H[H\delta(t)] = -\delta(t)$$

$$H\left[\frac{1}{\pi t}\right] = -\delta(t)$$

sa(t)

$$f(t) = \frac{2 \text{Sin} t \cdot \text{Sin} t/2}{\pi t^2} = \frac{2}{\pi} \underset{f_1(t)}{\text{Sa}[t]} \cdot \underset{f_2(t)}{\text{Sa}[t/2]}$$



$$\frac{1}{\pi t} \rightarrow -j \operatorname{sgn}(\omega)$$

(154)

$$f(t) \rightarrow F(\omega)$$

$$f(t) * \frac{1}{\pi t} \rightarrow F(\omega) [-j \operatorname{sgn}(\omega)]$$

$$F(\omega) e^{-j\pi/2} = -j F(\omega) \quad \omega > 0$$

$$F(\omega) e^{+j\pi/2} = +j F(\omega) \quad \omega < 0$$

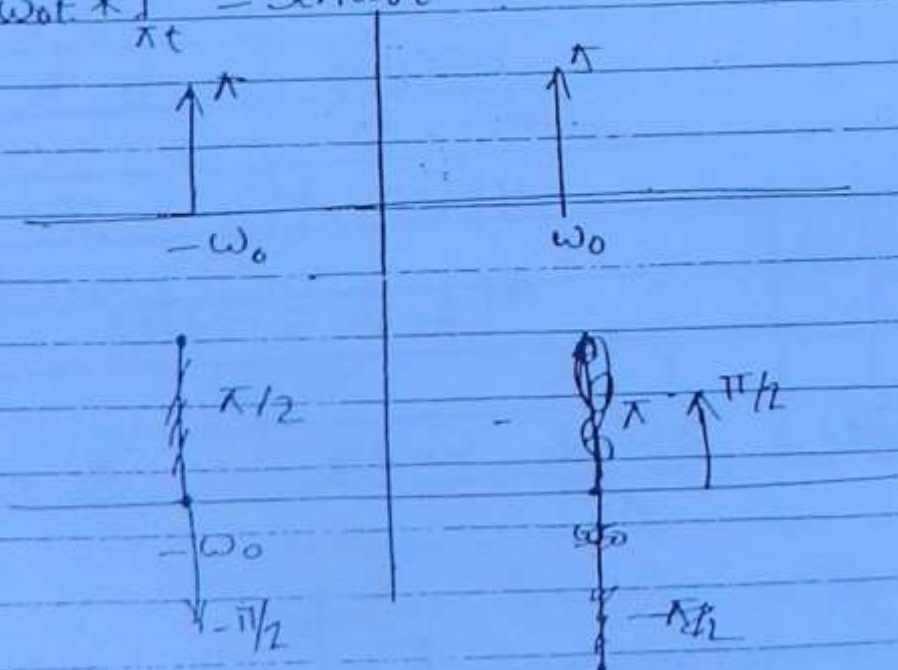
\* Hilbert transform of a signal  $f(t)$  is denoted by a symbol  $\hat{f}(t) = f(t) * \frac{1}{\pi t}$

\* The effect of taking Hilbert transform for a signal  $f(t)$ , it shifts all frequency components of  $f(t)$  uniformly by a phase of  $\pi/2$ .

\* Hilbert transform is also called as wide band phase shifter offering a shift of  $\pi/2$ .  
Band  $\rightarrow$  Group of frequencies.

$$f(t) = \cos \omega_0 t$$

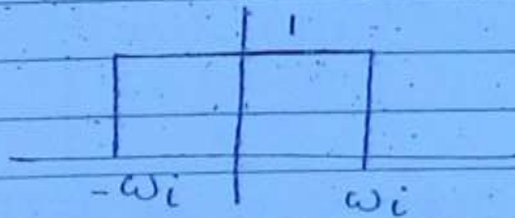
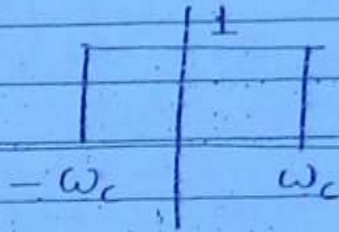
$$\hat{f}(t) = \cos \omega_0 t * \frac{1}{\pi t} = \sin \omega_0 t$$



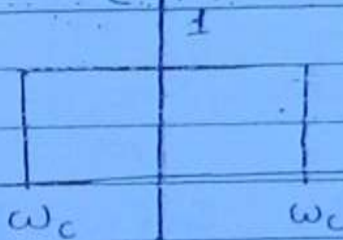
$$Y(\omega) = H(\omega) \cdot F(\omega)$$

(135)

$$= \frac{1 + \pi^2 \omega^2}{4\pi^2} g(\omega) \cdot g'(\omega)$$



$H(\omega) \cdot F(\omega)$



$\omega_i > \omega_c$

$$Y(\omega) = \frac{1 + 4\pi^2 \omega^2}{4\pi^2} g(\omega) \quad \text{if } \omega_i > \omega_c$$

$$= \frac{1 + 4\pi^2 \omega^2}{4\pi^2} g'(\omega) \quad \text{if } \omega_c > \omega_i$$

$$f(t) = \frac{2\omega_c}{2\pi} \text{sinc}[\omega_c t]$$

$$= \frac{\omega_c}{\pi} \text{sinc}[\omega_c t]$$

$$f(t) = \frac{\omega_c}{\pi} \text{sinc}[\omega_c t] \quad \omega_i > \omega_c$$

$$f(t) = f(t) \quad \omega_i > \omega_c$$

$$= f(t) \quad \omega_c > \omega_i$$

$$Y(\omega) = H(\omega) F(\omega)$$

$$= \frac{1}{a+j\omega} + \frac{1}{b+j\omega} \quad \text{--- 9}$$

$$= \frac{(b-a)1}{(b-a)(a+j\omega)} + \frac{1(a-b)}{(a-b)(b+j\omega)}$$

$$= \left( \frac{1}{b-a} \right) \left[ \frac{1}{a+j\omega} - \frac{1}{b+j\omega} \right]$$

$$y(t) = \frac{1}{b-a} \left[ e^{-at} u(t) - e^{-bt} u(t) \right] \quad \underline{\text{Ans}}$$

Q. Find the response of an LTI system

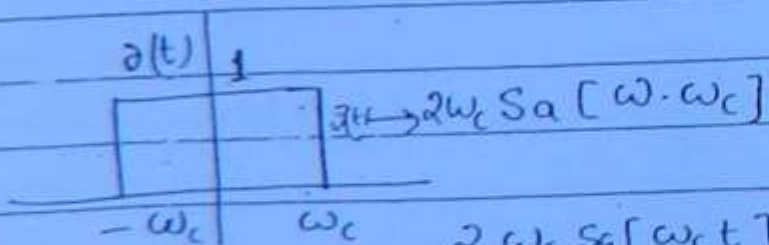
$$h(t) = \frac{\sin \omega_c t}{\pi t} =$$

$$f(t) = \frac{\sin \omega_c t}{\pi t}$$

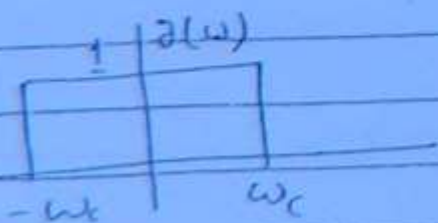


$$H(\omega) = F \left[ \frac{\omega_c}{\pi} \text{Sa}[\omega_c t] \right]$$

$$= \mathcal{F} \left[ \frac{\omega_c}{\pi} \right]$$



$$2\omega_c \text{Sa}[\omega_c t] \longleftrightarrow \mathcal{F}(-\omega) \times 2\pi / g(\omega)$$



$$\frac{\omega_c}{\pi} \text{Sa}[\omega_c t] \rightarrow \frac{1}{2\pi} g(\omega) \times 2\pi /$$

$$\frac{\omega_c}{\pi} \text{Sa}[\omega_c t] \rightarrow \frac{1}{2\pi} g'(\omega) \times 2\pi$$

