

17443

21415

3 Hours / 100 Marks

Seat No.

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- Instructions :** (1) All Questions are *compulsory*.
(2) Illustrate your answers with neat sketches wherever necessary.
(3) Figures to the right indicate full marks.
(4) Assume suitable data, if necessary.

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| 1. (A) Attempt any SIX : | 12 |
| (a) Which type of memory available in 8155 ? Also state its capacity. | |
| (b) What is bus ? What are different types of buses used in Microprocessor ? | |
| (c) How the port 'C' is divided in Group A and Group B of 8255 ? | |
| (d) What is fetching and execution operations of Microprocessor ? | |
| (e) Compare RIM and SIM instructions (any two). | |
| (f) Compare PUSH and POP instructions. | |
| (g) List two differences between static RAM and dynamic RAM. | |
| (h) Draw pin configuration of 8255A. | |
| (i) With the help of one example in each case explain the effect of the following instructions in 8085 | |
| (i) DAD B | |
| (ii) DAA | |
| (B) Attempt any TWO : | 8 |
| (a) What is Microprocessor ? State any four applications of Microprocessor. | |
| (b) Sketch and explain the timing diagram of the instruction MVI A, 08H. | |
| (c) LED is connected to SOD line of 8085. Write the instruction to 'ON' the LED. | |

P.T.O.

2. Attempt any FOUR :**16**

- (a) What is stack ? Explain working of stack in detail.
- (b) Define addressing mode ? Explain various addressing modes related to 8085 with suitable examples.
- (c) How SOD and SID pins can be used as a single bit output and input ports respectively ?
- (d) State any four features of 8085.
- (e) Write a program using the ADI instruction to add the two hexadecimal numbers 3 AH and 48 H and to display the answer at an output port.
- (f) Draw the block diagram of 8255, and explain the function of Group A port bits and Group B port bits.

3. Attempt any FOUR :**16**

- (a) What operations can be performed by each of the following instructions ?
 - (i) MVI A, data
 - (ii) MOV C, A
 - (iii) XRI 8 bit
 - (iv) ADDR
- (b) Write the priorities of hardware interrupts of 8085 microprocessor. Also write their vector addresses.
- (c) What is demultiplexing of the address and data bus ? Which signal is used to demultiplex the address and data bus ? Describe with the help of neat diagram.
- (d) State different operating modes of 8255. Explain mode 2 in detail.
- (e) Draw the neat labelled minimum system using 8085, 8155 and 8355.
- (f) Compare INTR interrupt with RST 6.5 interrupt on the basis of operation, advantages and disadvantages.

4. Attempt any FOUR :**16**

- (a) Interface 8 K RAM to 8085. State the memory map.
- (b) Explain the control word format of 8255 with suitable diagram.
- (c) Interface the ADC to 8055 and write assembly language program to convert analog data to digital data.
- (d) Interface 8255 to 8085 in I/O mapped I/O. Write the addresses of 8255.
- (e) What do you mean by timing diagram ? Define instruction cycle, machine cycle and T-state.
- (f) Differentiate between I/O mapped I/O and memory mapped I/O (any four points).

5. Attempt any FOUR :**16**

- (a) Write the timer modes of 8155 and explain any one with the timing diagram.
- (b) Draw a neat labelled block diagram of 8155.
- (c) Write the initialization instruction for 8255 in mode 'O' to configure Port A as a input and Port B as a output. Write instructions to read the content of Port A and display it on Port B.
- (d) Draw the neat labelled block diagram of 8355.
- (e) Write the assembly language program to arrange the data stored in memory location from 3000 H to 3009 H in ascending order.
- (f) Compare EI and DI instructions.

6. Attempt any TWO :**16**

- (a) Describe the functions of following blocks of 8085 microprocessor :
 - (i) General purpose registers
 - (ii) ALU
 - (iii) Timing and control unit
 - (iv) Instruction decoder and machine cycle encoding.

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- (b) Draw the flowchart and write a program to transfer the block of 30 data bytes stored in memory from location 9000 H; to the memory locations starting from 9040 H.

 - (c) Draw a diagram to interface stepper motor to 8085 microprocessor using 8255 PPI, write an 8085 assembly language program to rotate the stepper motor in clockwise direction continuously.
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