# Convolution Property

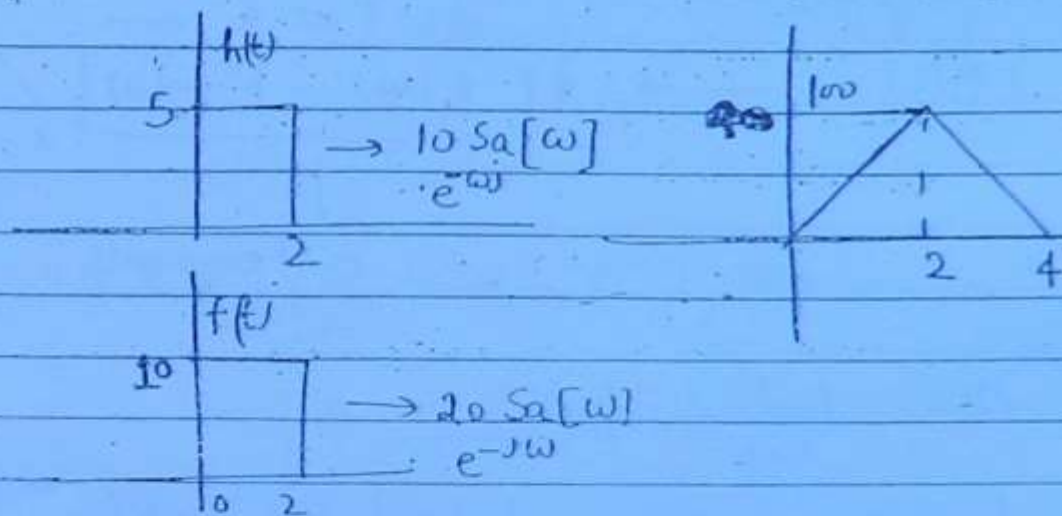
(157)

$$f(t) \rightarrow F(\omega)$$

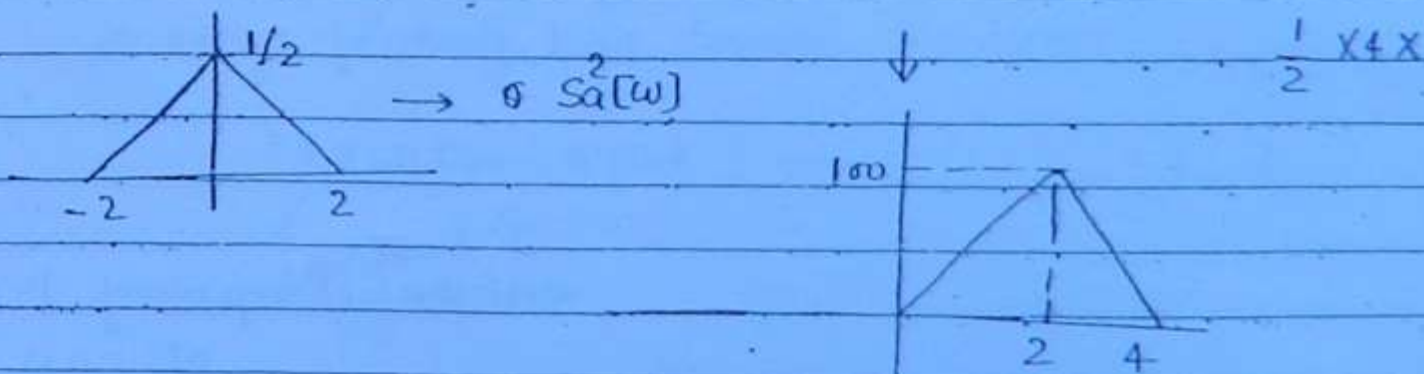
$$h(t) \rightarrow H(\omega)$$

$$f(t) \times h(t) \leftrightarrow F(\omega) \cdot H(\omega)$$

Q. Find response of a LTI system with an impulse response & I/P as shown below.



$$h(\omega) F(\omega) \rightarrow 200 \text{Sa}^2[\omega] e^{-2j\omega}$$



Repeat the above problem for following impulse response & i/p's

$$h(t) = e^{-at} u(t)$$

$$f(t) = e^{-bt} u(t)$$

$$H(\omega) = \frac{1}{a + j\omega}$$

$$F(\omega) = \frac{1}{b + j\omega}$$



$$f^*(-t) \rightarrow F^*(\omega)$$

158

$$c = a + jb$$

$$C_r = a$$

$$j C_i = jb$$

$$f_R(t) \xrightarrow{\frac{f^*(t) + f(t)}{2}} \frac{F^*(-\omega) + F(\omega)}{2}$$

$\downarrow$  real part of  $f(t)$                        $\downarrow$  even conjugate of  $F(\omega)$

$$j f_I(t) \xrightarrow{\frac{F(\omega) - F^*(-\omega)}{2j}}$$

$\downarrow$  odd conjugate

$f(t) = f_R(t) + j f_I(t)$

$$f(t) = f_R(t) + j f_I(t)$$

$$f_R(t) \xrightarrow{\frac{F(\omega) + F^*(\omega)}{2}}$$

$\downarrow$  real part of  $F(\omega)$

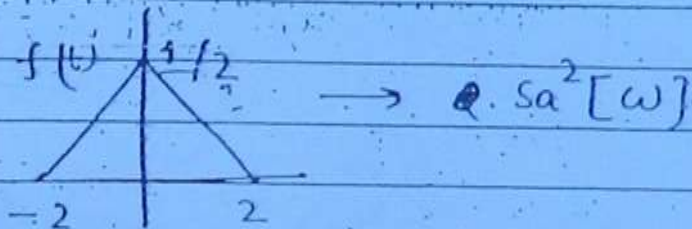
$$j f_I(t) \xrightarrow{\frac{F(\omega) - F^*(\omega)}{2j}}$$

$\downarrow$  ~~odd part~~ imaginary part of  $F(\omega)$ .

$$\int_{-\infty}^{\infty} \text{Sa}^2(\omega) e^{-j\omega/2} d\omega$$

(159)

$$= f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{+j\omega t} d\omega$$



$\Rightarrow \frac{1}{4}$

$$f(-1/2) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{-j\omega/2} d\omega$$

$$\frac{1}{4} \left( \frac{1}{2} + \frac{1}{2} \right) = \frac{1}{8} + \frac{1}{8}$$

$$2\pi \times \frac{3}{8} = \int_{-\infty}^{\infty} F(\omega) e^{-j\omega/2} d\omega$$

$$\frac{3}{2}$$

Ans  $\frac{3\pi}{4}$

Symmetry Property of fourier transform.

$$f(t) \rightarrow F(\omega)$$

complex valued signal

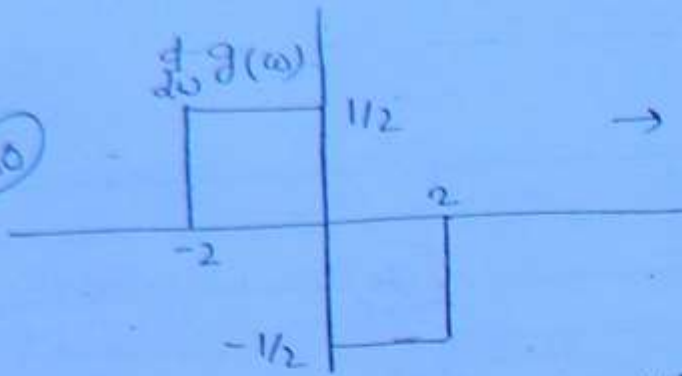
$$F(\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$$

$$F^*(\omega) = \int_{-\infty}^{\infty} f^*(t) e^{j\omega t} dt$$

$$F^*(-\omega) = \int_{-\infty}^{\infty} f^*(t) e^{-j\omega t} dt$$

$$f^*(t) \rightarrow F^*(-\omega)$$

(160)



$$\rightarrow \frac{1}{2} u(\omega+2) - u(\omega) + \frac{1}{2} u(\omega-2)$$

$$\therefore \frac{t}{\pi^2} [\text{Sa}(t)]^2 \xleftrightarrow{\text{F.T.}} \frac{j}{2\pi} \left[ u(\omega+2) - 2u(\omega) + u(\omega-2) \right]$$

Am

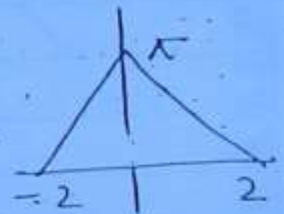
$$Q \rightarrow f(\omega) = \frac{4t}{(1+t^2)^2}$$

$$e^{-|t|} = \frac{2}{1+\omega^2}$$

$$t e^{-|t|} = -\frac{4\omega}{(1+\omega^2)^2} j$$

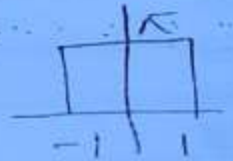
$\text{Sa}^2(t)$

$\rightarrow$



$\text{Sa}(t)$

$\leftrightarrow$



$$-\frac{4t}{(1+t^2)^2} j \leftrightarrow 2\pi (-\omega) e^{-|\omega|}$$

$$\frac{4t}{(1+t^2)^2} j \leftrightarrow +2\pi \omega e^{-|\omega|}$$

$$\frac{4t}{(1+t^2)^2} \leftrightarrow -2\pi j \omega e^{-|\omega|}$$

$$\int_{-\infty}^{\infty} \frac{\sin^2 t}{\pi t^2} dt = 1$$

$$\int_{-\infty}^{\infty} \frac{1}{\pi} \text{Sa}^2(t) dt = \frac{1}{\pi} \cdot \pi = 1$$

Duality Property:

(61)

$f(t) \rightarrow F(\omega)$   
 $F(\omega) \rightarrow 2\pi f(-\omega)$

$\int_0^{\infty} \frac{\sin t}{t} dt = \pi/2$

$\int_{-\infty}^{\infty} \frac{\sin t}{t} dt = \pi$

$f(t) = \frac{1}{jt+1}$

$F(\omega) \Rightarrow \frac{1}{1+j\omega} \longleftrightarrow e^{-t} u(t)$

$\frac{1}{1+jt} \longleftrightarrow 2\pi e^{\omega} u(-\omega)$

$\frac{\sin t}{t}$   
 is an even function of time

Q.  $\frac{1}{\pi t} \xrightarrow{FT} ?$

$\frac{1}{j\omega} \rightarrow \frac{1}{2} \text{sgn}(t)$

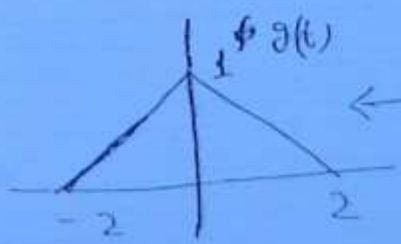
$\frac{1}{jt} \rightarrow \frac{1}{2} 2\pi \text{sgn}(-\omega)$

$\frac{1}{\pi t} \rightarrow \frac{1}{2} 2j \text{sgn}(-\omega)$

$\frac{1}{\pi t} \rightarrow -j \text{sgn}(\omega)$  Ans

Q.  $f(t) = t \left( \frac{\sin t}{\pi t} \right)^2$

$= \frac{t}{\pi^2} \left( \frac{\sin t}{t} \right)^2 = \frac{t}{\pi^2} [\text{sa}(t)]^2$



$\longleftrightarrow 2 \text{sa}(\omega) [\text{sa}(\omega)]^2$

$\frac{t}{\pi^2} [\text{sa}(t)]^2 \rightarrow 2\pi g(-\omega) - \pi(\omega)$

$\therefore \frac{t}{\pi^2} [\text{sa}(t)]^2 \rightarrow j\pi \frac{d}{d\omega} g(\omega) - \pi(\omega)$

Area Property  $\rightarrow$

(162)

$$F(\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$$

$$F(0) = \int_{-\infty}^{\infty} f(t) dt \quad \text{area under curve } f(t)$$

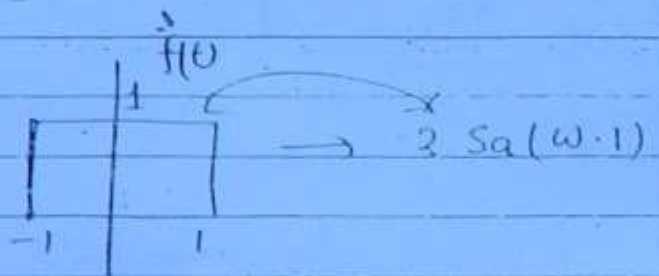
$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{j\omega t} d\omega$$

$$f(0) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) d\omega$$

$$\boxed{2\pi f(0) = \int_{-\infty}^{\infty} F(\omega) d\omega}$$

$$\int_{-\infty}^{\infty} \text{Sa}(t) dt$$

$$\downarrow = \int_{-\infty}^{\infty} \frac{\sin t}{t} dt = \pi$$



$$\mathcal{F}\{\text{Sa}(t)\} \leftrightarrow \pi f(-\omega)$$

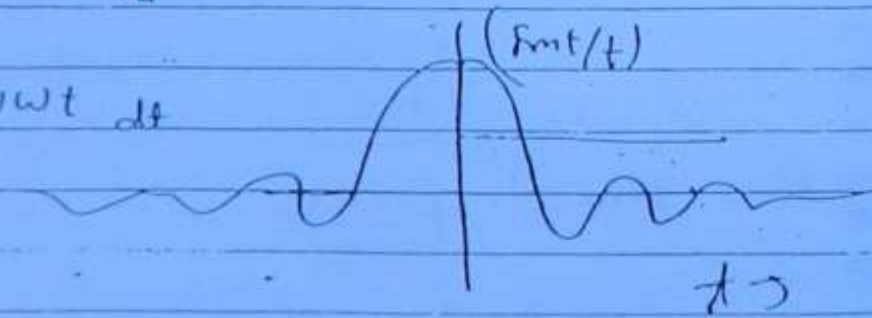
$$\pi f(\omega)$$

$$F(\omega) = \int_{-\infty}^{\infty} \text{Sa}(t) e^{-j\omega t} dt$$

$$\pi f(\omega) = \int_{-\infty}^{\infty} \text{Sa}(t) e^{-j\omega t} dt$$

$$\pi f(0) = \int_{-\infty}^{\infty} \text{Sa}(t) dt$$

$$\pi = \int_{-\infty}^{\infty} \text{Sa}(t) dt \quad \text{Ans.}$$



$$F(\omega) = e^{-\omega^2/4\pi}$$

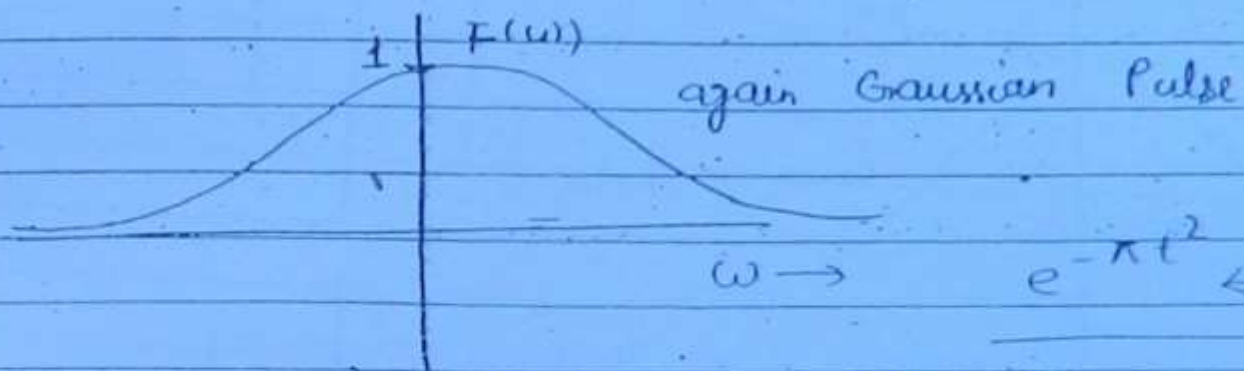
(163)

$$2\pi \frac{dF(\omega)}{d\omega} + \omega F(\omega) = 0$$

$$\frac{dF(\omega)}{F(\omega)} = -\frac{\omega}{2\pi} d\omega$$

$$\log F(\omega) = -\frac{\omega^2}{4\pi}$$

$$F(\omega) = e^{-\omega^2/4\pi} = e^{-f^2/\pi}$$



$$\text{F.T. } e^{-t^2} \rightarrow \text{ⓐ}$$

$$f(t) = e^{-\pi t^2}$$

$$F\left[\frac{t/\sqrt{\pi}}{\sqrt{\pi}}\right] \rightarrow \frac{1/\sqrt{\pi}}{\sqrt{\pi}} e^{-\frac{\omega^2/\pi/\pi^2}{4\pi^2}} \rightarrow \frac{1/\sqrt{\pi}}{\sqrt{\pi}} e^{-\frac{\omega^2}{4\pi^2}}$$

$$f(t/\sqrt{\pi}) \rightarrow \sqrt{\pi} e^{-\omega^2/4} \text{ Ans}$$

$$1 \rightarrow 2\pi \delta(\omega)$$

$$1 \rightarrow \delta(f)$$

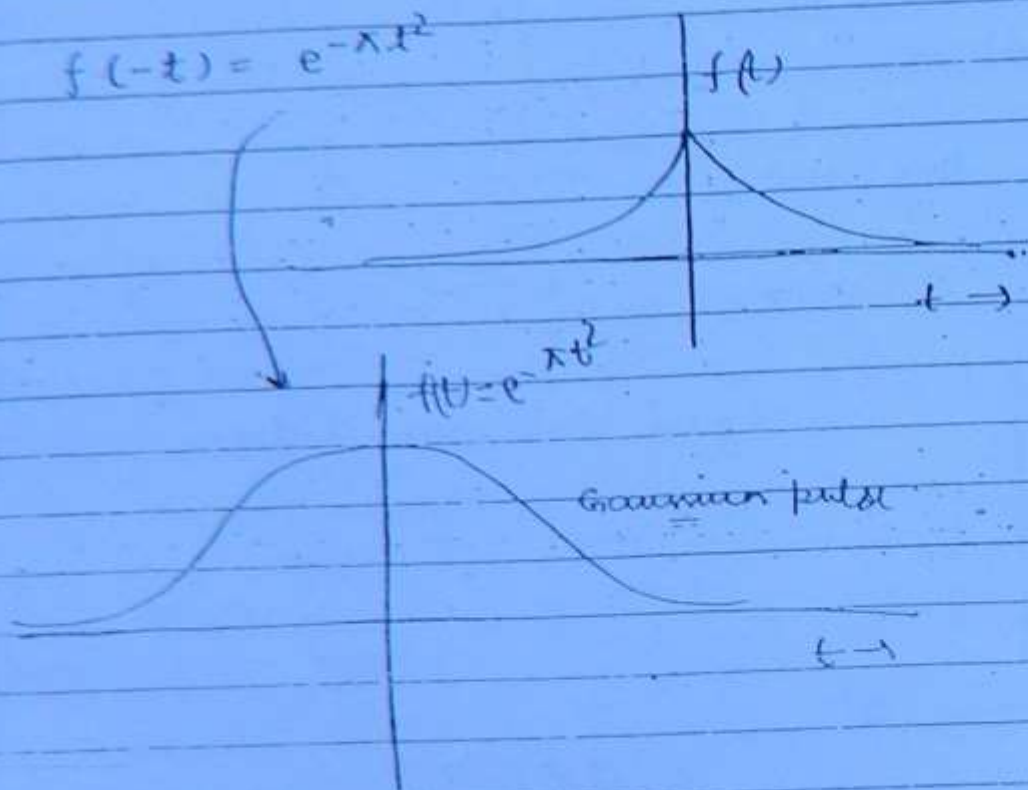
$$\text{sgn}(t) \rightarrow \text{ⓑ } \int_{-\infty}^{\infty} \frac{1}{j\omega} + \pi \delta(\omega)$$

$$\frac{1}{j2\pi f} + \frac{1}{2} \delta(f)$$

$$\lambda \quad t^h e^{-at} u(t) \rightarrow \frac{\Gamma(h)}{(a+j\omega)^{h+1}} \quad (64)$$

$$f(t) = e^{-\lambda t^2}$$

$$f(-t) = e^{-\lambda t^2}$$



$$\frac{df}{dt} \rightarrow j\omega F(\omega)$$

$$-2\lambda t e^{-\lambda t^2} \xrightarrow{F.T.} j\omega F(\omega)$$

$$-2\lambda j \frac{dF(\omega)}{d\omega} = j\omega F(\omega)$$

$$1 \quad (1) \quad [ \cdot \quad \infty \quad \cdot \quad 2\lambda ]$$

$$-2\lambda [ -2\lambda j \frac{dF(\omega)}{d\omega} ] F(\omega) = 0$$

$$j = \frac{j(\omega)}{2\lambda}$$

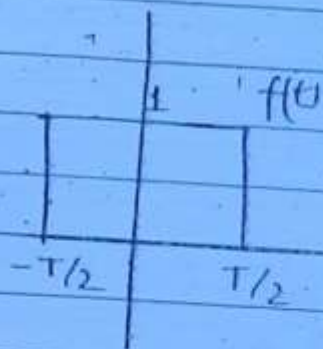
Q.  $f(t) \rightarrow F(\omega)$

find F.T. of  ~~$f(t)$~~   $\frac{d^2}{dt^2} [f(t-1)]$

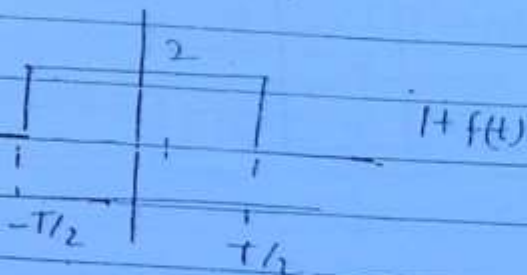
$f(t-1) \rightarrow e^{-j\omega} F(\omega)$

(165)

$\frac{d^2}{dt^2} [f(t-1)] \rightarrow -\omega^2 e^{-j\omega} F(\omega)$



$\frac{d}{dt} f(t-1)$   
 $d'$



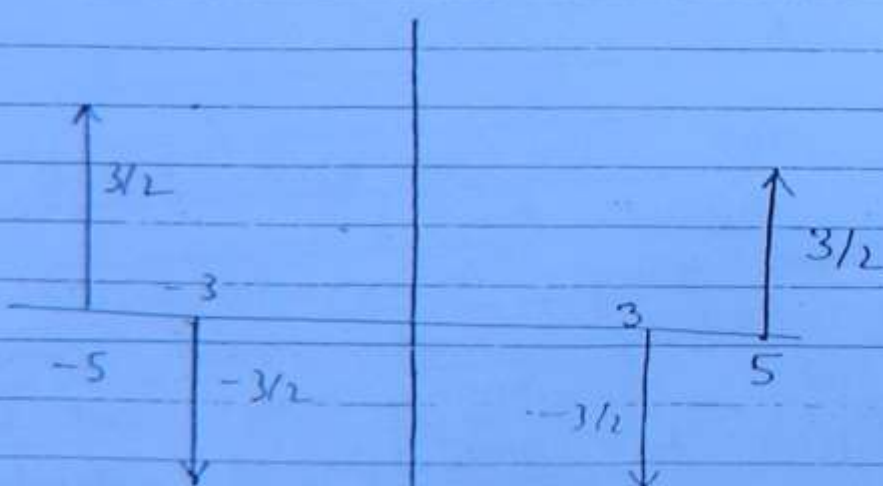
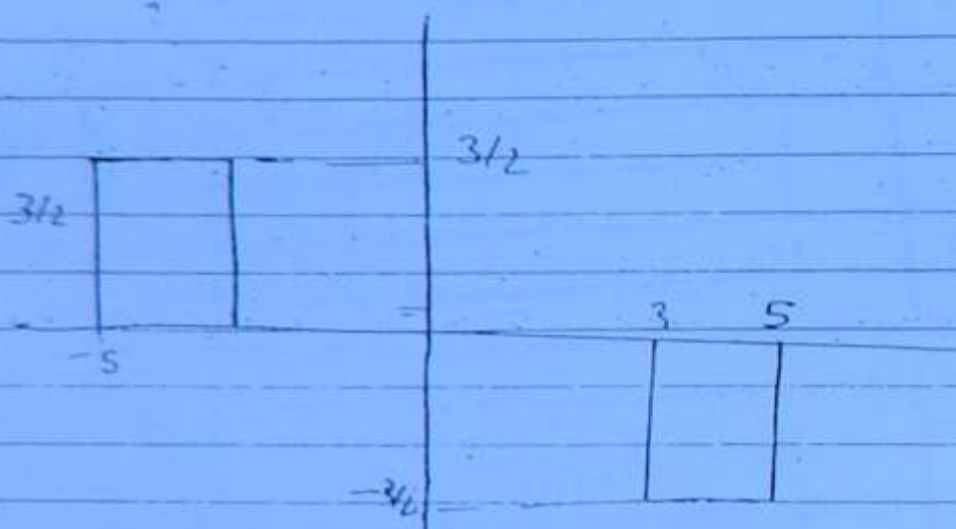
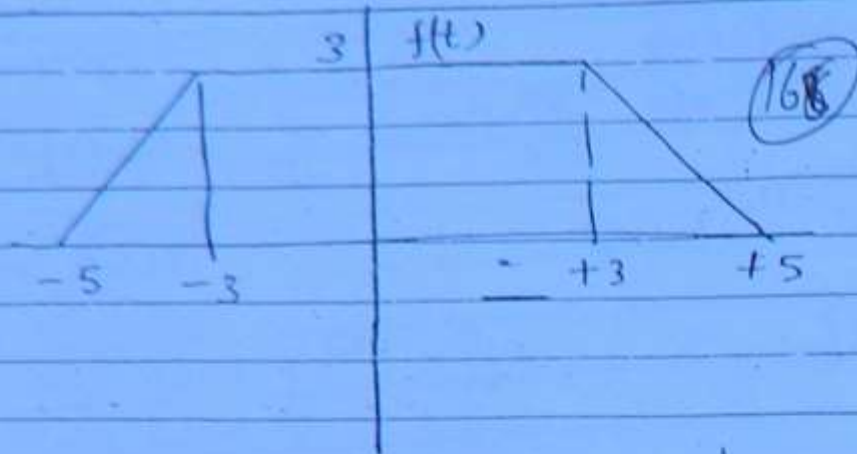
✓  $f(t)$  &  $1+f(t)$  are not same signal  
 so have different F.T.  
 if we are going in accordance with  
 differentiation property both have same F.T.  
 which is not possible so there must be  
 some condition for application of differentiation  
 property.

Multiplication by  $t \rightarrow$

$f(t) \rightarrow F(\omega)$

$t f(t) \rightarrow j \frac{dF(\omega)}{d\omega}$





$$-\omega^2 F(\omega) \rightarrow \frac{3}{2} [e^{-j5\omega} + e^{+j5\omega}]$$

$$- \frac{3}{2} [e^{-j3\omega} + e^{+j3\omega}]$$

$$-\omega^2 F(\omega) \rightarrow \frac{3 \times 2 \cos 5\omega - 3 \times 2 \cos 3\omega}{2}$$

$$F(\omega) \rightarrow \frac{3}{\omega^2} [\cos 3\omega - \cos 5\omega] \text{ Ans}$$

$$F(\omega) = \frac{1}{\omega^2} \left[ \frac{2}{T} - \frac{2}{T} \cos(\omega T) \right] \quad (137)$$

$$= \frac{2}{\omega^2 T} [1 - \cos(\omega T)]$$

$$F(\omega) = \frac{1}{\pi \omega} [1 - \cos(\omega T)] \quad \underline{\text{Am}}$$

$$= \frac{2 \sin^2 \frac{\omega T}{2}}{\pi \omega}$$

$$= \frac{2 \times 2T}{4} \left[ \text{Sa}(\omega T/2) \right]^2$$

$$\frac{2 \omega^2 T^2}{4 \times 2 \pi \omega}$$

$$\frac{2T}{\pi}$$

$$F(\omega) = \frac{2 \times 2T}{4} \left[ \text{Sa}(\omega T/2) \right]^2$$

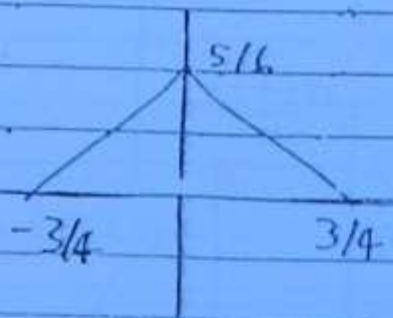
$$\frac{2 \omega^2 T^2}{\pi \omega \times 4}$$

$$F(\omega) = 2 \times T \left[ \text{Sa}(\omega T/2) \right]^2$$

$$F(\omega) = T \left[ \text{Sa}(\omega T/2) \right]^2$$

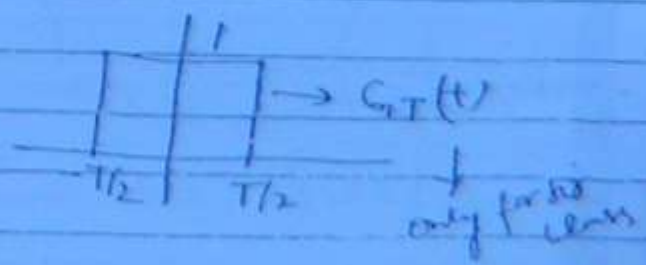
(31)  
1

area of triangle  
width  
4

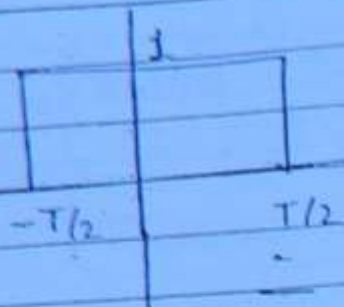


$$\frac{1}{2} \times \frac{3}{2} \times \frac{5}{6} \times 2 = \frac{3}{2}$$

$$F(\omega) \rightarrow \frac{5}{8} \left[ \text{Sa} \left[ \frac{\omega \cdot 3}{8} \right] \right]^2$$



(168)



$$\frac{df(t)}{dt} \leftrightarrow \left[ -e^{-j\omega T/2} + e^{j\omega T/2} \right]$$

$$\downarrow$$

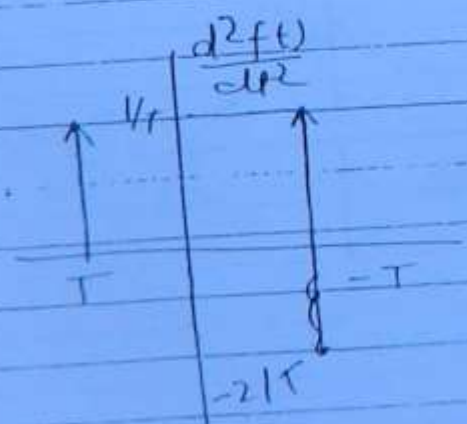
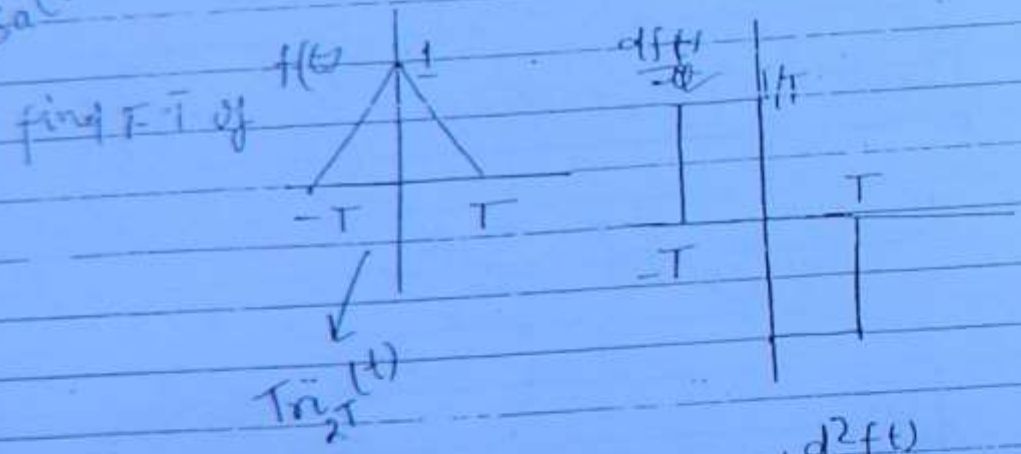
$$2j \sin \omega T/2$$

$$F(\omega) \rightarrow \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$$

$Sa(t) \rightarrow \left( \frac{\sin t}{t} \right)$

$\rightarrow \frac{2 \sin \omega T/2}{\omega}$

$\rightarrow T \text{ Sa}(\omega T/2)$



$$(j\omega)^2 F(\omega) \rightarrow -\frac{2}{T} + \frac{1}{T} (e^{j\omega T} + e^{-j\omega T})$$

$$(j\omega)^2 F(\omega) \rightarrow -\frac{2}{T} + \frac{1}{T} 2 \cos \omega T$$

# Frequency shifting Property $\rightarrow$

(169)

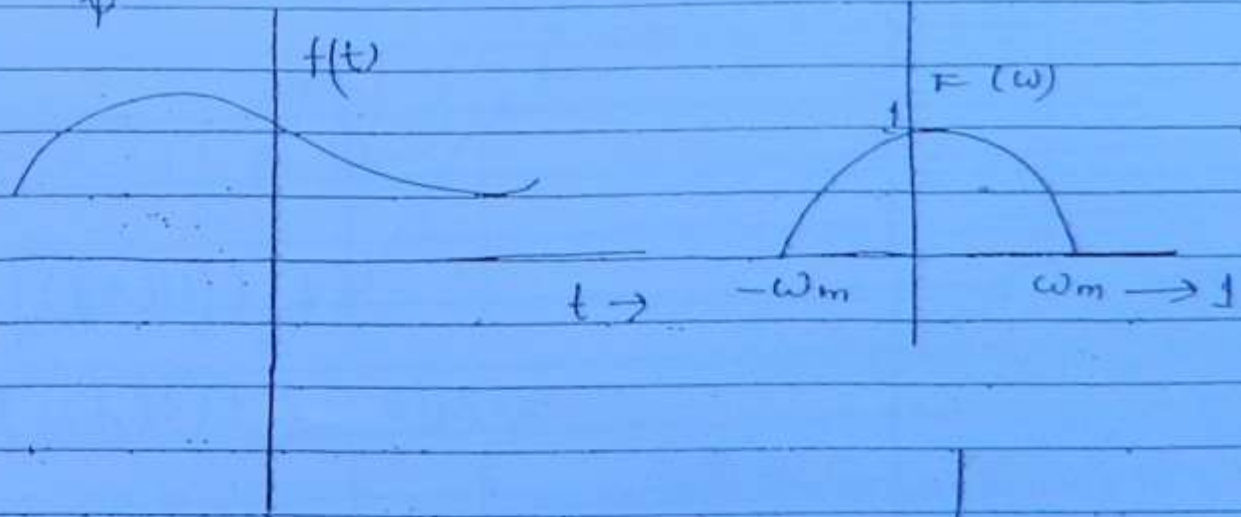
$$e^{j\omega_0 t} f(t) \rightarrow F(\omega - \omega_0)$$

$$e^{-j\omega_0 t} f(t) \rightarrow F(\omega + \omega_0)$$

$$\frac{1}{2} e^{j\omega_0 t} f(t) + \frac{1}{2} e^{-j\omega_0 t} f(t) \rightarrow \frac{1}{2} [F(\omega - \omega_0) + F(\omega + \omega_0)]$$

$$f(t) \cos \omega_0 t \rightarrow \frac{1}{2} [F(\omega - \omega_0) + F(\omega + \omega_0)]$$

Modulation theorem

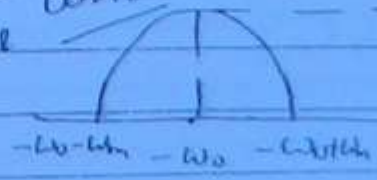


$\times \cos \omega_0 t$

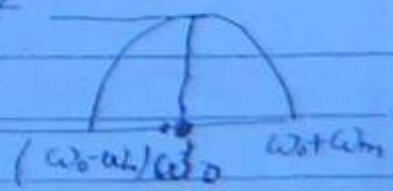
very high compare

$\omega_0 \gg \omega_m$

$f(t) \cos \omega_0 t \leftrightarrow$  F.T.



$\frac{1}{2}$



Time scaling

$$f(t) \rightarrow F(\omega)$$

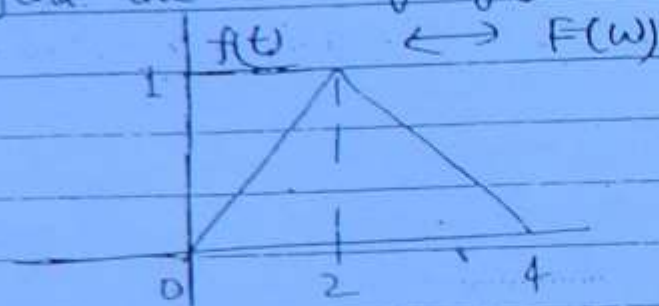
(170)

$$f(at) \rightarrow \frac{1}{|a|} F(\omega/a)$$

\* Expansion of a signal in time domain leads to compression in frequency domain by the same proportion and vice versa.

\* Always maintaining the product of time width & frequency width as a constant.

Q. F.T of  $f(t)$  shown below is known to  $F(\omega)$  then find the F.T of  $g(t)$ .



$$f(4t)$$

$$= f[4(t+3)]$$

$$g(t) = -2 f(4t+12)$$



$$= -2 e^{j\omega \times 12/4} F(\omega/4)$$

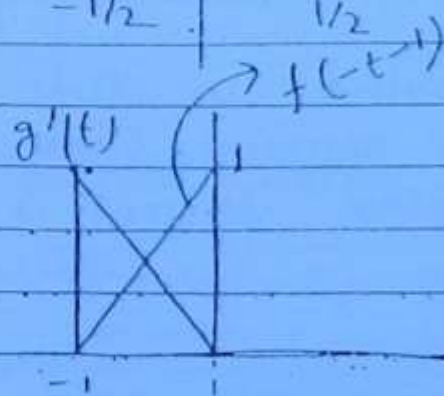
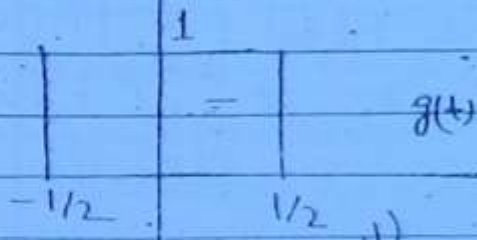
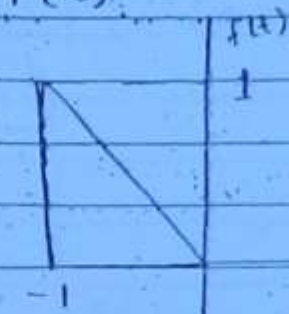
$$G(\omega) = -\frac{1}{2} e^{3j\omega} F(\omega/4)$$

$$F(\omega) = \left\{ \frac{1}{j\omega} + \pi \delta(\omega) \right\} * \mathcal{F} \left[ \begin{matrix} 1 + 3e^{-j\omega \times 2} - 3e^{-j\omega \times 5} \\ - e^{-j\omega \times 7} \end{matrix} \right]$$

27<sup>th</sup> Oct 10

(17)

Q. If the Fourier transform of the signal  $f(t)$  is known to  $F(\omega)$  find F.T. of signal  $g(t)$  in terms of  $F(\omega)$ .



$$g'(t) = f(t) + f(-t-1)$$

$$G'(\omega) \mathcal{F}\{g'(t)\} = F(\omega) + e^{+j\omega} F(-\omega)$$

$$G(\omega) = e^{-j\omega \cdot 1/2} \cdot F(\omega) + e^{+j\omega \cdot 1/2} F(-\omega)$$

Ans ✓

\* Even if F.T. is defined indirectly, for signal like  $\sin(t)$  &  $1$  which is not satisfying the above condition  $(\int_{-\infty}^{\infty} |f(t)| dt < \infty)$ , the F.T. so derived

will not be well defined F.T. i.e. this F.T. will have an undefined value atleast for one value of  $\omega$ .

(72)

Properties of F.T. :-

Time shifting

$$f(t) \rightarrow F(\omega) = |F(\omega)| \angle F(\omega)$$

$$f(t-t_0) \rightarrow e^{-j\omega t_0} F(\omega) = e^{-j\omega t_0} |F(\omega)| \angle F(\omega)$$

$$|F(\omega)| \angle [F(\omega) - \omega t_0]$$

\* When a signal is shifted in time domain magnitude part of spectrum remains same, only phase spectrum is affected i.e. phase spectrum is changed by  $\omega t_0$ .

$\delta(t) \rightarrow 1$

$\delta(t-t_0) \rightarrow e^{-j\omega t_0}$

$\delta(t+t_0) \rightarrow e^{j\omega t_0}$

$f(t-t_0) + f(t+t_0) \rightarrow 2 \cos \omega t_0 F(\omega)$



$u(t) + u(t-1) = u(t) - u(t-3)$

$f(t) = u(t) + 3u(t-2) - 3u(t-5) - u(t-7)$

$$F(\omega) = \frac{1}{j\omega} \left[ e^{j\omega T/2} - e^{-j\omega T/2} \right]$$

$$= \frac{1}{j\omega} 2j \sin \omega T/2$$

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$$F(\omega) = \frac{2 \sin \omega T/2}{\omega} = \textcircled{1} \text{Sa}(\omega T/2)$$

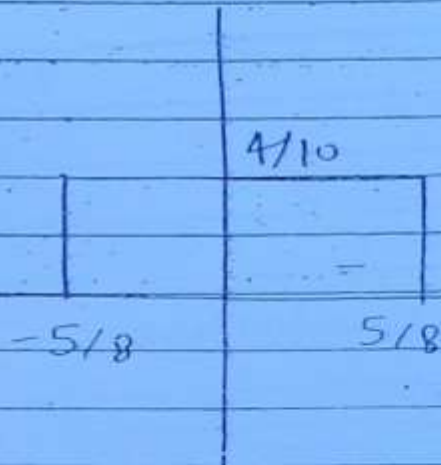
$$\sin \theta = \frac{\text{opposite}}{\text{hypotenuse}}$$

$$F(\omega) = T \cdot \text{Sinc} \frac{\omega T}{2\pi}$$

area of pulse

half of width

$$\frac{T}{\pi \omega T/2\pi}$$



$$\frac{1}{2} \text{Sa} \left( \frac{5\omega}{8} \right)$$

$$\frac{4/10 \times 2 \times 5}{8}$$

$e^{-at} u(t)$ ,  $e^{at} u(t)$ ,  $\delta(t)$ ,  $\text{rect}(t)$   $\xrightarrow{\text{F.T.}}$  is completely defined F.T.

$\text{Sgn}(t)$ ,  $1$ ,  $e^{j\omega t}$ ,  $\cos \omega t$ ,  $\sin \omega t$ ,  $u(t)$   $\rightarrow$  F.T. is not completely defined for all values of  $\omega$ .

Existence of Fourier Transform  $\rightarrow$

$$F(\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$$

$$|F(\omega)| < \infty$$

$$\left| \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt \right| < \infty$$

$$\int_{-\infty}^{\infty} |f(t)| dt < \infty$$

if this condition is satisfied then only we can use the integral formula for calculation of F.T.

$$\int_{-\infty}^{\infty} |f(t)| dt < \infty \rightarrow \text{for well defined F.T.}$$

$f(t)$  must satisfy this condition.



174

- t →

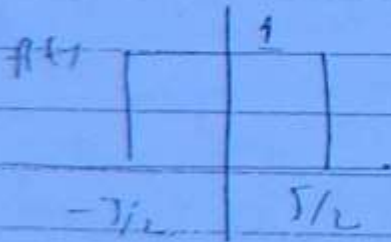
t  
1

ω

$$u(t) = \frac{1}{2} [\text{sgn}(t) + 1]$$

$$\square U(\omega) = \frac{1}{2} \left[ \frac{1}{2j\omega} + \pi\delta(\omega) \right]$$

$$U(\omega) = \frac{1}{4} \left[ \frac{1}{j\omega} + \pi\delta(\omega) \right]$$



$$= \int_{-T/2}^{T/2} 1 \cdot e^{j\omega t} dt$$

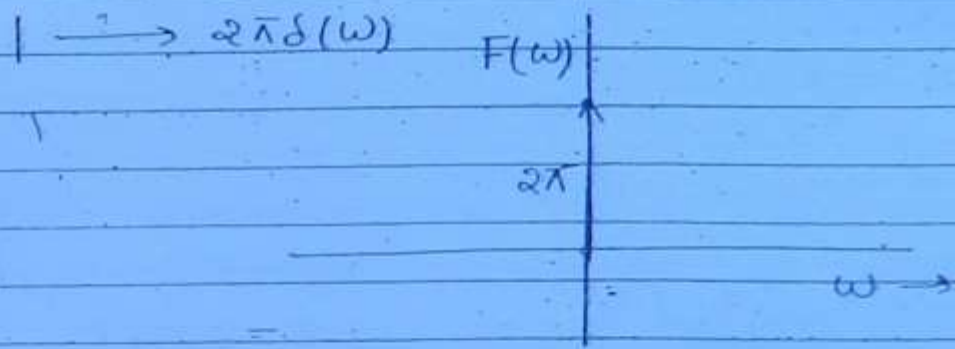
$$F(\omega) = \left[ \frac{e^{-j\omega t}}{-j\omega} \right]_{-T/2}^{T/2}$$

175

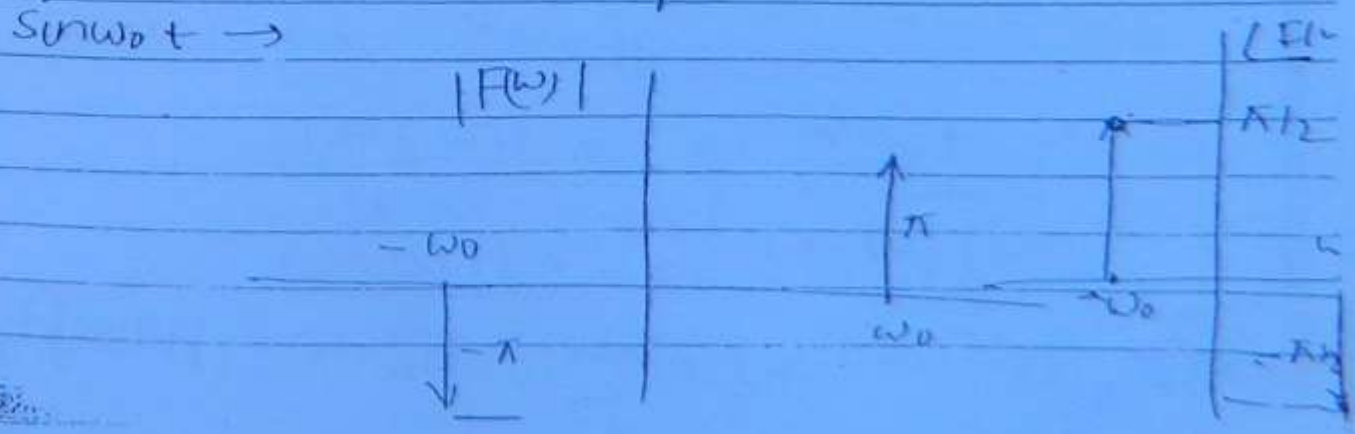
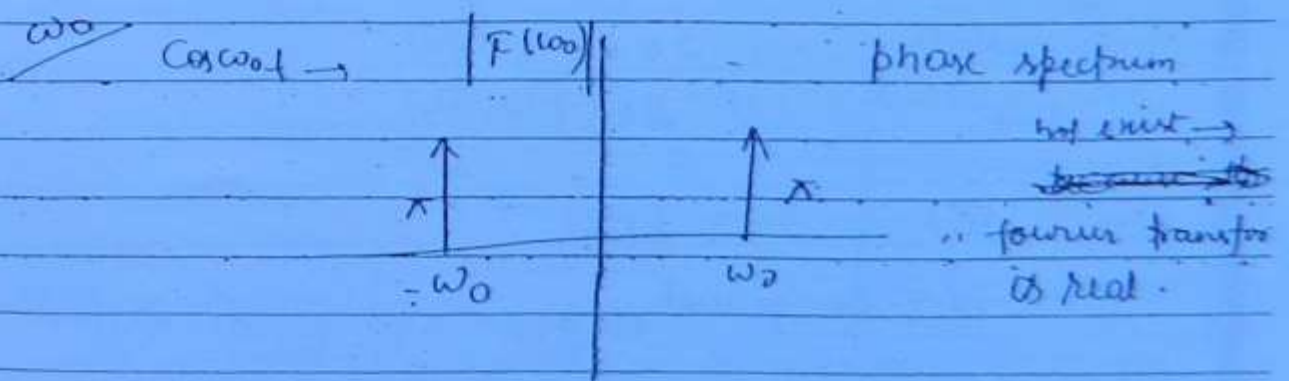
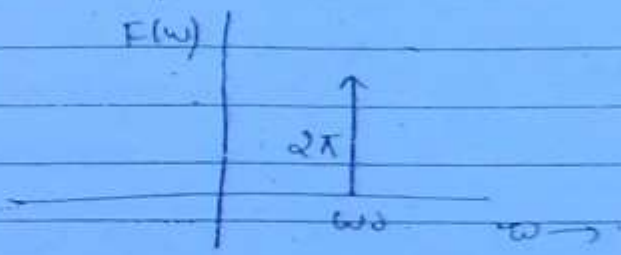
$\cos \omega_0 t \rightarrow \pi \delta(\omega + \omega_0) + \pi \delta(\omega - \omega_0)$

$\frac{1}{2j} e^{j\omega_0 t} + \frac{1}{2j} e^{-j\omega_0 t} \rightarrow \frac{1}{2j} \left[ \pi \delta(\omega - \omega_0) - \pi \delta(\omega + \omega_0) \right]$

$\sin \omega_0 t \rightarrow \frac{1}{j} \left[ \pi \delta(\omega - \omega_0) - \pi \delta(\omega + \omega_0) \right]$



$e^{j\omega_0 t} \rightarrow 2\pi \delta(\omega - \omega_0)$   
 ↓  
 having a single angular frequency



$$\delta(t) \rightarrow 1$$

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{j\omega t} d\omega \quad (176)$$

$$F(\omega) = \delta(\omega)$$

$$f(t) = \frac{1}{2\pi}$$

$$\frac{1}{2\pi} \rightarrow \delta(\omega)$$

$$1 \cdot \mathcal{F} \rightarrow 2\pi \delta(\omega)$$

$$F(\omega) \rightarrow \delta(\omega - \omega_0)$$

$$f(t) = \frac{1}{2\pi} e^{j\omega_0 t}$$

$$\frac{e^{j\omega_0 t}}{2\pi} \rightarrow \delta(\omega - \omega_0)$$

$$e^{j\omega_0 t} \rightarrow 2\pi \delta(\omega - \omega_0)$$

$$1 \cdot e^{j\omega_0 t} \rightarrow 2\pi \delta(\omega - \omega_0)$$

$$f(t) \rightarrow F(\omega)$$

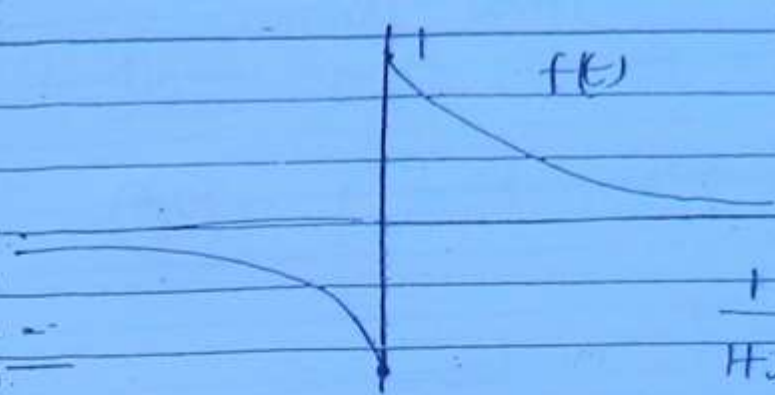
$$f(t) e^{j\omega_0 t} \rightarrow F(\omega - \omega_0)$$

$$f(t) e^{-j\omega_0 t} \rightarrow F(\omega + \omega_0)$$

$$\frac{1}{2} e^{j\omega_0 t} \rightarrow \pi \delta(\omega - \omega_0)$$

$$\frac{1}{2} e^{-j\omega_0 t} \rightarrow \pi \delta(\omega + \omega_0)$$

$$\frac{1}{2} e^{j\omega_0 t} + \frac{1}{2} e^{-j\omega_0 t} \rightarrow \pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)$$



(177)

$$\frac{1}{1+j\omega} - \frac{1}{1-j\omega}$$

$$F(\omega) = \frac{-2j\omega}{(1+\omega^2)} \quad \text{imaginary \& odd in nature}$$

$f(t)$  is real & odd

$\hookrightarrow F(\omega)$  is also imaginary & odd.

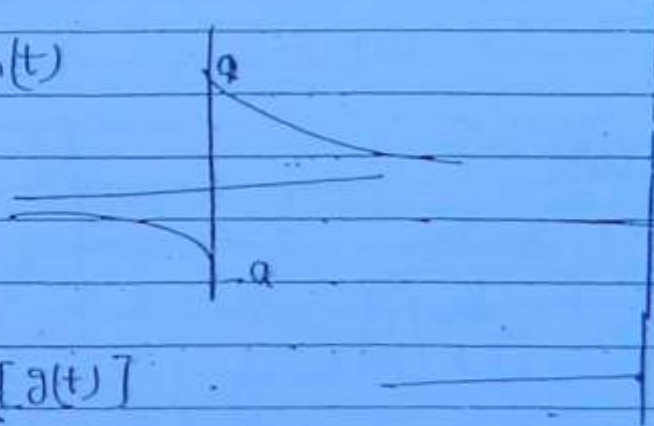
(\*) Fourier transforms of neither even nor odd signals is generally a complex in nature this complex fourier transform is conjugate symmetric.

(\*) When  $f(t)$  is an even signal Fourier transform is purely real is even function of  $\omega$ .

(\*) When  $f(t)$  is odd fourier transform is purely imaginary and this imaginary part is odd.

$$\lim_{a \rightarrow 0} g(t) = \text{sgn}(t)$$

$$a \rightarrow 0$$



$$F[\text{sgn}(t)] = \lim_{a \rightarrow 0} F[g(t)]$$

$$= \lim_{a \rightarrow 0} F[g(t)]$$

$$= \lim_{a \rightarrow 0} \left[ \frac{1}{a+j\omega} - \frac{1}{a-j\omega} \right]$$

$$F[\text{sgn}(t)] = \frac{2}{j\omega}$$

$\pi/2$

$\angle F(\omega)$

Phase spectrum

odd in nature

$\omega \rightarrow$

178

$$F(\omega) = |F(\omega)| e^{j\angle F(\omega)}$$

$$e^{at} u(-t)$$

$$F(\omega) = \int_{-\infty}^0 e^{at} e^{-j\omega t} dt$$

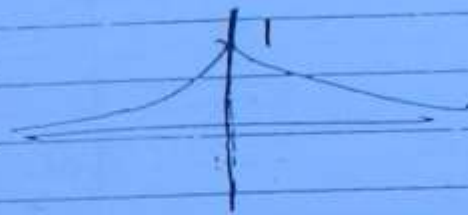
$$F(\omega) = \frac{1}{(a - j\omega)}$$

$$= \frac{a}{a^2 + \omega^2} + \frac{j\omega}{a^2 + \omega^2}$$

$\downarrow$  even                       $\downarrow$  odd

$f(t) \rightarrow F(\omega)$  } time reversal property  
 $f(-t) \rightarrow F(-\omega)$  }

$$F(t) = \frac{e^t + e^{-t}}{2} u(t)$$



$$F(\omega) = \frac{1}{1 - j\omega} + \frac{1}{1 + j\omega}$$

$F(\omega) = \frac{2}{1 + \omega^2} \rightarrow$  real & even  
 if  $f(t)$  is real & even

$$f_1(t) \rightarrow F_1(\omega)$$

$$f_2(t) \rightarrow F_2(\omega)$$

$$a f_1(t) + b f_2(t) \rightarrow a F_1(\omega) + b F_2(\omega)$$

Q. Fourier Transform of  $f(t) = e^{-at} u(t)$

$$= \int_0^{\infty} e^{-at} e^{-j\omega t} dt$$

(179)

$$= \frac{1}{-(j\omega + a)} [e^{-(j\omega + a)t}]_0^{\infty}$$

$$F(\omega) = \frac{1}{a + j\omega} = \frac{a - j\omega}{(a^2 + \omega^2)} = \frac{a}{a^2 + \omega^2} - \frac{j\omega}{a^2 + \omega^2}$$

generally complex in nature

$$F_R(\omega) = \frac{a}{a^2 + \omega^2}$$

$$F_R(-\omega) = \frac{a}{a^2 + \omega^2} = F_R(\omega) \rightarrow \text{even in nature}$$

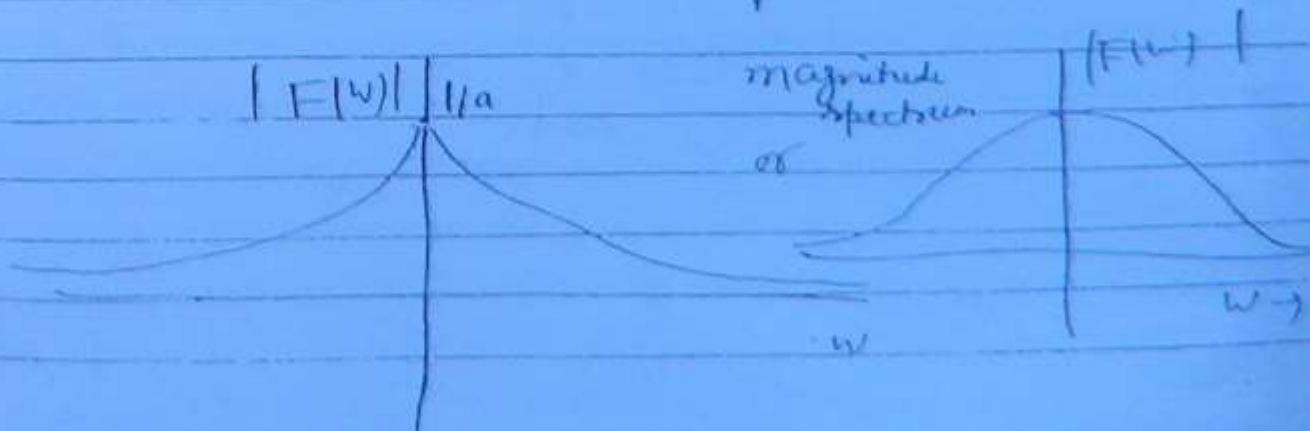
$$F_I(\omega) = \frac{-\omega}{a^2 + \omega^2}$$

$$F_I(-\omega) = \frac{+\omega}{a^2 + \omega^2} = -F_I(\omega) \rightarrow \text{odd in nature}$$

$F(\omega)$  is even conjugate or conjugate symmetric in nature

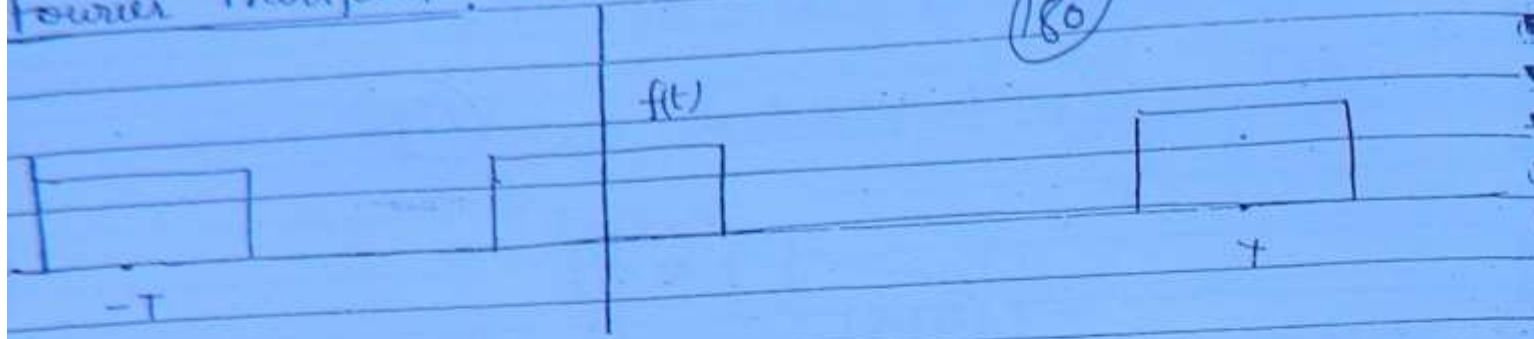
$$F(\omega) = F^*(\omega)$$

$$F(\omega) = |F(\omega)| \angle F(\omega) = \frac{1}{\sqrt{a^2 + \omega^2}} \angle (-\tan^{-1} \omega/a)$$

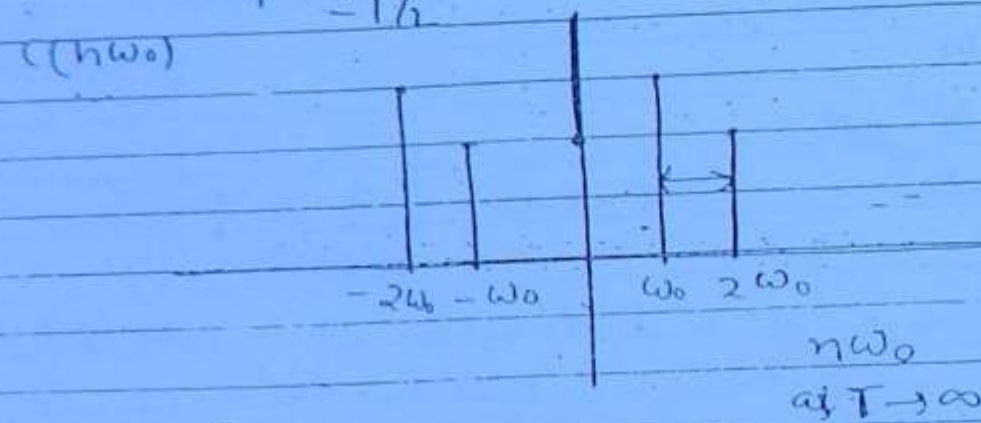


Fourier Transform: →

(180)



$$C_n = \frac{1}{T} \int_{-T/2}^{T/2} f(t) e^{-jn\omega_0 t} dt$$



$$f(t) = \sum_{n=-\infty}^{\infty} C_n e^{jn\omega_0 t}$$

$$F[n\omega_0] = \int_{-T/2}^{T/2} f(t) e^{-jn\omega_0 t} dt$$

$$T C_n =$$

$n\omega_0 \rightarrow \omega$   
 $\downarrow$   
 Spacing becomes zero, means become continuous

$$f(t) = \frac{1}{T} \sum_{n=-\infty}^{\infty} F[n\omega_0] e^{jn\omega_0 t}$$

$$\text{as } T \rightarrow \infty \quad F(\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$$

as  $T \rightarrow \infty$   
 F(t) becomes a continuous function

$$f(t) = \frac{\omega_0}{2\pi} \sum_{n=-\infty}^{\infty} F[n\omega_0] e^{jn\omega_0 t} = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{j\omega t} d\omega$$

$$Q. f(t) = \sum_{n=-100}^{100} \cos n\pi e^{jn\pi/100t}$$

(18)

$$C_n = \begin{cases} \cos n\pi & n \rightarrow -100 \text{ to } 100 \\ 0 & \text{otherwise} \end{cases}$$

$$C_1 = \cos \pi, \quad C_{-1} = \cos \pi$$

$$C_n = C_{-n}^*$$

$$C_n = C_{-1}$$

→ real & even

f(t) = real & even

$$f(t) = \sum_{n=-100}^{100} j \sin n\pi/2 e^{jn\pi/100t}$$

$$C_n = j \sin n\pi/2 \quad n \rightarrow -100 \rightarrow 100$$

$$C_1 = j$$

$$C_{-1} = -j$$

$$C_1 = C_{-1}^*$$

imaginary & odd

real & odd

$$f(t) = \sum_{n=-\infty}^{\infty} C_n e^{jn\omega_0 t}$$

Q. A signal f(t) as fourier coefficient C<sub>n</sub> find the fourier coefficient of

$$f(t) + f(t-1) = C_n + f(t)$$

f(-t)

$$f(1-t) = f(-t+1)$$

$$= \sum_{n=-\infty}^{\infty} C_n e^{jn\omega_0(1-t)}$$

$$= \sum_{n=-\infty}^{\infty} C_{-n} e^{-jn\omega_0(1-t)}$$

$$f(t) + f(1-t) = C_n + C_{-n} e^{-jn\omega_0(1-t)}$$